# IAR C/C++ Development Guide

Compiling and Linking

for Advanced RISC Machines Ltd's ARM® Cores





### **COPYRIGHT NOTICE**

Copyright © 1999-2011 IAR Systems AB.

No part of this document may be reproduced without the prior written consent of IAR Systems AB. The software described in this document is furnished under a license and may only be used or copied in accordance with the terms of such a license.

### **DISCLAIMER**

The information in this document is subject to change without notice and does not represent a commitment on any part of IAR Systems. While the information contained herein is assumed to be accurate, IAR Systems assumes no responsibility for any errors or omissions.

In no event shall IAR Systems, its employees, its contractors, or the authors of this document be liable for special, direct, indirect, or consequential damage, losses, costs, c charges, claims, demands, claim for lost profits, fees, or expenses of any nature or kind.

### **TRADEMARKS**

IAR Systems, IAR Embedded Workbench, C-SPY, visualSTATE, From Idea To Target, IAR KickStart Kit, IAR PowerPac, IAR YellowSuite, IAR Advanced Development Kit, IAR, and the IAR Systems logotype are trademarks or registered trademarks owned by IAR Systems AB. J-Link is a trademark licensed to IAR Systems AB.

Microsoft and Windows are registered trademarks of Microsoft Corporation.

ARM, Thumb, and Cortex are registered trademarks of Advanced RISC Machines Ltd.

Adobe and Acrobat Reader are registered trademarks of Adobe Systems Incorporated.

All other product names are trademarks or registered trademarks of their respective owners.

### **EDITION NOTICE**

Seventh edition: April 2011

Part number: DARM-7

This guide applies to version 6.2x of IAR Embedded Workbench® for ARM®.

The *IAR C/C++ Development Guide for ARM*® replaces all versions of the ARM *IAR C/C++ Compiler Reference Guide* and the *IAR Linker and Library Tools Reference Guide*.

Internal reference: M10, Too6.3, csrct2010.1, V\_110411, ISUD.

# **Brief contents**

lables	19
Preface	21
Part I. Using the build tools	29
Introduction to the IAR build tools	31
Developing embedded applications	37
Data storage	53
Functions	57
Linking using ILINK	67
Linking your application	77
The DLIB runtime environment	89
Assembler language interface	125
Using C	143
Using C++	153
Application-related considerations	165
Efficient coding for embedded applications	179
Part 2. Reference information	199
External interface details	201
Compiler options	209
Linker options	251
Data representation	275
Extended keywords	291

Pragma directives3	305
ntrinsic functions3	323
The preprocessor3	365
Library functions3	371
The linker configuration file	381
Section reference4	103
AR utilities4	109
mplementation-defined behavior4	139
ndex4	155

# **Contents**

lables		19
Preface		21
Who	should read this guide	.21
How	to use this guide	. 21
What	this guide contains	. 22
Othe	documentation	. 23
	User and reference guides	. 24
	The online help system	. 24
	Further reading	. 25
	Web sites	. 25
Docu	ment conventions	. 26
	Typographic conventions	. 26
	Naming conventions	. 27
Part I. C	ising the nillia tanis	. 29
	Jsing the build toolsn to the IAR build tools	
Introductio		31
Introductio	n to the IAR build tools	31
Introductio	n to the IAR build toolsAR build tools—	31 .31 .31
Introductio	n to the IAR build tools  AR build tools—an overview  IAR C/C++ Compiler	31 .31 .31
Introductio	n to the IAR build tools  AR build tools—an overview  IAR C/C++ Compiler  IAR Assembler	31 .31 .31 .32
Introductio	n to the IAR build tools  AR build tools—an overview  IAR C/C++ Compiler  IAR Assembler  The IAR ILINK Linker	31 .31 .32 .32
Introductio The I	n to the IAR build tools  AR build tools—an overview  IAR C/C++ Compiler  IAR Assembler  The IAR ILINK Linker  Specific ELF tools	31 .31 .32 .32 .32
Introductio The I	n to the IAR build tools  AR build tools—an overview  IAR C/C++ Compiler  IAR Assembler  The IAR ILINK Linker  Specific ELF tools  External tools	31 .31 .32 .32 .32 .32
Introductio The I	n to the IAR build tools  AR build tools—an overview  IAR C/C++ Compiler  IAR Assembler  The IAR ILINK Linker  Specific ELF tools  External tools  anguage overview	31 .31 .32 .32 .32 .33 .33
Introductio The I	n to the IAR build tools  AR build tools—an overview  IAR C/C++ Compiler  IAR Assembler  The IAR ILINK Linker  Specific ELF tools  External tools  anguage overview  e support	31 .31 .32 .32 .32 .33 .33
Introductio The I	n to the IAR build tools  AR build tools—an overview  IAR C/C++ Compiler  IAR Assembler  The IAR ILINK Linker  Specific ELF tools  External tools  anguage overview  e support  Supported ARM devices	31 .31 .32 .32 .32 .32 .33 .34 .34
Introductio The I	n to the IAR build tools  AR build tools—an overview  IAR C/C++ Compiler  IAR Assembler  The IAR ILINK Linker  Specific ELF tools  External tools  anguage overview  e support  Supported ARM devices  Preconfigured support files  Examples for getting started  al support for embedded systems	31 .31 .32 .32 .32 .33 .34 .34 .34
Introductio The I	n to the IAR build tools  AR build tools—an overview  IAR C/C++ Compiler  IAR Assembler  The IAR ILINK Linker  Specific ELF tools  External tools  anguage overview  e support  Supported ARM devices  Preconfigured support files  Examples for getting started	31 .31 .32 .32 .32 .33 .33 .34 .34 .34

	Predefined symbols	35
	Special function types	35
	Accessing low-level features	35
Developin	g embedded applications	37
Dev	eloping embedded software using IAR build tools	37
	Mapping of internal and external memory	37
	Communication with peripheral units	38
	Event handling	38
	System startup	38
	Real-time operating systems	38
	Interoperability with other build tools	39
The	build process—an overview	39
	The translation process	39
	The linking process	40
	After linking	42
Арр	lication execution—an overview	42
	The initialization phase	43
	The execution phase	47
	The termination phase	47
Buile	ding applications—an overview	47
Basi	c project configuration	48
	Processor configuration	48
	Optimization for speed and size	49
	Runtime environment	50
Data stora	age	53
Intro	oduction	53
	Different ways to store data	53
Auto	o variables—on the stack	54
	The steels	

Dyn	amic memory on the heap	55
Functions		57
Fund	ction-related extensions	57
ARM	1 and Thumb code	57
Exec	cution in RAM	58
Prin	nitives for interrupts, concurrency, and OS-relate	d
prog	gramming	59
	Interrupt functions	59
	An interrupt function must have the return type void, and it can	not spec-
	ify any parameters.Installing exception functions	60
	Interrupts and fast interrupts	61
	Nested interrupts	61
	Software interrupts	62
	Interrupt operations	63
	Interrupts for ARM Cortex-M	64
	C++ and special function types	65
Linking us	ing ILINK	67
Link	ing—an overview	67
Mod	lules and sections	68
The	linking process	69
Plac	ing code and data—the linker configuration file	71
	A simple example of a configuration file	71
Initia	alization at system startup	73
	The initialization process	74
	C++ dynamic initialization	75
Linking yo	our application	77
Link	ing considerations	77
	Choosing a linker configuration file	77
	Defining your own memory areas	78
	Placing sections	79
	Reserving space in RAM	80
	Keening modules	81

	Keeping symbols and sections	81
	Application startup	81
	Setting up the stack	81
	Setting up the heap	82
	Setting up the atexit limit	82
	Changing the default initialization	82
	Interaction between ILINK and the application	85
	Standard library handling	85
	Producing other output formats than ELF/DWARF	86
	Veneers	86
Hints	for troubleshooting	86
	Relocation errors	86
The DLIB i	runtime environment	89
Intro	duction to the runtime environment	89
	Runtime environment functionality	89
	Setting up the runtime environment	90
Using	g prebuilt libraries	91
	Library filename syntax	92
	Groups of library files	93
	Customizing a prebuilt library without rebuilding	94
Choo	osing formatters for printf and scanf	
	Choosing a printf formatter	95
	Choosing a scanf formatter	96
Appli	cation debug support	97
	Including C-SPY debug support	97
	The debug library functionality	98
	The C-SPY Terminal I/O window	98
	Low-level functions in the debug library	99
Adap	ting the library for target hardware	
	Library low-level interface	100
Over	riding library modules	101
Build	ing and using a customized library	101
	Setting up a library project	101

	Modifying the library functionality	102
	Using a customized library	102
Syste	em startup and termination	103
	System startup	103
	System termination	105
Cust	omizing system initialization	106
	low_level_init	106
	Modifying the file cstartup.s	107
Libra	ry configurations	107
	Choosing a runtime configuration	108
Stand	dard streams for input and output	108
	Implementing low-level character input and output	108
Conf	iguration symbols for printf and scanf	110
	Customizing formatting capabilities	111
File i	nput and output	112
Loca	le	112
	Locale support in prebuilt libraries	113
	Customizing the locale support	113
	Changing locales at runtime	114
Envir	onment interaction	115
	The getenv function	115
	The system function	115
Signa	al and raise	116
Time		116
Pow		116
Asse	rt	117
Atex	it	117
Mana	aging a multithreaded environment	117
	Multithread support in the DLIB library	118
	Enabling multithread support	118
	Changes in the linker configuration file	122
Chec	king module consistency	122
	Runtime model attributes	122
	Using runtime model attributes	123

Assembler	language interface	125
Mixin	g C and assembler	. 125
	Intrinsic functions	. 125
	Mixing C and assembler modules	. 126
	Inline assembler	. 127
Callin	g assembler routines from C	. 129
	Creating skeleton code	. 129
	Compiling the code	. 130
Callin	g assembler routines from C++	. 131
Callin	g convention	. 132
	Function declarations	. 133
	Using C linkage in C++ source code	. 133
	Preserved versus scratch registers	. 133
	Function entrance	. 134
	Function exit	. 136
	Examples	. 137
Call f	rame information	. 138
	CFI directives	. 139
	Creating assembler source with CFI support	. 140
Using C		143
C lan	guage overview	. 143
Exten	nsions overview	. 144
	Enabling language extensions	. 145
IAR C	language extensions	. 146
	Extensions for embedded systems programming	
	Relaxations to Standard C	. 148
Using C++		153
Over	view—EC++ and EEC++	. 153
	Embedded C++	. 153
	Extended Embedded C++	. 154
Over	view—Standard C++	. 154
	Modes for exceptions and RTTI support	. 155

Exception handling	156
Enabling support for C++ and variants	157
C++ and EC++ feature descriptions	158
Using IAR attributes with Classes	158
Function types	159
Using static class objects in interrupts	159
Using New handlers	159
Templates	160
Debug support in C-SPY	160
EEC++ feature description	160
Templates	160
Variants of cast operators	161
Mutable	161
Namespace	161
The STD namespace	161
EC++ and C++ language extensions	161
Application-related considerations	165
Output format considerations	165
Stack considerations	165
Stack size considerations	166
Stack alignment	166
Exception stacks	166
Heap considerations	167
Interaction between the tools and your application	168
Checksum calculation	169
Calculating a checksum	170
Adding a checksum function to your source code	171
Things to remember	173
C-SPY considerations	173
Linker optimizations	174
Virtual Function Elimination	174
AEABI compliance	174
Linking AEABI-compliant modules using the IAR ILINK Li	nker 175

Linking AEABI-compliant modules using a third-party linker	176
Enabling AEABI compliance in the compiler	176
CMSIS integration	176
CMSIS DSP library	177
Customizing the CMSIS DSP library	177
Building with CMSIS on the command line	177
Building with CMSIS in IAR Embedded Workbench	177
Efficient coding for embedded applications	179
Selecting data types	179
Using efficient data types	179
Floating-point types	180
Alignment of elements in a structure	180
Anonymous structs and unions	181
Controlling data and function placement in memory	182
Data placement at an absolute location	183
Data and function placement in sections	185
Data placement in registers	186
Controlling compiler optimizations	187
Scope for performed optimizations	187
Multi-file compilation units	187
Optimization levels	188
Speed versus size	189
Fine-tuning enabled transformations	189
Facilitating good code generation	192
Writing optimization-friendly source code	192
Saving stack space and RAM memory	193
Function prototypes	193
Integer types and bit negation	194
Protecting simultaneously accessed variables	194
Accessing special function registers	195
Passing values between C and assembler objects	196
Non initialized variables	106

Part 2. Reference information	199
External interface details	201
Invocation syntax	201
Compiler invocation syntax	
ILINK invocation syntax	201
Passing options	202
Environment variables	202
Include file search procedure	203
Compiler output	204
ILINK output	205
Diagnostics	206
Message format for the compiler	206
Message format for the linker	207
Severity levels	207
Setting the severity level	208
Internal error	208
Compiler options	209
Options syntax	209
Types of options	209
Rules for specifying parameters	209
Summary of compiler options	212
Descriptions of compiler options	215
Linker options	251
Summary of linker options	251
Descriptions of linker options	
Data representation	275
Alignment	275
Alignment on the ARM core	275
Byte order	276
Basic data types	276
Integer types	276

