

# IAR Application Note G - 001

## Generic Software Uart written in C

### SUMMARY

*This application note details a generic software UART written in C which can be implemented on any microprocessor with a C compiler. It requires a timer interrupt to be set to 3 times the baud rate, and two software-controlled pins for the receive and transmit functions.*

### KEYWORDS

UART, C code

### The Problem to be solved

Software UARTs are generally coded in assembly for speed purposes, but with the increasing speed of processors, a software UART written in C is now easily implemented and highly portable.

### The Difficulties Involved

The implementation has three fundamental requirements:

1. A compiler must exist for the microprocessor.
2. A timer interrupt must be set to interrupt at three times the required baud rate. Most microprocessors have a timer interrupt that can be used for this, or an external clock interrupt could be used to achieve the same goal.
3. There must be a transmit pin which can be set from the software, and a receive pin which can be read by the software.

### The Solution

The C source file must be linked into the user's application with the necessary interface routines listed as follows:

1. void get\_rx\_pin\_status( void )  
Returns 0 or 1 dependent on whether the receive pin is high or low.
2. void set\_tx\_pin\_high( void )  
Sets the transmit pin to the high state.
3. void set\_tx\_pin\_low( void )  
Sets the transmit pin to the low state.
4. void idle( void )  
Background functions to execute while waiting for input.
5. void timer\_set( int BAUD\_RATE )  
Sets the timer to 3 times the baud rate.

6. `void set_timer_interrupt( timer_isr )`  
Enables the timer interrupt.

The baud rate is selectable by changing the `BAUD_RATE` macro at the top of the source file, and can be set to as high a value as the timer can support.

```
#define BAUD_RATE 19200.0
```

The user's initialization routine must initially call the `init_uart()` function before any other UART function.

The following standard functions are provided:

- a. `void flush_input_buffer( void )`  
Clears the contents of the input buffer.
- b. `char kbhit( void )`  
Tests whether an input character has been received.
- c. `char getchar( void )`  
Reads a character from the input buffer, waiting if necessary.
- d. `void putchar( char )`  
Writes a character to the serial port.
- e. `void turn_rx_on( void )`  
Turns on the receive function.
- f. `void turn_rx_off( void )`  
Turns off the receive function.

Note that received characters are buffered so that there is no loss of data for a continuous sequence of characters. The `idle()` function provides the user with the capability to perform background processing while the `getchar()` function is called waiting on keystroke input.

### User Benefits

Clearly, the low-level adaptations that require many lines of assembly code can be done in C using the IAR C language extensions, thus increasing readability and portability.

### Conclusions

The solution can also be modified to similar serial protocols to RS232, such as the 1553 bus.

### References

See the attached listing of the C source code `UART.C`.