	Floating-point types	. 282
Poin	nter types	. 284
	Function pointers	. 284
	Data pointers	. 284
	Casting	. 284
Stru	ıcture types	. 285
	Alignment	. 285
	General layout	. 285
	Packed structure types	. 286
Тур	e qualifiers	. 287
	Declaring objects volatile	. 287
	Declaring objects volatile and const	. 288
	Declaring objects const	. 289
Data	a types in C++	. 289
Extended	keywords	291
Gen	eral syntax rules for extended keywords	. 291
	Type attributes	. 291
	Object attributes	. 293
Sum	nmary of extended keywords	. 294
Desc	criptions of extended keywords	. 295
Pragma di	rectives	305
Sum	nmary of pragma directives	. 305
Desc	criptions of pragma directives	.307
Intrinsic fu	unctions	323
Sum	nmary of intrinsic functions	.323
	Intrinsic functions for Neon instructions	.329

Desc	riptions of intrinsic functions	330
The prepro	ocessor	365
Over	view of the preprocessor	365
Desc	riptions of predefined preprocessor symbols	366
Desc	riptions of miscellaneous preprocessor extensions.	369
	NDEBUG	369
	#warning message	370
Library fun	nctions	371
Libra	ıry overview	371
	Header files	371
	Library object files	371
	Alternative more accurate library functions	372
	Reentrancy	372
	The longjmp function	373
IAR I	DLIB Library	373
	C header files	373
	C++ header files	374
	Library functions as intrinsic functions	377
	Added C functionality	
	Symbols used internally by the library	378
The linker	configuration file	381
Over	view	381
Defin	ning memories and regions	382
	Define memory directive	382
	Define region directive	383
Regio	ons	383
	Region literal	383
	Region expression	385
	Empty region	386
Secti	on handling	
	Define block directive	
	Define overlay directive	388

	Initialize directive	390
	Do not initialize directive	392
	Keep directive	392
	Place at directive	393
	Place in directive	394
Section	on selection	394
	Section-selectors	395
	Extended-selectors	397
Using	symbols, expressions, and numbers	398
	Define symbol directive	398
	Export directive	399
	Expressions	399
	Numbers	400
Struc	tural configuration	401
	If directive	401
	Include directive	402
Section refe	erence	403
Sumn	nary of sections	403
Descr	iptions of sections and blocks	404
IAR utilities		409
The I	AR Archive Tool—iarchive	409
	Invocation syntax	409
	Summary of iarchive commands	410
	Summary of iarchive options	411
	Diagnostic messages	411
The I	AR ELF Tool—ielftool	412
	Invocation syntax	413
	Summary of ielftool options	413
The I	AR ELF Dumper for ARM—ielfdumparm	414
	Invocation syntax	414
	Summary of ielfdumparm options	415
The I	AR ELF Object Tool—iobjmanip	415
	Invocation syntax	415

	Summary of iobjmanip options	416
	Diagnostic messages	416
The	e IAR Absolute Symbol Exporter—isymexport	418
	Invocation syntax	418
	Summary of isymexport options	419
	Steering files	419
	Show directive	420
	Hide directive	420
	Rename directive	420
	Diagnostic messages	421
De	scriptions of options	423
Impleme	ntation-defined behavior	439
De	scriptions of implementation-defined behavior .	439
	J.3.1 Translation	
	J.3.2 Environment	440
	J.3.3 Identifiers	441
	J.3.4 Characters	441
	J.3.5 Integers	443
	J.3.6 Floating point	443
	J.3.7 Arrays and pointers	444
	J.3.8 Hints	444
	J.3.9 Structures, unions, enumerations, and bitfields	445
	J.3.10 Qualifiers	445
	J.3.11 Preprocessing directives	446
	J.3.12 Library functions	447
	J.3.13 Architecture	452
	J.4 Locale	453
Indov		155

# **Tables**

1. Typographic conventions used in this guide	20
2: Naming conventions used in this guide	27
3: Sections holding initialized data	74
4: Description of a relocation error	87
5: Customizable items	94
6: Formatters for printf	95
7: Formatters for scanf	96
8: Functions with special meanings when linked with debug library	99
9: Library configurations 1	07
10: Descriptions of printf configuration symbols 1	11
11: Descriptions of scanf configuration symbols	11
12: Low-level I/O files	12
13: Library objects using TLS	18
14: Macros for implementing TLS allocation	21
15: Example of runtime model attributes	23
16: Registers used for passing parameters	35
17: Registers used for returning values	36
18: Call frame information resources defined in a names block 1	39
19: Language extensions	45
20: Section operators and their symbols	48
21: Exception stacks	66
22: Compiler optimization levels	88
23: Compiler environment variables	202
24: ILINK environment variables	203
25: Error return codes	205
26: Compiler options summary	212
27: Linker options summary	251
28: Integer types	276
29: Floating-point types	282
30: Extended keywords summary	294
31: Pragma directives summary	305

32:	Intrinsic functions summary	323
33:	Predefined symbols	366
34:	Traditional Standard C header files—DLIB	373
35:	Embedded C++ header files	374
36:	Standard template library header files	375
37:	New Standard C header files—DLIB	376
38:	Examples of section selector specifications	396
39:	Section summary	403
40:	iarchive parameters	410
41:	iarchive commands summary	410
42:	iarchive options summary	411
43:	ielftool parameters	413
44:	ielftool options summary	413
45:	ielfdumparm parameters	414
46:	ielfdumparm options summary	415
47:	iobjmanip parameters	415
48:	iobjmanip options summary	416
49:	ielftool parameters	418
50:	isymexport options summary	419
51:	Message returned by strerror()—IAR DLIB library	454

# **Preface**

Welcome to the IAR C/C++ Development Guide for ARM®. The purpose of this guide is to provide you with detailed reference information that can help you to use the build tools to best suit your application requirements. This guide also gives you suggestions on coding techniques so that you can develop applications with maximum efficiency.

## Who should read this guide

Read this guide if you plan to develop an application using the C or C++ language for the ARM core and need detailed reference information on how to use the build tools. You should have working knowledge of:

- The architecture and instruction set of the ARM core. Refer to the documentation from Advanced RISC Machines Ltd for information about the ARM core
- The C or C++ programming language
- Application development for embedded systems
- The operating system of your host computer.

## How to use this guide

When you start using the IAR C/C++ compiler and linker for ARM, you should read *Part 1. Using the build tools* in this guide.

When you are familiar with the compiler and linker and have already configured your project, you can focus more on *Part 2. Reference information*.

If you are new to using the IAR Systems build tools, we recommend that you first study the *IDE Project Management and Building Guide for ARM*®. This guide contains a product overview, tutorials that can help you get started, conceptual and user information about the IDE and the IAR C-SPY® Debugger, and corresponding reference information.

### What this guide contains

Below is a brief outline and summary of the chapters in this guide.

### Part I. Using the build tools

- Introduction to the IAR build tools gives an introduction to the IAR build tools, which includes an overview of the tools, the programming languages, the available device support, and extensions provided for supporting specific features of the ARM core.
- Developing embedded applications gives the information you need to get started developing your embedded software using the IAR build tools.
- Data storage describes how to store data in memory.
- Functions gives a brief overview of function-related extensions—mechanisms for controlling functions—and describes some of these mechanisms in more detail.
- Linking using ILINK describes the linking process using the IAR ILINK Linker and the related concepts.
- Linking your application lists aspects that you must consider when linking your
  application, including using ILINK options and tailoring the linker configuration
  file.
- The DLIB runtime environment describes the DLIB runtime environment in which
  an application executes. It covers how you can modify it by setting options,
  overriding default library modules, or building your own library. The chapter also
  describes system initialization introducing the file cstartup, how to use modules
  for locale, and file I/O.
- Assembler language interface contains information required when parts of an
  application are written in assembler language. This includes the calling convention.
- Using C gives an overview of the two supported variants of the C language and an
  overview of the compiler extensions, such as extensions to Standard C.
- Using C++ gives an overview of the two levels of C++ support: The industry-standard EC++ and IAR Extended EC++.
- Application-related considerations discusses a selected range of application issues related to using the compiler and linker.
- Efficient coding for embedded applications gives hints about how to write code that compiles to efficient code for an embedded application.

### Part 2. Reference information

 External interface details provides reference information about how the compiler and linker interact with their environment—the invocation syntax, methods for passing options to the compiler and linker, environment variables, the include file search procedure, and the different types of compiler and linker output. The chapter also describes how the diagnostic system works.

- *Compiler options* explains how to set options, gives a summary of the options, and contains detailed reference information for each compiler option.
- *Linker options* gives a summary of the options, and contains detailed reference information for each linker option.
- Data representation describes the available data types, pointers, and structure types.
   This chapter also gives information about type and object attributes.
- Extended keywords gives reference information about each of the ARM-specific keywords that are extensions to the standard C/C++ language.
- Pragma directives gives reference information about the pragma directives.
- Intrinsic functions gives reference information about functions to use for accessing ARM-specific low-level features.
- The preprocessor gives a brief overview of the preprocessor, including reference information about the different preprocessor directives, symbols, and other related information.
- Library functions gives an introduction to the C or C++ library functions, and summarizes the header files.
- The linker configuration file describes the purpose of the linker configuration file and describes its contents.
- Section reference gives reference information about the use of sections.
- IAR utilities describes the IAR utilities that handle the ELF and DWARF object formats.
- Implementation-defined behavior describes how the compiler handles the implementation-defined areas of the C language standard.

### Other documentation

User documentation is available as hypertext PDFs and as a context-sensitive online help system in HTML format. You can access the documentation from the Information Center or from the **Help** menu in the IAR Embedded Workbench IDE. The online help system is also available via the F1 key.

### **USER AND REFERENCE GUIDES**

The complete set of IAR Systems development tools is described in a series of guides. For information about:

- System requirements and information about how to install and register the IAR Systems products, refer to the booklet Quick Reference (available in the product box) and the Installation and Licensing Guide.
- Getting started using IAR Embedded Workbench and the tools it provides, see the guide Getting Started with IAR Embedded Workbench®.
- Using the IDE for project management and building, see the IDE Project Management and Building Guide for ARM®.
- Using the IAR C-SPY® Debugger, see the C-SPY® Debugging Guide for ARM®.
- Programming for the IAR C/C++ Compiler, see the IAR C/C++ Compiler Reference Guide if your product package includes the IAR XLINK Linker, and the IAR C/C++ Development Guide, Compiling and Linking if your product package includes the IAR ILINK Linker.
- Programming for the IAR Assembler for ARM, see the ARM® IAR Assembler Reference Guide.
- Using the IAR DLIB Library, see the *DLIB Library Reference information*, available in the online help system.
- Porting application code and projects created with a previous version of the IAR Embedded Workbench for ARM, see the IAR Embedded Workbench® Migration Guide for ARM®.
- Developing safety-critical applications using the MISRA C guidelines, see the IAR Embedded Workbench® MISRA C:2004 Reference Guide or the IAR Embedded Workbench® MISRA C:1998 Reference Guide.

Note: Additional documentation might be available depending on your product installation.

### THE ONLINE HELP SYSTEM

The context-sensitive online help contains:

- Comprehensive information about debugging using the IAR C-SPY® Debugger
- Reference information about the menus, windows, and dialog boxes in the IDE
- Compiler reference information
- Keyword reference information for the DLIB library functions. To obtain reference information for a function, select the function name in the editor window and press F1.

### **FURTHER READING**

These books might be of interest to you when using the IAR Systems development tools:

- Seal, David, and David Jagger. ARM Architecture Reference Manual. Addison-Wesley
- Barr, Michael, and Andy Oram, ed. Programming Embedded Systems in C and C++. O'Reilly & Associates.
- Furber, Steve, ARM System-on-Chip Architecture. Addison-Wesley.
- Harbison, Samuel P. and Guy L. Steele (contributor). C: A Reference Manual. Prentice Hall.
- Josuttis, Nicolai M. *The C++ Standard Library: A Tutorial and Reference*. Addison-Wesley.
- Kernighan, Brian W. and Dennis M. Ritchie. The C Programming Language. Prentice Hall.
- Labrosse, Jean J. Embedded Systems Building Blocks: Complete and Ready-To-Use Modules in C. R&D Books.
- Lippman, Stanley B. and Josée Lajoie. C++ Primer. Addison-Wesley.
- Mann, Bernhard. C für Mikrocontroller. Franzis-Verlag. [Written in German.]
- Meyers, Scott. *Effective C++: 50 Specific Ways to Improve Your Programs and Designs.* Addison-Wesley.
- Meyers, Scott. *More Effective C++*. Addison-Wesley.
- Meyers, Scott. Effective STL. Addison-Wesley.
- Sloss, Andrew N. et al, ARM System Developer's Guide: Designing and Optimizing System Software. Morgan Kaufmann.
- Stroustrup, Bjarne. The C++ Programming Language. Addison-Wesley.
- Stroustrup, Bjarne. Programming Principles and Practice Using C++. Addison-Wesley.
- Sutter, Herb. Exceptional C++: 47 Engineering Puzzles, Programming Problems, and Solutions. Addison-Wesley.

### **WEB SITES**

Recommended web sites:

- The Advanced RISC Machines Ltd web site, www.arm.com, contains information
  and news about the ARM cores. This site also contains information about the ARM
  Embedded Application Binary Interface (AEABI) for the ARM architecture, and
  directs you to documentation about the ELF/DWARF standards.
- The IAR Systems web site, www.iar.com, holds application notes and other product information.

- The web site of the C standardization working group, www.open-std.org/jtc1/sc22/wg14.
- The web site of the C++ Standards Committee, www.open-std.org/jtc1/sc22/wg21.
- Finally, the Embedded C++ Technical Committee web site,
   www.caravan.net/ec2plus, contains information about the Embedded C++ standard.

### **Document conventions**

When, in this text, we refer to the programming language C, the text also applies to C++, unless otherwise stated.

When referring to a directory in your product installation, for example arm\doc, the full path to the location is assumed, for example c:\Program Files\IAR Systems\Embedded Workbench 6.n\arm\doc.

### TYPOGRAPHIC CONVENTIONS

This guide uses the following typographic conventions:

Style	Used for
computer	<ul><li>Source code examples and file paths.</li><li>Text on the command line.</li><li>Binary, hexadecimal, and octal numbers.</li></ul>
parameter	A placeholder for an actual value used as a parameter, for example filename.h where filename represents the name of the file.
[option]	An optional part of a linker directive, [ and ] are not part of the actual directive, but any [, ], {, or } are part of the directive syntax.
{option}	A mandatory part of a linker directive, <b>{</b> and <b>}</b> are not part of the actual directive, but any [, ], {, or } are part of the directive syntax
[option]	An optional part of a command.
[a b c]	An optional part of a command with alternatives.
{a b c}	A mandatory part of a command with alternatives.
bold	Names of menus, menu commands, buttons, and dialog boxes that appear on the screen.
italic	<ul><li>A cross-reference within this guide or to another guide.</li><li>Emphasis.</li></ul>
	An ellipsis indicates that the previous item can be repeated an arbitrary number of times.

Table 1: Typographic conventions used in this guide

Style	Used for
<u></u>	Identifies instructions specific to the IAR Embedded Workbench® IDE
	interface.
	Identifies instructions specific to the command line interface.
	Identifies helpful tips and programming hints.
<u>•</u>	Identifies warnings.

Table 1: Typographic conventions used in this guide (Continued)

### **NAMING CONVENTIONS**

The following naming conventions are used for the products and tools from IAR Systems® referred to in this guide:

Brand name	Generic term
IAR Embedded Workbench® for ARM	IAR Embedded Workbench®
IAR Embedded Workbench® IDE for ARM	the IDE
IAR C-SPY® Debugger for ARM	C-SPY, the debugger
IAR C-SPY® Simulator	the simulator
IAR C/C++ Compiler $^{TM}$ for ARM	the compiler
IAR Assembler™ for ARM	the assembler
IAR ILINK Linker™	ILINK, the linker
IAR DLIB Library™	the DLIB library

Table 2: Naming conventions used in this guide

Document conventions

# Part I. Using the build tools

This part of the IAR C/C++ Development Guide for ARM® includes these chapters:

- Introduction to the IAR build tools
- Developing embedded applications
- Data storage
- Functions
- Linking using ILINK
- Linking your application
- The DLIB runtime environment
- Assembler language interface
- Using C
- Using C++
- Application-related considerations
- Efficient coding for embedded applications.



# Introduction to the IAR build tools

This chapter gives an introduction to the IAR build tools for the ARM core, which means you will get an overview of:

- The IAR build tools—the build interfaces, compiler, assembler, and linker
- The programming languages
- The available device support
- The extensions provided by the IAR C/C++ Compiler for ARM to support specific features of the ARM core.

### The IAR build tools—an overview

In the IAR product installation you can find a set of tools, code examples, and user documentation, all suitable for developing software for ARM-based embedded applications. The tools allow you to develop your application in C, C++, or in assembler language.



IAR Embedded Workbench® is a very powerful Integrated Development Environment (IDE) that allows you to develop and manage complete embedded application projects. It provides an easy-to-learn and highly efficient development environment with maximum code inheritance capabilities, comprehensive and specific target support. IAR Embedded Workbench promotes a useful working methodology, and thus a significant reduction of the development time.

For information about the IDE, see the *IDE Project Management and Building Guide for ARM*®.



The compiler, assembler, and linker can also be run from a command line environment, if you want to use them as external tools in an already established project environment.

#### IAR C/C++ COMPILER

The IAR C/C++ Compiler for ARM is a state-of-the-art compiler that offers the standard features of the C and C++ languages, plus extensions designed to take advantage of the ARM-specific facilities.

### IAR ASSEMBLER

The IAR Assembler for ARM is a powerful relocating macro assembler with a versatile set of directives and expression operators. The assembler features a built-in C language preprocessor and supports conditional assembly.

The IAR Assembler for ARM uses the same mnemonics and operand syntax as the Advanced RISC Machines Ltd ARM Assembler, which simplifies the migration of existing code. For detailed information, see the ARM® IAR Assembler Reference Guide.

### THE IAR ILINK LINKER

The IAR ILINK Linker for ARM is a powerful, flexible software tool for use in the development of embedded controller applications. It is equally well suited for linking small, single-file, absolute assembler programs as it is for linking large, relocatable input, multi-module, C/C++, or mixed C/C++ and assembler programs.

### SPECIFIC ELF TOOLS

ILINK both uses and produces industry-standard ELF and DWARF as object format, additional IAR utilities that handle these formats are provided:

- The IAR Archive Tool—iarchive—creates and manipulates a library (archive) of several ELF object files
- The IAR ELF Tool—ielftool—performs various transformations on an ELF executable image (such as, fill, checksum, format conversion etc)
- The IAR ELF Dumper for ARM—ielfdumparm—creates a text representation of the contents of an ELF relocatable or executable image
- The IAR ELF Object Tool—iobjmanip—is used for performing low-level manipulation of ELF object files
- The IAR Absolute Symbol Exporter—isymexport—exports absolute symbols from a ROM image file, so that they can be used when linking an add-on application.

**Note:** These ELF utilities are well-suited for object files produced by the tools from IAR Systems. Thus, we recommend using them instead of the GNU binary utilities.

### **EXTERNAL TOOLS**

For information about how to extend the tool chain in the IDE, see the *IDE Project Management and Building Guide for ARM*®.

### IAR language overview

There are two high-level programming languages you can use with the IAR C/C++ Compiler for ARM:

- C, the most widely used high-level programming language in the embedded systems industry. You can build freestanding applications that follow these standards:
  - Standard C—also known as C99. Hereafter, this standard is referred to as *Standard C* in this guide.
  - C89—also known as C94, C90, C89, and ANSI C. This standard is required when MISRA C is enabled.
- C++, a modern object-oriented programming language with a full-featured library well suited for modular programming. Any of these standards can be used:
  - Standard C++—can be used with different levels of support for exceptions and runtime type information (RTTI).
  - Embedded C++ (EC++)—a subset of the C++ programming standard, which is intended for embedded systems programming. It is defined by an industry consortium, the Embedded C++ Technical committee. See the chapter *Using* C++.
  - IAR Extended Embedded C++ (EEC++)—EC++ with additional features such as full template support, multiple inheritance, namespace support, the new cast operators, as well as the Standard Template Library (STL).

Each of the supported languages can be used in *strict* or *relaxed* mode, or relaxed with IAR extensions enabled. The strict mode adheres to the standard, whereas the relaxed mode allows some common deviations from the standard.

For more information about C, see the chapter Using C.

For more information about C++, Embedded C++, and Extended Embedded C++, see the chapter *Using C++*.

For information about how the compiler handles the implementation-defined areas of the languages, see the chapter *Implementation-defined behavior*.

It is also possible to implement parts of the application, or the whole application, in assembler language. See the ARM® IAR Assembler Reference Guide.

## **Device support**

To get a smooth start with your product development, the IAR product installation comes with a wide range of device-specific support.

### SUPPORTED ARM DEVICES

The IAR C/C++ Compiler for ARM supports several different ARM cores and devices based on the instruction sets version 4, 5, 6, 6M, and 7. The object code that the compiler generates is not always binary compatible between the cores. Therefore it is crucial to specify a processor option to the compiler. The default core is ARM7TDMI.

### PRECONFIGURED SUPPORT FILES

The IAR product installation contains preconfigured files for supporting different devices. If you need additional files for device support, they can be created using one of the provided ones as a template.

### Header files for I/O

Standard peripheral units are defined in device-specific I/O header files with the filename extension h. The product package supplies I/O files for all devices that are available at the time of the product release. You can find these files in the arm\inc\<vendor> directory. Make sure to include the appropriate include file in your application source files. If you need additional I/O header files, they can be created using one of the provided ones as a template. For detailed information about the header file format, see EWARM\_HeaderFormat.pdf located in the arm\doc\ directory.

### **Device description files**

The debugger handles several of the device-specific requirements, such as definitions of peripheral registers and groups of these, by using device description files. These files are located in the arm\inc directory and they have the filename extension ddf. For more information about these files, see the *C-SPY® Debugging Guide for ARM®* and EWARM DDFFormat.pdf located in the arm\doc\ directory.

### **EXAMPLES FOR GETTING STARTED**

The arm\examples directory contains several hundreds of examples of working applications to give you a smooth start with your development. The complexity of the examples ranges from simple LED blink to USB mass storage controllers. Examples are provided for most of the supported devices.

## Special support for embedded systems

This section briefly describes the extensions provided by the compiler to support specific features of the ARM core.

### **EXTENDED KEYWORDS**

The compiler provides a set of keywords that can be used for configuring how the code is generated. For example, there are keywords for declaring special function types.



By default, language extensions are enabled in the IDE.

The command line option -e makes the extended keywords available, and reserves them so that they cannot be used as variable names. See, -e, page 225 for additional information.

For more information about the extended keywords, see the chapter Extended keywords.

#### PRAGMA DIRECTIVES

The pragma directives control the behavior of the compiler, for example how it allocates memory, whether it allows extended keywords, and whether it issues warning messages.

The pragma directives are always enabled in the compiler. They are consistent with standard C, and are very useful when you want to make sure that the source code is portable.

For more information about the pragma directives, see the chapter *Pragma directives*.

### PREDEFINED SYMBOLS

With the predefined preprocessor symbols, you can inspect your compile-time environment, for example the CPU mode and time of compilation.

For more information about the predefined symbols, see the chapter *The preprocessor*.

### **SPECIAL FUNCTION TYPES**

The special hardware features of the ARM cores are supported by the compiler's special function types: software interrupts, interrupts, and fast interrupts. You can write a complete application without having to write any of these functions in assembler language.

For more information, see *Primitives for interrupts, concurrency, and OS-related programming*, page 59.

### **ACCESSING LOW-LEVEL FEATURES**

For hardware-related parts of your application, accessing low-level features is essential. The compiler supports several ways of doing this: intrinsic functions, mixing C and assembler modules, and inline assembler. For information about the different methods, see *Mixing C and assembler*, page 125.

Special support for embedded systems

# Developing embedded applications

This chapter provides the information you need to get started developing your embedded software for the ARM core using the IAR build tools.

First, you will get an overview of the tasks related to embedded software development, followed by an overview of the build process, including the steps involved for compiling and linking an application.

Next, the program flow of an executing application is described.

Finally, you will get an overview of the basic settings needed for a project.

## Developing embedded software using IAR build tools

Typically, embedded software written for a dedicated microcontroller is designed as an endless loop waiting for some external events to happen. The software is located in ROM and executes on reset. You must consider several hardware and software factors when you write this kind of software.

#### MAPPING OF INTERNAL AND EXTERNAL MEMORY

Embedded systems typically contain various types of memory, such as on-chip RAM, external DRAM or SRAM, ROM, EEPROM, or flash memory.

As an embedded software developer, you must understand the features of the different memory types. For example, on-chip RAM is often faster than other types of memories, and variables that are accessed often would in time-critical applications benefit from being placed here. Conversely, some configuration data might be accessed seldom but must maintain their value after power off, so they should be saved in EEPROM or flash memory.

For efficient memory usage, the compiler provides several mechanisms for controlling placement of functions and data objects in memory. For more information, see *Controlling data and function placement in memory*, page 182. The linker places sections of code and data in memory according to the directives you specify in the linker configuration file, see *Placing code and data—the linker configuration file*, page 71.

#### **COMMUNICATION WITH PERIPHERAL UNITS**

If external devices are connected to the microcontroller, you might need to initialize and control the signalling interface, for example by using chip select pins, and detect and handle external interrupt signals. Typically, this must be initialized and controlled at runtime. The normal way to do this is to use special function registers, or SFRs. These are typically available at dedicated addresses, containing bits that control the chip configuration.

Standard peripheral units are defined in device-specific I/O header files with the filename extension h. See *Device support*, page 33. For an example, see *Accessing special function registers*, page 195.

#### **EVENT HANDLING**

In embedded systems, using *interrupts* is a method for handling external events immediately; for example, detecting that a button was pressed. In general, when an interrupt occurs in the code, the core immediately stops executing the code it runs, and starts executing an interrupt routine instead.

The compiler supports the following processor exception types: interrupts, software interrupts, and fast interrupts, which means that you can write your interrupt routines in C, see *Interrupt functions*, page 59.

#### **SYSTEM STARTUP**

In all embedded systems, system startup code is executed to initialize the system—both the hardware and the software system—before the main function of the application is called. The CPU imposes this by starting execution from a fixed memory address.

As an embedded software developer, you must ensure that the startup code is located at the dedicated memory addresses, or can be accessed using a pointer from the vector table. This means that startup code and the initial vector table must be placed in non-volatile memory, such as ROM, EPROM, or flash.

A C/C++ application further needs to initialize all global variables. This initialization is handled by the linker and the system startup code in conjunction. For more information, see *Application execution—an overview*, page 42.

#### REAL-TIME OPERATING SYSTEMS

In many cases, the embedded application is the only software running in the system. However, using an RTOS has some advantages.

For example, the timing of high-priority tasks is not affected by other parts of the program which are executed in lower priority tasks. This typically makes a program

more deterministic and can reduce power consumption by using the CPU efficiently and putting the CPU in a lower-power state when idle.

Using an RTOS can make your program easier to read and maintain, and in many cases smaller as well. Application code can be cleanly separated in tasks which are truly independent of each other. This makes teamwork easier, as the development work can be easily split into separate tasks which are handled by one developer or a group of developers.

Finally, using an RTOS reduces the hardware dependence and creates a clean interface to the application, making it easier to port the program to different target hardware.

#### INTEROPERABILITY WITH OTHER BUILD TOOLS

The IAR compiler and linker provide support for AEABI, the Embedded Application Binary Interface for ARM. For more information about this interface specification, see the www.arm.com web site.

The advantage of this interface is the interoperability between vendors supporting it; an application can be built up of libraries of object files produced by different vendors and linked with a linker from any vendor, as long as they adhere to the AEABI standard.

AEABI specifies full compatibility for C and C++ object code, and for the C library. The AEABI does not include specifications for the C++ library.

For more information about the AEABI support in the IAR build tools, see *AEABI compliance*, page 174.

The ARM IAR build tools version 6.xx are not fully compatible with earlier versions of the product, see the *IAR Embedded Workbench*® *Migration Guide for ARM*® for more information.

## The build process—an overview

This section gives an overview of the build process; how the various build tools—compiler, assembler, and linker—fit together, going from source code to an executable image.

To get familiar with the process in practice, you should run one or more of the tutorials available from the IAR Information Center.

#### THE TRANSLATION PROCESS

There are two tools in the IDE that translate application source files to intermediary object files. The IAR C/C++ Compiler and the IAR Assembler. Both produce relocatable object files in the industry-standard format ELF, including the DWARF format for debug information.

**Note:** The compiler can also be used for translating C/C++ source code into assembler source code. If required, you can modify the assembler source code which then can be assembled into object code. For more information about the IAR Assembler, see the *ARM® IAR Assembler Reference Guide*.

This illustration shows the translation process:

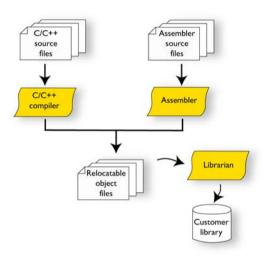


Figure 1: The build process before linking

After the translation, you can choose to pack any number of modules into an archive, or in other words, a library. The important reason you should use libraries is that each module in a library is conditionally linked in the application, or in other words, is only included in the application if the module is used directly or indirectly by a module supplied as an object file. Optionally, you can create a library; then use the IAR utility iarchive.

#### THE LINKING PROCESS

The relocatable modules, in object files and libraries, produced by the IAR compiler and assembler cannot be executed as is. To become an executable application, they must be *linked*.

**Note:** Modules produced by a toolset from another vendor can be included in the build as well. Be aware that this also might require a compiler utility library from the same vendor.

The IAR ILINK Linker (ilinkarm.exe) is used for building the final application. Normally, ILINK requires the following information as input:

- Several object files and possibly certain libraries
- A program start label (set by default)
- The linker configuration file that describes placement of code and data in the memory of the target system.

This illustration shows the linking process:

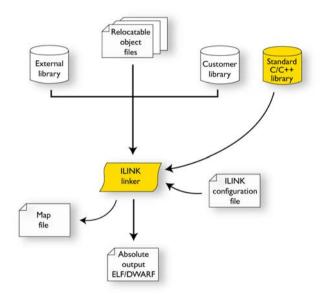


Figure 2: The linking process

**Note:** The Standard C/C++ library contains support routines for the compiler, and the implementation of the C/C++ standard library functions.

During the linking, ILINK might produce error messages and logging messages on stdout and stderr. The log messages are useful for understanding why an application was linked the way it was, for example, why a module was included or a section removed.

For more information about the procedure performed by ILINK, see *The linking process*, page 69.

#### **AFTER LINKING**

The IAR ILINK Linker produces an absolute object file in ELF format that contains the executable image. After linking, the produced absolute executable image can be used for:

- Loading into the IAR C-SPY Debugger or any other compatible external debugger that reads ELF and DWARF.
- Programming to a flash/PROM using a flash/PROM programmer. Before this is
  possible, the actual bytes in the image must be converted into the standard Motorola
  32-bit S-record format or the Intel Hex-32 format. For this, use ielftool, see *The IAR ELF Tool—ielftool*, page 412.

This illustration shows the possible uses of the absolute output ELF/DWARF file:

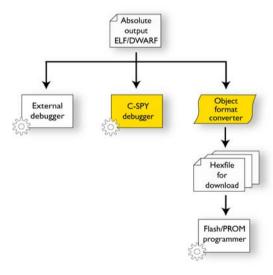


Figure 3: Possible uses of the absolute output ELF/DWARF file

## Application execution—an overview

This section gives an overview of the execution of an embedded application divided into three phases, the:

- Initialization phase
- Execution phase
- Termination phase.

#### THE INITIALIZATION PHASE

• Application initialization

Initialization is executed when an application is started (the CPU is reset) but before the main function is entered. The initialization phase can for simplicity be divided into:

- Hardware initialization, which generally at least initializes the stack pointer.

  The hardware initialization is typically performed in the system startup code cstartup.s and if required, by an extra low-level routine that you provide. It might include resetting/starting the rest of the hardware, setting up the CPU, etc, in preparation for the software C/C++ system initialization.
- Software C/C++ system initialization
   Typically, this includes assuring that every global (statically linked) C/C++ symbol receives its proper initialization value before the main function is called.
  - This depends entirely on your application. It can include setting up an RTOS kernel and starting initial tasks for an RTOS-driven application. For a bare-bone application, it can include setting up various interrupts, initializing communication, initializing devices, etc.

For a ROM/flash-based system, constants and functions are already placed in ROM. All symbols placed in RAM must be initialized before the main function is called. The linker has already divided the available RAM into different areas for variables, stack, heap, etc.

The following sequence of illustrations gives a simplified overview of the different stages of the initialization.

I When an application is started, the system startup code first performs hardware initialization, such as initialization of the stack pointer to point at the end of the predefined stack area:

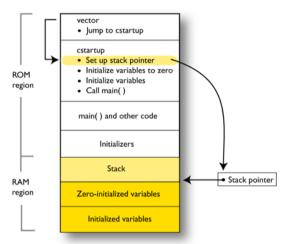


Figure 4: Initializing hardware

**2** Then, memories that should be zero-initialized are cleared, in other words, filled with zeros:

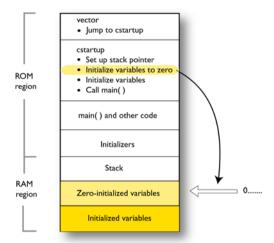


Figure 5: Zero-initializing variables

Typically, this is data referred to as *zero-initialized data*; variables declared as, for example, int i = 0;

**3** For *initialized data*, data declared, for example, like int i = 6; the initializers are copied from ROM to RAM:

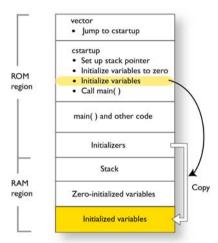


Figure 6: Initializing variables

**4** Finally, the main function is called:

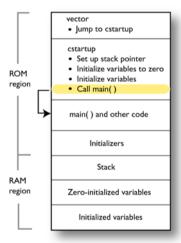


Figure 7: Calling main

For more information about each stage, see *System startup and termination*, page 103. For more information about initialization of data, see *Initialization at system startup*, page 73.

#### THE EXECUTION PHASE

The software of an embedded application is typically implemented as a loop which is either interrupt-driven or uses polling for controlling external interaction or internal events. For an interrupt-driven system, the interrupts are typically initialized at the beginning of the main function.

In a system with real-time behavior and where responsiveness is critical, a multi-task system might be required. This means that your application software should be complemented with a real-time operating system. In this case, the RTOS and the different tasks must also be initialized at the beginning of the main function.

#### THE TERMINATION PHASE

Typically, the execution of an embedded application should never end. If it does, you must define a proper end behavior.

To terminate an application in a controlled way, either call one of the Standard C library functions exit, \_Exit, or abort, or return from main. If you return from main, the exit function is executed, which means that C++ destructors for static and global variables are called (C++ only) and all open files are closed.

Of course, in case of incorrect program logic, the application might terminate in an uncontrolled and abnormal way—a system crash.

For more information about this, see System termination, page 105.

## **Building applications—an overview**

In the command line interface, this line compiles the source file myfile.c into the object file myfile.o using the default settings:

iccarm myfile.c

On the command line, this line can be used for starting ILINK:

ilinkarm myfile.o myfile2.o -o a.out --config my\_configfile.icf

In this example, myfile.o and myfile2.o are object files, and my\_configfile.icf is the linker configuration file. The option -o specifies the name of the output file.

**Note:** By default, the label where the application starts is \_\_iar\_program\_start. You can use the --entry command line option to change this.

## **Basic project configuration**

This section gives an overview of the basic settings for the project setup that are needed to make the compiler and linker generate the best code for the ARM device you are using. You can specify the options either from the command line interface or in the IDE.

You need settings for:

- Processor configuration, that is processor variant, CPU mode, interworking, VFP and floating-point arithmetic, and byte order
- Optimization settings
- Runtime environment
- Customizing the ILINK configuration, see the chapter Linking your application.

In addition to these settings, many other options and settings can fine-tune the result even further. For information about how to set options and for a list of all available options, see the chapters Compiler options, Linker options, and the IDE Project Management and Building Guide for ARM®, respectively.

#### PROCESSOR CONFIGURATION

To make the compiler generate optimum code, you should configure it for the ARM core you are using.

#### **Processor variant**

The IAR C/C++ Compiler for ARM supports several different ARM cores and devices based on the instruction sets version 4, 5, 6, and 7. All supported cores support Thumb instructions and 64-bit multiply instructions. The object code that the compiler generates is not always binary compatible between the cores. Therefore it is crucial to specify a processor option to the compiler. The default core is ARM7TDMI.



See the IDE Project Management and Building Guide for ARM® for information about setting the **Processor variant** option in the IDE.



Use the --cpu option to specify the ARM core; see --cpu, page 218 for syntax information.

#### CPU mode

The IAR C/C++ Compiler for ARM supports two CPU modes: ARM and Thumb.

All functions and function pointers will compile in the mode that you specify, except those explicitly declared \_\_arm or \_\_thumb.



See the IDE Project Management and Building Guide for ARM® for information about setting the **Processor variant** or **Chip** option in the IDE.



Use the --arm or --thumb option to specify the CPU mode for your project; see --arm, page 217 and --thumb, page 247, for syntax information.

#### Interworking

When code is compiled with the --interwork option, ARM and Thumb code can be freely mixed. Interworking functions can be called from both ARM and Thumb code. Interworking is default for devices based on the instruction sets version 5, 6, and 7, or when using the --aeabi compiler option.



See the *IDE Project Management and Building Guide for ARM*® for information about setting the **Generate interwork code** option in the IDE.



Use the --interwork option to specify interworking capabilities for your project; see --interwork, page 229, for syntax information.

#### VFP and floating-point arithmetic

If you are using an ARM core that contains a Vector Floating Point (VFP) coprocessor, you can use the --fpu option to generate code that carries out floating-point operations utilizing the coprocessor, instead of using the software floating-point library routines.



See the *IDE Project Management and Building Guide for ARM*® for information about setting the **FPU** option in the IDE.



Use the --fpu option to use the coprocessor for floating-point operations; see --fpu, page 228, for syntax information.

#### Byte order

The IAR C/EC++ Compiler for ARM supports the big-endian and little-endian byte order. All user and library modules in your application must use the same byte order.



See the *IDE Project Management and Building Guide for ARM*® for information about setting the **Endian mode** option in the IDE.



Use the --endian option to specify the byte order for your project; see --endian, page 226, for syntax information.

#### **OPTIMIZATION FOR SPEED AND SIZE**

The compiler's optimizer that performs, among other things, dead-code elimination, constant propagation, inlining, common subexpression elimination, static clustering, instruction scheduling, and precision reduction. It also performs loop optimizations, such as unrolling and induction variable elimination.

You can decide between several optimization levels and for the highest level you can choose between different optimization goals—*size*, *speed*, or *balanced*. Most

optimizations will make the application both smaller and faster. However, when this is not the case, the compiler uses the selected optimization goal to decide how to perform the optimization.

The optimization level and goal can be specified for the entire application, for individual files, and for individual functions. In addition, some individual optimizations, such as function inlining, can be disabled.

For information about compiler optimizations and for more information about efficient coding techniques, see the chapter *Efficient coding for embedded applications*.

#### **RUNTIME ENVIRONMENT**

To create the required runtime environment you should choose a runtime library and set library options. You might also need to override certain library modules with your own customized versions.

The runtime library provided is the IAR DLIB Library, which supports Standard C and C++. This library also supports floating-point numbers in IEEE 754 format and it can be configured to include different levels of support for locale, file descriptors, multibyte characters, etc.

The runtime library contains the functions defined by the C and the C++ standards, and include files that define the library interface (the system header files).

The runtime library you choose can be one of the prebuilt libraries, or a library that you customized and built yourself. The IDE provides a library project template that you can use for building your own library version. This gives you full control of the runtime environment. If your project only contains assembler source code, you do not need to choose a runtime library.

For more information about the runtime environments, see the chapters *The DLIB* runtime environment.



#### Setting up for the runtime environment in the IDE

The library is automatically chosen by the linker according to the settings you made in **Project>Options>General Options**, on the pages **Library Configuration**, **Library Options**, and **Library Usage**.

Note that for the DLIB library there are different configurations—Normal and Full—which include different levels of support for locale, file descriptors, multibyte characters, et cetera. See *Library configurations*, page 107, for more information.

Based on which library configuration you choose and your other project settings, the correct library file is used automatically. For the device-specific include files, a correct include path is set up.



#### Setting up for the runtime environment from the command line

You do not have to specify a library file explicitly, as ILINK automatically uses the correct library file.

A library configuration file that matches the library object file is automatically used. To explicitly specify a library configuration, use the --dlib\_config option.

In addition to these options you might want to specify any target-specific linker options or the include path to application-specific header files by using the -I option, for example:

-I arm\inc

For information about the prebuilt library object files for the IAR DLIB Library, see *Using prebuilt libraries*, page 91.

#### Setting library and runtime environment options

You can set certain options to reduce the library and runtime environment size:

- The formatters used by the functions printf, scanf, and their variants, see *Choosing formatters for printf and scanf*, page 94 (DLIB) and page 149.
- The size of the stack and the heap, see *The stack*, page 104, and *The heap*, page 106, respectively.

Basic project configuration

## **Data storage**

This chapter gives a brief introduction to the memory layout of the ARM core and the fundamental ways data can be stored in memory: on the stack, in static (global) memory, or in heap memory. Finally, detailed information about data storage on the stack and the heap is provided.

#### Introduction

An ARM core can address 4 Gbytes of continuous memory, ranging from 0x000000000 to 0xffffffff. Different types of physical memory can be placed in the memory range. A typical application will have both read-only memory (ROM) and read/write memory (RAM). In addition, some parts of the memory range contain processor control registers and peripheral units.

#### **DIFFERENT WAYS TO STORE DATA**

In a typical application, data can be stored in memory in three different ways:

- Auto variables
  - All variables that are local to a function, except those declared static, are stored on the stack. These variables can be used as long as the function executes. When the function returns to its caller, the memory space is no longer valid.
- Global variables, module-static variables, and local variables declared static
   In this case, the memory is allocated once and for all. The word static in this context means that the amount of memory allocated for this kind of variables does not change while the application is running. The ARM core has one single address space and the compiler supports full memory addressing.
- Dynamically allocated data.
  - An application can allocate data on the *heap*, where the data remains valid until it is explicitly released back to the system by the application. This type of memory is useful when the number of objects is not known until the application executes. Note that there are potential risks connected with using dynamically allocated data in systems with a limited amount of memory, or systems that are expected to run for a long time. For more information, see *Dynamic memory on the heap*, page 55.

## Auto variables—on the stack

Variables that are defined inside a function—and not declared static—are named *auto variables* by the C standard. A few of these variables are placed in processor registers; the rest are placed on the stack. From a semantic point of view, this is equivalent. The main differences are that accessing registers is faster, and that less memory is required compared to when variables are located on the stack.

Auto variables can only live as long as the function executes; when the function returns, the memory allocated on the stack is released.

#### THE STACK

The stack can contain:

- Local variables and parameters not stored in registers
- Temporary results of expressions
- The return value of a function (unless it is passed in registers)
- Processor state during interrupts
- Processor registers that should be restored before the function returns (callee-save registers).

The stack is a fixed block of memory, divided into two parts. The first part contains allocated memory used by the function that called the current function, and the function that called it, etc. The second part contains free memory that can be allocated. The borderline between the two areas is called the *top of stack* and is represented by the stack pointer, which is a dedicated processor register. Memory is allocated on the stack by moving the stack pointer.

A function should never refer to the memory in the area of the stack that contains free memory. The reason is that if an interrupt occurs, the called interrupt function can allocate, modify, and—of course—deallocate memory on the stack.

#### **Advantages**

The main advantage of the stack is that functions in different parts of the program can use the same memory space to store their data. Unlike a heap, a stack will never become fragmented or suffer from memory leaks.

It is possible for a function to call itself either directly or indirectly—a *recursive function*—and each invocation can store its own data on the stack.

#### Potential problems

The way the stack works makes it impossible to store data that is supposed to live after the function returns. The following function demonstrates a common programming mistake. It returns a pointer to the variable x, a variable that ceases to exist when the function returns.

```
int *MyFunction()
{
  int x;
  /* Do something here. */
  return &x; /* Incorrect */
}
```

Another problem is the risk of running out of stack. This will happen when one function calls another, which in turn calls a third, etc., and the sum of the stack usage of each function is larger than the size of the stack. The risk is higher if large data objects are stored on the stack, or when recursive functions are used.

## Dynamic memory on the heap

Memory for objects allocated on the heap will live until the objects are explicitly released. This type of memory storage is very useful for applications where the amount of data is not known until runtime.

In C, memory is allocated using the standard library function malloc, or one of the related functions calloc and realloc. The memory is released again using free.

In C++, a special keyword, new, allocates memory and runs constructors. Memory allocated with new must be released using the keyword delete.

For related information, see --basic\_heap, page 253.

#### **Potential problems**

Applications that are using heap-allocated objects must be designed very carefully, because it is easy to end up in a situation where it is not possible to allocate objects on the heap.

The heap can become exhausted if your application uses too much memory. It can also become full if memory that no longer is in use was not released.

For each allocated memory block, a few bytes of data for administrative purposes is required. For applications that allocate a large number of small blocks, this administrative overhead can be substantial.

There is also the matter of *fragmentation*; this means a heap where small sections of free memory is separated by memory used by allocated objects. It is not possible to allocate a new object if no piece of free memory is large enough for the object, even though the sum of the sizes of the free memory exceeds the size of the object.

Unfortunately, fragmentation tends to increase as memory is allocated and released. For this reason, applications that are designed to run for a long time should try to avoid using memory allocated on the heap.

## **Functions**

This chapter contains information about functions. It gives a brief overview of function-related extensions—mechanisms for controlling functions—and describes some of these mechanisms in more detail.

### **Function-related extensions**

In addition to supporting Standard C, the compiler provides several extensions for writing functions in C. Using these, you can:

- Generate code for the different CPU modes ARM and Thumb
- Make functions execute in RAM
- Use primitives for interrupts, concurrency, and OS-related programming
- Facilitate function optimization
- Access hardware features.

The compiler uses compiler options, extended keywords, pragma directives, and intrinsic functions to support this.

For more information about optimizations, see *Efficient coding for embedded applications*, page 179. For information about the available intrinsic functions for accessing hardware operations, see the chapter *Intrinsic functions*.

## **ARM** and Thumb code

The IAR C/C++ Compiler for ARM can generate code for either the 32-bit ARM, or the 16-bit Thumb or Thumb2 instruction set. Use the --cpu\_mode option, alternatively the --arm or --thumb options, to specify which instruction set should be used for your project. For individual functions, it is possible to override the project setting by using the extended keywords \_\_arm and \_\_thumb. You can freely mix ARM and thumb code in the same application, as long as the code is interworking.

The size of all code pointers is 4 bytes. There are restrictions to implicit and explicit casts from code pointers to data pointers or integer types or vice versa. For further information about the restrictions, see *Pointer types*, page 284.

In the chapter Assembler language interface, the generated code is studied in more detail in the description of calling C functions from assembler language and vice versa.

## **Execution in RAM**

The \_\_ramfunc keyword makes a function execute in RAM. In other words it places the function in a section that has read/write attributes. The function is copied from ROM to RAM at system startup just like any initialized variable, see *System startup and termination*, page 103.

The keyword is specified before the return type:

```
__ramfunc void foo(void);
```

If a function declared \_\_ramfunc tries to access ROM, the compiler will issue a warning.

If the whole memory area used for code and constants is disabled—for example, when the whole flash memory is being erased—only functions and data stored in RAM may be used. Interrupts must be disabled unless the interrupt vector and the interrupt service routines are also stored in RAM.

String literals and other constants can be avoided by using initialized variables. For example, the following lines:

```
__ramfunc void test()
{
    /* myc: initializer in ROM */
    const int myc[] = { 10, 20 };

    /* string literal in ROM */
    msg("Hello");
}

can be rewritten to:
    __ramfunc void test()
{
    /* myc: initialized by cstartup */
    static int myc[] = { 10, 20 };

    /* hello: initialized by cstartup */
    static char hello[] = "Hello";

    msg(hello);
}
```

For more details, see Initializing code—copying ROM to RAM, page 84.

## Primitives for interrupts, concurrency, and OS-related programming

The IAR C/C++ Compiler for ARM provides the following primitives related to writing interrupt functions, concurrent functions, and OS-related functions:

- The extended keywords \_\_irg, \_\_fig, \_\_swi, and \_\_nested
- The intrinsic functions \_\_enable\_interrupt, \_\_disable\_interrupt, \_\_get\_interrupt\_state, and \_\_set\_interrupt\_state.

**Note:** ARM Cortex-M has a different interrupt mechanism than other ARM devices, and for these devices a different set of primitives is available. For more details, see *Interrupts for ARM Cortex-M*, page 64.

#### INTERRUPT FUNCTIONS

In embedded systems, using interrupts is a method for handling external events immediately; for example, detecting that a button was pressed.

#### Interrupt service routines

In general, when an interrupt occurs in the code, the core immediately stops executing the code it runs, and starts executing an interrupt routine instead. It is important that the environment of the interrupted function is restored after the interrupt is handled (this includes the values of processor registers and the processor status register). This makes it possible to continue the execution of the original code after the code that handled the interrupt was executed.

The compiler supports interrupts, software interrupts, and fast interrupts. For each interrupt type, an interrupt routine can be written.

All interrupt functions must be compiled in ARM mode; if you are using Thumb mode, use the \_\_arm extended keyword or the #pragma type\_attribute=\_\_arm directive to override the default behavior.

#### Interrupt vectors and the interrupt vector table

Each interrupt routine is associated with a vector address/instruction in the exception vector table, which is specified in the ARM cores documentation. The interrupt vector is the address in the exception vector table. For the ARM cores, the exception vector table starts at address 0x0.

#### Defining an interrupt function—an example

To define an interrupt function, the <code>\_\_irq</code> or the <code>\_\_fiq</code> keyword can be used. For example:

```
__irq __arm void IRQ_Handler(void)
{
    /* Do something */
}
```

See the ARM cores documentation for more information about the interrupt vector table.

An interrupt function must have the return type void, and it cannot specify any parameters. **INSTALLING EXCEPTION FUNCTIONS** 

All interrupt functions and software interrupt handlers must be installed in the vector table. This is done in assembler language in the system startup file cstartup.s.

The default implementation of the ARM exception vector table in the standard runtime library jumps to predefined functions that implement an infinite loop. Any exception that occurs for an event not handled by your application will therefore be caught in the infinite loop (B.).

The predefined functions are defined as weak symbols. A weak symbol is only included by the linker as long as no duplicate symbol is found. If another symbol is defined with the same name, it will take precedence. Your application can therefore simply define its own exception function by just defining it using the correct name.

These exception function names are defined in cstartup.s and referred to by the library exception vector code:

```
Undefined_Handler
SWI_Handler
Prefetch_Handler
Abort_Handler
IRQ_Handler
FIQ_Handler
```

To implement your own exception handler, define a function using the appropriate exception function name from the list above.

For example to add an interrupt function in C, it is sufficient to define an interrupt function named IRQ\_Handler:

```
__irq __arm void IRQ_Handler()
{
}
```

An interrupt function must have C linkage, read more in Calling convention, page 132.

If you use C++, an interrupt function could look, for example, like this:

```
extern "C"
{
    __irq __arm void IRQ_Handler(void);
}
__irq __arm void IRQ_Handler(void)
{
}
```

No other changes are needed.

#### **INTERRUPTS AND FAST INTERRUPTS**

The interrupt and fast interrupt functions are easy to handle as they do not accept parameters or have a return value.

- To declare an interrupt function, use the \_\_irq extended keyword or the #pragma type\_attribute=\_\_irq directive. For syntax information, see \_\_irq, page 296, and type\_attribute, page 320, respectively.
- To declare a fast interrupt function, use the \_\_fiq extended keyword or the #pragma type\_attribute=\_\_fiq directive. For syntax information, see \_\_fiq, page 296, and type\_attribute, page 320, respectively.

**Note:** An interrupt function (irq) and a fast interrupt function (fiq) must have a return type of void and cannot have any parameters. A software interrupt function (swi) may have parameters and return values. By default, only four registers, R0-R3, can be used for parameters and only the registers R0-R1 can be used for return values.

#### **NESTED INTERRUPTS**

Interrupts are automatically disabled by the ARM core prior to entering an interrupt handler. If an interrupt handler re-enables interrupts, calls functions, and another interrupt occurs, then the return address of the interrupted function—stored in LR—is overwritten when the second IRQ is taken. In addition, the contents of SPSR will be destroyed when the second interrupt occurs. The <code>\_\_irq</code> keyword itself does not save and restore LR and SPSR. To make an interrupt handler perform the necessary steps needed when handling nested interrupts, the keyword <code>\_\_nested</code> must be used in addition to <code>\_\_irq</code>. The function prolog—function entrance sequence—that the compiler generates for nested interrupt handlers will switch from IRQ mode to system mode. Make sure that both the IRQ stack and system stack is set up. If you use the default <code>cstartup.s</code> file, both stacks are correctly set up.

Compiler-generated interrupt handlers that allow nested interrupts are supported for IRQ interrupts only. The FIQ interrupts are designed to be serviced quickly, which in most cases mean that the overhead of nested interrupts would be too high.

This example shows how to use nested interrupts with the ARM vectored interrupt controller (VIC):

```
__irq __nested __arm void interrupt_handler(void)

void (*interrupt_task)();
unsigned int vector;

/* Get interrupt vector. */
vector = VICVectAddr;

/* Acknowledge interrupt in VIC. */
VICVectAddr = 0;

interrupt_task = (void(*)()) vector;

/* Allow other IRQ interrupts to be serviced. */
__enable_interrupt();

/* Execute the task associated with this interrupt. */
(*interrupt_task)();
```

**Note:** The \_\_nested keyword requires the processor mode to be in either User or System mode.

#### **SOFTWARE INTERRUPTS**

Software interrupt functions are slightly more complex than other interrupt functions, in the way that they need a software interrupt handler (a dispatcher), are invoked (called) from running application software, and that they accept arguments and have return values. The mechanisms for calling a software interrupt function and how the software interrupt handler dispatches the call to the actual software interrupt function is described here.

#### Calling a software interrupt function

To call a software interrupt function from your application source code, the assembler instruction SVC #immed is used, where immed is an integer value that is referred to as the software interrupt number—or swi\_number—in this guide. The compiler provides an easy way to implicitly generate this instruction from C/C++ source code, by using the \_\_swi keyword and the #pragma swi\_number directive when declaring the function.

A \_\_swi function can for example be declared like this:

```
#pragma swi_number=0x23
__swi int swi_function(int a, int b);
```

In this case, the assembler instruction SVC 0x23 will be generated where the function is called.

Software interrupt functions follow the same calling convention regarding parameters and return values as an ordinary function, except for the stack usage, see *Calling convention*, page 132.

For more information, see \_\_swi, page 300, and swi\_number, page 320, respectively.

#### The software interrupt handler and functions

The interrupt handler, for example SWI\_Handler works as a dispatcher for software interrupt functions. It is invoked from the interrupt vector and is responsible for retrieving the software interrupt number and then calling the proper software interrupt function. The SWI\_Handler must be written in assembler as there is no way to retrieve the software interrupt number from C/C++ source code.

#### The software interrupt functions

The software interrupt functions can be written in C or C++. Use the \_\_swi keyword in a function definition to make the compiler generate a return sequence suited for a specific software interrupt function. The #pragma swi\_number directive is not needed in the interrupt function definition.

For more information, see *swi*, page 300.

#### Setting up the software interrupt stack pointer

If software interrupts will be used in your application, then the software interrupt stack pointer (SVC\_STACK) must be set up and some space must be allocated for the stack. The SVC\_STACK pointer can be set up together with the other stacks in the cstartup.s file. As an example, see the set up of the interrupt stack pointer. Relevant space for the SVC\_STACK pointer is set up in the linker configuration file, see *Setting up the stack*, page 81.

#### INTERRUPT OPERATIONS

An interrupt function is called when an external event occurs. Normally it is called immediately while another function is executing. When the interrupt function has finished executing, it returns to the original function. It is imperative that the environment of the interrupted function is restored; this includes the value of processor registers and the processor status register.

When an interrupt occurs, the following actions are performed:

• The operating mode is changed corresponding to the particular exception

- The address of the instruction following the exception entry instruction is saved in R14 of the new mode.
- The old value of the CPSR is saved in the SPSR of the new mode
- Interrupt requests are disabled by setting bit 7 of the CPSR and, if the exception is a
  fast interrupt, further fast interrupts are disabled by setting bit 6 of the CPSR
- The PC is forced to begin executing at the relevant vector address.

For example, if an interrupt for vector 0x18 occurs, the processor will start to execute code at address 0x18. The memory area that is used as start location for interrupts is called the interrupt vector table. The content of the interrupt vector is normally a branch instruction jumping to the interrupt routine.

**Note:** If the interrupt function enables interrupts, the special processor registers needed to return from the interrupt routine must be assumed to be destroyed. For this reason they must be stored by the interrupt routine to be restored before it returns. This is handled automatically if the \_\_nested keyword is used.

#### INTERRUPTS FOR ARM CORTEX-M

ARM Cortex-M has a different interrupt mechanism than previous ARM architectures, which means the primitives provided by the compiler are also different.

On ARM Cortex-M, an interrupt service routine enters and returns in the same way as a normal function, which means no special keywords are required. Thus, the keywords <code>\_\_irq</code>, <code>\_\_fiq</code>, and <code>\_\_nested</code> are not available when you compile for ARM Cortex-M.

These exception function names are defined in <code>cstartup\_M.c</code> and <code>cstartup\_M.s</code>. They are referred to by the library exception vector code:

NMI\_Handler
HardFault\_Handler
MemManage\_Handler
BusFault\_Handler
UsageFault\_Handler
SVC\_Handler
DebugMon\_Handler
PendSV\_Handler
SysTick Handler

The vector table is implemented as an array. It should always have the name \_\_vector\_table, because cmain refers to that symbol and C-SPY looks for that symbol when determining where the vector table is located.

The predefined exception functions are defined as weak symbols. A weak symbol is only included by the linker as long as no duplicate symbol is found. If another symbol is defined with the same name, it will take precedence. Your application can therefore simply define its own exception function by just defining it using the correct name from the list above. If you need other interrupts or other exception handlers, you must make a copy of the <code>cstartup\_M.c</code> or <code>cstartup\_M.s</code> file and make the proper addition to the vector table.

The intrinsic functions \_\_get\_CPSR and \_\_set\_CPSR are not available when you compile for ARM Cortex-M. Instead, if you need to get or set values of these or other registers, you can use inline assembler. For more information, see *Passing values between C and assembler objects*, page 196.

#### C++ AND SPECIAL FUNCTION TYPES

C++ member functions can be declared using special function types, with the exception that interrupt member functions must be static. When a non-static member function is called, it must be applied to an object. When an interrupt occurs and the interrupt function is called, there is no object available to apply the member function to.

Special function types can be used for static member functions. For example, in the following example, the function handler is declared as an interrupt function:

```
class Device
{
   static __arm __irq void handler();
};
```

Primitives for interrupts, concurrency, and OS-related programming

# Linking using ILINK

This chapter describes the linking process using the IAR ILINK Linker and the related concepts—first with an overview and then in more detail.

## Linking—an overview

The IAR ILINK Linker is a powerful, flexible software tool for use in the development of embedded applications. It is equally well suited for linking small, single-file, absolute assembler programs as it is for linking large, relocatable, multi-module, C/C++, or mixed C/C++ and assembler programs.

ILINK combines one or more relocatable object files—produced by the IAR Systems compiler or assembler—with selected parts of one or more object libraries to produce an executable image in the industry-standard format *Executable and Linking Format* (ELF).

ILINK will automatically load only those library modules—user libraries and Standard C or C++ library variants—that are actually needed by the application you are linking. Further, ILINK eliminates duplicate sections and sections that are not required.

ILINK can link both ARM and Thumb code, as well as a combination of them. By automatically inserting additional instructions (veneers), ILINK will assure that the destination will be reached for any calls and branches, and that the processor state is switched when required. For more details about how to generate veneers, see *Veneers*, page 86.

ILINK uses a *configuration file* where you can specify separate locations for code and data areas of your target system memory map. This file also supports automatic handling of the application's initialization phase, which means initializing global variable areas and code areas by copying initializers and possibly decompressing them as well.

The final output produced by ILINK is an absolute object file containing the executable image in the ELF (including DWARF for debug information) format. The file can be downloaded to C-SPY or any other compatible debugger that supports ELF/DWARF, or it can be stored in EPROM or flash.

To handle ELF files, various tools are included. For information about included utilities, see *Specific ELF tools*, page 32.

#### Modules and sections

Each relocatable object file contains one module, which consists of:

- Several sections of code or data
- Runtime attributes specifying various types of information, for example the version
  of the runtime environment
- Optionally, debug information in DWARF format
- A symbol table of all global symbols and all external symbols used.

A *section* is a logical entity containing a piece of data or code that should be placed at a physical location in memory. A section can consist of several *section fragments*, typically one for each variable or function (symbols). A section can be placed either in RAM or in ROM. In a normal embedded application, sections that are placed in RAM do not have any content, they only occupy space.

Each section has a name and a type attribute that determines the content. The type attribute is used (together with the name) for selecting sections for the ILINK configuration. The most commonly used attributes are:

code Executable code
readonly Constant variables
readwrite Initialized variables
zeroinit Zero-initialized variables

**Note:** In addition to these section types—sections that contain the code and data that are part of your application—a final object file will contain many other types of sections, for example sections that contain debugging information or other type of meta information.

A section is the smallest linkable unit; but if possible, ILINK can exclude smaller units—section fragments—from the final application. For more information, see *Keeping modules*, page 81, and *Keeping symbols and sections*, page 81.

At compile time, data and functions are placed in different sections. At link time, one of the most important functions of the linker is to assign addresses to the various sections used by the application.

The IAR build tools have many predefined section names. See the chapter *Section reference* for more information about each section.

## The linking process

The relocatable modules in object files and libraries, produced by the IAR compiler and assembler, cannot be executed as is. To become an executable application, they must be *linked*.

**Note:** Modules produced by a toolset from another vendor can be included in the build as well, as long as the module is AEABI (ARM Embedded Application Binary Interface) compliant. Be aware that this also might require a compiler utility library from the same vendor.

The IAR ILINK Linker is used for the link process. It normally performs the following procedure (note that some of the steps can be turned off by command line options or by directives in the linker configuration file):

- Determine which modules to include in the application. Modules provided in object
  files are always included. A module in a library file is only included if it provides a
  definition for a global symbol that is referenced from an included module.
- Select which standard library files to use. The selection is based on attributes of the included modules. These libraries are then used for satisfying any still outstanding undefined symbols.
- Determine which sections/section fragments from the included modules to include
  in the application. Only those sections/section fragments that are actually needed by
  the application are included. There are several ways to determine of which
  sections/section fragments that are needed, for example, the \_\_root object
  attribute, the #pragma required directive, and the keep linker directive. In case
  of duplicate sections, only one is included.
- Where appropriate, arrange for the initialization of initialized variables and code in RAM. The initialize directive causes the linker to create extra sections to enable copying from ROM to RAM. Each section that will be initialized by copying is divided into two sections, one for the ROM part and one for the RAM part. If manual initialization is not used, the linker also arranges for the startup code to perform the initialization.
- Determine where to place each section according to the section placement directives
  in the linker configuration file. Sections that are to be initialized by copying appear
  twice in the matching against placement directives, once for the ROM part and once
  for the RAM part, with different attributes. During the placement, the linker also
  adds any required veneers to make a code reference reach its destination or to
  switch CPU modes.
- Produce an absolute file that contains the executable image and any debug information provided. The contents of each needed section in the relocatable input files is calculated using the relocation information supplied in its file and the addresses determined when placing sections. This process can result in one or more

relocation failures if some of the requirements for a particular section are not met, for instance if placement resulted in the destination address for a PC-relative jump instruction being out of range for that instruction.

 Optionally, produce a map file that lists the result of the section placement, the address of each global symbol, and finally, a summary of memory usage for each module and library.

This illustration shows the linking process:

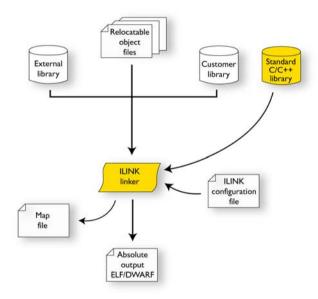


Figure 8: The linking process

During the linking, ILINK might produce error messages and logging messages on stdout and stderr. The log messages are useful for understanding why an application was linked as it was. For example, why a module or section (or section fragment) was included.

**Note:** To see the actual content of an ELF object file, use ielfdumparm. See *The IAR ELF Dumper for ARM—ielfdumparm*, page 414.

## Placing code and data—the linker configuration file

The placement of sections in memory is performed by the IAR ILINK Linker. It uses the *linker configuration file* where you can define how ILINK should treat each section and how they should be placed into the available memories.

A typical linker configuration file contains definitions of:

- Available addressable memories
- Populated regions of those memories
- How to treat input sections
- · Created sections
- How to place sections into the available regions.

The file consists of a sequence of declarative directives. This means that the linking process will be governed by all directives at the same time.

To use the same source code with different derivatives, just rebuild the code with the appropriate configuration file.

#### A SIMPLE EXAMPLE OF A CONFIGURATION FILE

A simple configuration file can look like this:

```
/* The memory space denoting the maximum possible amount
   of addressable memory */
define memory Mem with size = 4G;
/* Memory regions in an address space */
define region ROM = Mem:[from 0x00000 size 0x10000];
define region RAM = Mem: [from 0x20000 size 0x10000];
/* Create a stack */
define block STACK with size = 0x1000, alignment = 8 { };
/* Handle initialization */
do not initialize { section .noinit };
initialize by copy { readwrite }; /* Initialize RW sections,
                                     exclude zero-initialized
                                     sections */
/* Place startup code at a fixed address */
place at start of ROM { readonly section .cstartup };
/* Place code and data */
place in ROM { readonly }; /* Place constants and initializers in
                              ROM: .rodata and .data_init
```

```
place in RAM { readwrite, /* Place .data, .bss, and .noinit */
    block STACK }; /* and STACK */
```

This configuration file defines one addressable memory Mem with the maximum of 4 Gbytes of memory. Further, it defines a ROM region and a RAM region in Mem, namely ROM and RAM. Each region has the size of 64 Kbytes.

The file then creates an empty block called STACK with a size of 4 Kbytes in which the application stack will reside. To create a *block* is the basic method which you can use to get detailed control of placement, size, etc. It can be used for grouping sections, but also as in this example, to specify the size and placement of an area of memory.

Next, the file defines how to handle the initialization of variables, read/write type (readwrite) sections. In this example, the initializers are placed in ROM and copied at startup of the application to the RAM area. By default, ILINK may compress the initializers if this appears to be advantageous.

The last part of the configuration file handles the actual placement of all the sections into the available regions. First, the startup code—defined to reside in the read-only (readonly) section .cstartup—is placed at the start of the ROM region, that is at address 0x10000. Note that the part within {} is referred to as section selection and it selects the sections for which the directive should be applied to. Then the rest of the read-only sections are placed in the ROM region. Note that the section selection { readonly section .cstartup } takes precedence over the more generic section selection { readonly }.

Finally, the read/write (readwrite) sections and the STACK block are placed in the RAM region.

This illustration gives a schematic overview of how the application is placed in memory:

Figure 9: Application in memory

In addition to these standard directives, a configuration file can contain directives that define how to:

- Map a memory that can be addressed in multiple ways
- Handle conditional directives
- Create symbols with values that can be used in the application
- More in detail, select the sections a directive should be applied to
- More in detail, initialize code and data.

For more details and examples about customizing the linker configuration file, see the chapter *Linking your application*.

For more information about the linker configuration file, see the chapter *The linker configuration file*.

## Initialization at system startup

In Standard C, all static variables—variables that are allocated at a fixed memory address—must be initialized by the runtime system to a known value at application startup. This value is either an explicit value assigned to the variable, or if no value is

given, it is cleared to zero. In the compiler, there is one exception to this rule and that is variables declared \_\_no\_init which are not initialized at all.

The compiler generates a specific type of section for each type of variable initialization:

Categories of declared data	Source	Section type	Section name	Section content
Zero-initialized data	int i;	Read/write data, zero-init	.bss	None
Zero-initialized data	int i = 0;	Read/write data, zero-init	.bss	None
Initialized data (non-zero)	int i = 6;	Read/write data	.data	The initializer
Non-initialized data	no_init int i;	Read/write data, zero-init	.noinit	None
Constants	<pre>const int i = 6;</pre>	Read-only data	.rodata	The constant
Code	<pre>ramfunc void   myfunc() {}</pre>	Read/write code	.textrw	The code

Table 3: Sections holding initialized data

**Note:** Clustering of static variables might group zero-initialized variables together with initialized data in .data. The compiler can decide to place constants in the .text section to avoid loading the address of a constant from a constant table.

For information about all supported sections, see the chapter *Section reference*.

## THE INITIALIZATION PROCESS

Initialization of data is handled by ILINK and the system startup code in conjunction.

To configure the initialization of variables, you must consider these issues:

- Sections that should be zero-initialized are handled automatically by ILINK; they should only be placed in RAM
- Sections that should be initialized, except for zero-initialized sections, should be listed in an initialize directive

Normally during linking, a section that should be initialized is split in two sections, where the original initialized section will keep the name. The contents are placed in the new initializer section, which will keep the original name suffixed with \_init. The initializers should be placed in ROM and the initialized sections in RAM, by means of placement directives. The most common example is the .data section that the linker splits in .data and .data\_init.

- Sections that contains constants should not be initialized; they should only be placed in flash/ROM
- Sections holding \_\_no\_init declared variables should not be initialized and thus should be listed in a do not initialize directive. They should also be placed in RAM.

In the linker configuration file, it can look like this:

For more information about and examples of how to configure the initialization, see *Linking considerations*, page 77.

## C++ DYNAMIC INITIALIZATION

The compiler places subroutine pointers for performing C++ dynamic initialization into sections of the ELF section types SHT\_PREINIT\_ARRAY and SHT\_INIT\_ARRAY. By default, the linker will place these into a linker-created block, ensuring that all sections of the section type SHT\_PREINIT\_ARRAY are placed before those of the type SHT\_INIT\_ARRAY. If any such sections were included, code to call the routines will also be included.

The linker-created blocks are only generated if the linker configuration does not contain section selector patterns for the preinit\_array and init\_array section types. The effect of the linker-created blocks will be very similar to what happens if the linker configuration file contains this:

If you put this into your linker configuration file, you must also mention the CPP\_INIT block in one of the section placement directives. If you wish to select where the

linker-created block is placed, you can use a section selector with the name ".init\_array".

See also Section-selectors, page 395.

# Linking your application

This chapter lists aspects that you must consider when linking your application. This includes using ILINK options and tailoring the linker configuration file.

Finally, this chapter provides some hints for troubleshooting.

## Linking considerations

Before you can link your application, you must set up the configuration required by ILINK. Typically, you must consider:

- Defining your own memory areas
- Placing sections
- Keeping modules in the application
- Keeping symbols and sections in the application
- Application startup
- Setting up the stack and heap
- Setting up the atexit limit
- Changing the default initialization
- Symbols for controlling the application
- Standard library handling
- Other output formats than ELF/DWARF
- Veneers.

#### **CHOOSING A LINKER CONFIGURATION FILE**

The config directory contains two ready-made templates for the linker configuration file:

- generic.icf, designed for all cores except for Cortex-M cores
- generic\_cortex.icf, designed for all Cortex-M cores.

These files contain the information required by ILINK. The only change, if any, you will normally have to make to the supplied configuration file is to customize the start and end addresses of each region so they fit the target system memory map. If, for example, your application uses additional external RAM, you must also add details about the external RAM memory area.

To edit a linker configuration file, use the editor in the IDE, or any other suitable editor. Alternatively, choose **Project>Options>Linker** and click the **Edit** button on the **Config** page to open the dedicated linker configuration file editor.

Remember not to change the original template file. We recommend that you make a copy in the working directory, and modify the copy instead. If you are using the linker configuration file editor in the IDE, the IDE will make a copy for you.

Each project in the IDE should have a reference to one, and only one, linker configuration file. This file can be edited, but for the majority of all projects it is sufficient to configure the vital parameters in **Project>Options>Linker>Config.** 

#### **DEFINING YOUR OWN MEMORY AREAS**

The default configuration file that you selected has predefined ROM and RAM regions. This example will be used as a starting-point for all further examples in this chapter:

```
/* Define the addressable memory */
define memory Mem with size = 4G;

/* Define a region named ROM with start address 0 and to be 64
Kbytes large */
define region ROM = Mem:[from 0 size 0x10000];

/* Define a region named RAM with start address 0x20000 and to be
64 Kbytes large */
define region RAM = Mem:[from 0x20000 size 0x10000];
```

Each region definition must be tailored for the actual hardware.

To find out how much of each memory that was filled with code and data after linking, inspect the memory summary in the map file (command line option --map).

## Adding an additional region

To add an additional region, use the define region directive, for example:

```
/* Define a 2nd ROM region to start at address 0x80000 and to be
128 Kbytes large */
define region ROM2 = Mem:[from 0x80000 size 0x20000];
```

## Merging different areas into one region

If the region is comprised of several areas, use a region expression to merge the different areas into one region, for example:

```
/* Define the 2nd ROM region to have two areas. The first with the start address 0x80000 and 128 Kbytes large, and the 2nd with the start address 0xC0000 and 32 Kbytes large */
```

#### PLACING SECTIONS

The default configuration file that you selected places all predefined sections in memory, but there are situations when you might want to modify this. For example, if you want to place the section that holds constant symbols in the CONSTANT region instead of in the default place. In this case, use the place in directive, for example:

```
/* Place sections with readonly content in the ROM region */
place in ROM {readonly};
/* Place the constant symbols in the CONSTANT region */
place in CONSTANT {readonly section .rodata};
```

**Note:** Placing a section—used by the IAR build tools—in a different memory which use a different way of referring to its content, will fail.

For the result of each placement directive after linking, inspect the placement summary in the map file (the command line option --map).

## Placing a section at a specific address in memory

To place a section at a specific address in memory, use the place at directive, for example:

```
/* Place section .vectors at address 0 */
place at address Mem:[0] {readonly section .vectors};
```

## Placing a section first or last in a region

To place a section first or last in a region is similar, for example:

```
/* Place section .vectors at start of ROM */
place at start of ROM {readonly section .vectors};
```

## Declare and place your own sections

To declare new sections—in addition to the ones used by the IAR build tools—to hold specific parts of your code or data, use mechanisms in the compiler and assembler. For example:

```
/* Create a section for variables. */
#pragma section = "MYOWNSECTION"
/* Place a variable in that section. */
const short MyVariable @ "MYOWNSECTION" = 0xF0F0;
```

This is the corresponding example in assembler language:

```
name createSection
section MYOWNSECTION:CONST ; Create a section,
; and fill it with
dc16 0xF0F0 ; constant bytes.
end
```

To place your new section, the original place in ROM {readonly}; directive is sufficient.

However, to place the section MyOwnSection explicitly, update the linker configuration file with a place in directive, for example:

```
/* Place MyOwnSection in the ROM region */
place in ROM {readonly section MyOwnSection};
```

#### **RESERVING SPACE IN RAM**

Often, an application must have an empty uninitialized memory area to be used for temporary storage, for example a heap or a stack. It is easiest to achieve this at link time. You must create a block with a specified size and then place it in a memory.

In the linker configuration file, it can look like this:

```
define block TempStorage with size = 0x1000, alignment = 4 { };
place in RAM { block TempStorage };
```

To retrieve the start of the allocated memory from the application, the source code could look like this:

```
/* Declare a section for temporary storage. */
#pragma section = "TEMPSTORAGE"

char *GetTempStorageStartAddress()
{
    /* Return start address of section TEMPSTORAGE. */
    return __section_begin("TEMPSTORAGE");
}
```

## **KEEPING MODULES**

If a module is linked as an object file, it is always kept. That is, it will contribute to the linked application. However, if a module is part of a library, it is included only if it is symbolically referred to from other parts of the application. This is true, even if the library module contains a root symbol. To assure that such a library module is always included, use <code>iarchive</code> to extract the module from the library, see *The IAR Archive Tool—iarchive*, page 409.

For information about included and excluded modules, inspect the log file (the command line option --log modules).

For more information about modules, see *Modules and sections*, page 68.

### **KEEPING SYMBOLS AND SECTIONS**

By default, ILINK removes any sections, section fragments, and global symbols that are not needed by the application. To retain a symbol that does not appear to be needed—or actually, the section fragment it is defined in—you can either use the root attribute on the symbol in your C/C++ or assembler source code, or use the ILINK option --keep. To retain sections based on attribute names or object names, use the directive keep in the linker configuration file.

To prevent ILINK from excluding sections and section fragments, use the command line options --no\_remove or --no\_fragments, respectively.

For information about included and excluded symbols and sections, inspect the log file (the command line option --log sections).

For more information about the linking procedure for keeping symbols and sections, see *The linking process*, page 69.

## **APPLICATION STARTUP**

By default, the point where the application starts execution is defined by the \_\_iar\_program\_start label, which is defined to point at the start of the cstartup.s file. The label is also communicated via ELF to any debugger that is used.

To change the start point of the application to another label, use the ILINK option --entry; see --entry, page 259.

## **SETTING UP THE STACK**

The size of the CSTACK block is defined in the linker configuration file. To change the allocated amount of memory, change the block definition for CSTACK:

```
define block CSTACK with size = 0x2000, alignment = 8{ };
```

Specify an appropriate size for your application.

For more information about the stack, see *Stack considerations*, page 165.

#### **SETTING UP THE HEAP**

The size of the heap is defined in the linker configuration file as a block:

```
define block HEAP with size = 0x1000, alignment = 8{ };
place in RAM {block HEAP};
```

Specify the appropriate size for your application.

#### SETTING UP THE ATEXIT LIMIT

By default, the atexit function can be called a maximum of 32 times from your application. To either increase or decrease this number, add a line to your configuration file. For example, to reserve room for 10 calls instead, write:

```
define symbol __iar_maximum_atexit_calls = 10;
```

#### CHANGING THE DEFAULT INITIALIZATION

By default, memory initialization is performed during application startup. ILINK sets up the initialization process and chooses a suitable packing method. If the default initialization process does not suit your application and you want more precise control over the initialization process, these alternatives are available:

- Choosing the packing algorithm
- Manual initialization
- Initializing code—copying ROM to RAM.

For information about the performed initializations, inspect the log file (the command line option --log initialization).

## Choosing packing algorithm

To override the default packing algorithm, write for example:

```
initialize by copy with packing = lzw { readwrite };
```

For more information about the available packing algorithms, see *Initialize directive*, page 390.

## **Manual initialization**

The initialize manually directive lets you take complete control over initialization. For each involved section, ILINK creates an extra section that contains the initialization

data, but makes no arrangements for the actual copying. This directive is, for example, useful for overlays:

```
/* Sections MYOVERLAY1 and MYOVERLAY2 will be overlaid in
MyOverlay */
define overlay MyOverlay { section MYOVERLAY1 };
define overlay MyOverlay { section MYOVERLAY2 };
/* Split the overlay sections but without initialization during
system startup */
initialize manually { section MYOVERLAY* };
/* Place the initializer sections in a block each */
define block MyOverlay1InRom { section MYOVERLAY1 init };
define block MyOverlay2InRom { section MYOVERLAY2_init };
/* Place the overlay and the initializers for it */
place in RAM { overlay MyOverlay };
place in ROM { block MyOverlay1InRom, block MyOverlay2InRom };
The application can then start a specific overlay by copying, as in this case, ROM to
RAM:
#include <string.h>
/* Declare the overlay sections. */
#pragma section = "MYOVERLAY"
#pragma section = "MYOVERLAY1INROM"
/* Function that switches in image 1 into the overlay. */
void SwitchToOverlay1()
{
 char *targetAddr
                     = __section_begin("MYOVERLAY");
 char *sourceAddr = __section_begin("MYOVERLAY1INROM");
 char *sourceAddrEnd = __section_end("MYOVERLAY1INROM");
 int size = sourceAddrEnd - sourceAddr;
 memcpy(targetAddr, sourceAddr, size);
}
```

## Initializing code—copying ROM to RAM

Sometimes, an application copies pieces of code from flash/ROM to RAM. This can be easily achieved by ILINK for whole code regions. However, for individual functions, the \_\_ramfunc keyword can be used, see *Execution in RAM*, page 32.

List the code sections that should be initialized in an initialize directive and then place the initializer and initialized sections in ROM and RAM, respectively.

In the linker configuration file, it can look like this:

```
/* Split the .textrw section into a readonly and a readwrite
section */
initialize by copy { section .textrw };

/* Place both in a block */
define block RamCode { section .textrw };
define block RamCodeInit { section .textrw_init };

/* Place them in ROM and RAM */
place in ROM { block RamCodeInit };
place in RAM { block RamCode };
```

The block definitions makes it possible to refer to the start and end of the blocks from the application.

For more examples, see *Interaction between the tools and your application*, page 168.

## Running all code from RAM

If you want to copy the entire application from ROM to RAM at program startup, use the initilize by copy directive, for example:

```
initialize by copy { readonly, readwrite };
```

The readwrite pattern will match all statically initialized variables and arrange for them to be initialized at startup. The readonly pattern will do the same for all read-only code and data, except for code and data needed for the initialization.

To reduce the ROM space that is needed, it might be useful to compress the data with one of the available packing algorithms. For example,

```
initialize by copy with packing = lzw { readonly, readwrite };
```

For more information about the available compression algorithms, see *Initialize directive*, page 390.

Because the function \_\_low\_level\_init, if present, is called before initialization, it, and anything it needs, will not be copied from ROM to RAM either. In some circumstances—for example, if the ROM contents are no longer available to the

program after startup—you might need to avoid using the same functions during startup and in the rest of the code.

If anything else should not be copied, include it in an except clause. This can apply to, for example, the interrupt vector table.

It is also recommended to exclude the C++ dynamic initialization table from being copied to RAM, as it is typically only read once and then never referenced again. For example, like this:

## INTERACTION BETWEEN ILINK AND THE APPLICATION

ILINK provides the command line options --config\_def and --define\_symbol to define symbols which can be used for controlling the application. You can also use symbols to represent the start and end of a continuous memory area that is defined in the linker configuration file. For more information, see *Interaction between the tools and your application*, page 168.

To change a reference to one symbol to another symbol, use the ILINK command line option --redirect. This is useful, for example, to redirect a reference from a non-implemented function to a stub function, or to choose one of several different implementations of a certain function, for example, how to choose the DLIB formatter for the standard library functions printf and scanf.

The compiler generates mangled names to represent complex C/C++ symbols. If you want to refer to these symbols from assembler source code, you must use the mangled names.

For information about the addresses and sizes of all global (statically linked) symbols, inspect the entry list in the map file (the command line option --map).

For more information, see *Interaction between the tools and your application*, page 168.

## STANDARD LIBRARY HANDLING

By default, ILINK determines automatically which variant of the standard library to include during linking. The decision is based on the sum of the runtime attributes available in each object file and the library options passed to ILINK.

To disable the automatic inclusion of the library, use the option --no\_library\_search. In this case, you must explicitly specify every library file to

be included. For information about available library files, see *Using prebuilt libraries*, page 91.

#### PRODUCING OTHER OUTPUT FORMATS THAN ELF/DWARF

ILINK can only produce an output file in the ELF/DWARF format. To convert that format into a format suitable for programming PROM/flash, see *The IAR ELF Tool—ielftool*, page 412.

#### **VENEERS**

The ARM cores need to use veneers on two occasions:

- When calling an ARM function from Thumb mode or vice versa; the veneer then
  changes the state of the microprocessor. If the core supports the BLX instruction, a
  veneer is not needed for changing modes.
- When calling a function that it cannot normally reach; the veneer introduces code which makes the call successfully reach the destination.

Code for veneers can be inserted between any caller and called function. As a result, the R12 register must be treated as a scratch register at function calls, including functions written in assembler. This also applies to jumps.

For more information, see --no\_veneers, page 268.

## Hints for troubleshooting

ILINK has several features that can help you manage code and data placement correctly, for example:

- Messages at link time, for examples when a relocation error occurs
- The --log option that makes ILINK log information to stdout, which can be useful to understand why an executable image became the way it is, see --log, page 263
- The --map option that makes ILINK produce a memory map file, which contains the result of the linker configuration file, see --map, page 265.

### **RELOCATION ERRORS**

For each instruction that cannot be relocated correctly, ILINK will generate a *relocation error*. This can occur for instructions where the target is out of reach or is of an incompatible type, or for many other reasons.

A relocation error produced by ILINK can look like this:

Error[Lp002]: relocation failed: out of range or illegal value

The message entries are described in this table:

Message entry	Description		
Kind	The relocation directive that failed. The directive depends on the instruction used.		
Location	The location where the problem occurred, described with the following details:		
	<ul> <li>The instruction address, expressed both as a hexadecimal value and as a label with an offset. In this example, 0x40000448 and "myfunc" + 0x2c.</li> </ul>		
	_		
	The module, and the file. In this example, the     module somecode. o.		
	The section number and section name. In this example, section		
	number		
	7 with the name .text.		
	• The offset, specified in number of bytes, in the section. In this		
	example,		
	0x2c.		
Destination	The target of the instruction, described with the following details:		
	<ul> <li>The instruction address, expressed both as a hexadecimal value and as a label with an offset. In this example, 0x9000000c and "read" (thus, no offset).</li> </ul>		
	• The module, and when applicable the library. In this example, the		
	module read.o and the library iolib.a.		
	• The section number and section name. In this example, section		
	number		
	6 with the name . text.		
	The offset, specified in number of bytes, in the section. In this		
	example,		
	0x0.		

Table 4: Description of a relocation error

## **Possible solutions**

In this case, the distance from the instruction in myfunc to \_\_read is too long for the branch instruction.

Possible solutions include ensuring that the two .text sections are allocated closer to each other or using some other calling mechanism that can reach the required distance. It is also possible that the referring function tried to refer to the wrong target and that this caused the range error.

Different range errors have different solutions. Usually, the solution is a variant of the ones presented above, in other words modifying either the code or the section placement.

# The DLIB runtime environment

This chapter describes the runtime environment in which an application executes. In particular, the chapter covers the DLIB runtime library and how you can optimize it for your application.

## Introduction to the runtime environment

The runtime environment is the environment in which your application executes. The runtime environment depends on the target hardware, the software environment, and the application code.

#### **RUNTIME ENVIRONMENT FUNCTIONALITY**

The *runtime environment* supports Standard C and C++, including the standard template library. The runtime environment consists of the *runtime library*, which contains the functions defined by the C and the C++ standards, and include files that define the library interface (the system header files).

The runtime library is delivered both as prebuilt libraries and (depending on your product package) as source files, and you can find them in the product subdirectories arm\lib and arm\src\lib, respectively.

The runtime environment also consists of a part with specific support for the target system, which includes:

- Support for hardware features:
  - Direct access to low-level processor operations by means of *intrinsic* functions, such as functions for interrupt mask handling
  - Peripheral unit registers and interrupt definitions in include files
  - The Vector Floating Point (VFP) coprocessor.
- Runtime environment support, that is, startup and exit code and low-level interface to some library functions.
- A floating-point environment (fenv) that contains floating-point arithmetics support, see fenv.h, page 377.
- Special compiler support, for instance functions for switch handling or integer arithmetics.

For information about AEABI compliance, see AEABI compliance, page 174.

For more information about the library, see the chapter Library functions.

#### SETTING UP THE RUNTIME ENVIRONMENT

The IAR DLIB runtime environment can be used as is together with the debugger. However, to run the application on hardware, you must adapt the runtime environment. Also, to configure the most code-efficient runtime environment, you must determine your application and hardware requirements. The more functionality you need, the larger your code will become.

This is an overview of the steps involved in configuring the most efficient runtime environment for your target hardware:

- Choose which runtime library object file to use
   It is not necessary to specify a library file explicitly, as ILINK automatically uses the correct library file. See *Using prebuilt libraries*, page 91.
- Choose which predefined runtime library configuration to use—Normal or Full You can configure the level of support for certain library functionality, for example, locale, file descriptors, and multibyte characters. If you do not specify anything, a default library configuration file that matches the library object file is automatically used. To specify a library configuration explicitly, use the --dlib\_config compiler option. See *Library configurations*, page 107.
- Optimize the size of the runtime library
  - You can specify the formatters used by the functions printf, scanf, and their variants, see *Choosing formatters for printf and scanf*, page 94. You can also specify the size and placement of the stacks and the heap, see *Setting up the stack*, page 81, and *Setting up the heap*, page 82, respectively.
- Include debug support for runtime and I/O debugging
   The library offers support for mechanisms like redirecting standard input and output to the C-SPY Terminal I/O window and accessing files on the host computer, see Application debug support, page 97.
- Adapt the library for target hardware
  - The library uses a set of low-level functions for handling accesses to your target system. To make these accesses work, you must implement your own version of these functions. For example, to make printf write to an LCD display on your board, you must implement a target-adapted version of the low-level function \_\_write, so that it can write characters to the display. To customize such functions, you need a good understanding of the library low-level interface, see *Adapting the library for target hardware*, page 100.

• Override library modules

If you have customized the library functionality, you need to make sure your versions of the library modules are used instead of the default modules. This can be done without rebuilding the entire library, see *Overriding library modules*, page 101.

• Customize system initialization

It is likely that you need to customize the source code for system initialization, for example, your application might need to initialize memory-mapped special function registers, or omit the default initialization of data segments. You do this by customizing the routine <code>\_\_low\_level\_init</code>, which is executed before the data segments are initialized. See *System startup and termination*, page 103 and *Customizing system initialization*, page 106.

• Configure your own library configuration files

In addition to the prebuilt library configurations, you can make your own library configuration, but that requires that you *rebuild* the library. This gives you full control of the runtime environment. See *Building and using a customized library*, page 101.

Manage a multithreaded environment

In a multithreaded environment, you must adapt the runtime library to treat all library objects according to whether they are global or local to a thread. See *Managing a multithreaded environment*, page 117.

• Check module consistency

You can use runtime model attributes to ensure that modules are built using compatible settings, see *Checking module consistency*, page 122.

## Using prebuilt libraries

The prebuilt runtime libraries are configured for different combinations of these features:

- Architecture
- CPU mode
- Byte order
- Library configuration—Normal or Full
- Floating-point implementation.

The linker will automatically include the correct library object file and library configuration file. To explicitly specify a library configuration, use the --dlib\_config option. For more information, see *Runtime environment*, page 50.

## **>\_**

## LIBRARY FILENAME SYNTAX

The names of the libraries are constructed by these constituents:

{architecture} is the name of the architecture. It can be one of 4t, 5E, 6M,

or 7M for the ARM architectures v4T, v5TE, v6M, or v7M, respectively. Libraries built for the v5TE architecture are also used for the v6 architecture and later (except for v6M

and v7M).

{cpu\_mode} is one of t or a, for Thumb and ARM, respectively.

{byte\_order} is one of 1 or b, for little-endian and big-endian,

respectively.

{ fp\_implementation} when the library is compiled without VFP support, that is,

using a software implementation floating-point

functions.

v when the library is compiled with VFP support for architectures VFPv2 or later. Libraries compiled with VFP support have two entries for each function with floating-point signature. One entry is compliant with the VFP variant of AAPCS, the other is compliant with the AAPCS base standard. The linker will use the VFP variant entry for modules compiled with the VFP

other modules.

{language} is c when the library is compiled for Standard C++

support, and e when compiled for Embedded C++ support.

calling convention, and the base standard entry for

{lib\_config} is one of n or f for normal and full, respectively.

{debug\_interface} is one of s, b or i, for the SWI/SVC mechanism, the

BKPT mechanism, and the IAR-specific breakpoint mechanism, respectively. For more information, see

--semihosting, page 272.

{ rwp} is s when the library contains read/write

position-independent code, see --rwpi, page 245.

**Note:** There are two library configuration files: DLib\_Config\_Normal.h and DLib\_Config\_Full.h.

You can find the library object files and the library configuration files in the subdirectory arm\lib.

## **GROUPS OF LIBRARY FILES**

The libraries are delivered in groups of library functions.

## Library files for C library functions

These are the functions defined by Standard C, for example functions like printf and scanf. Note that this library does not include math functions.

The names of the library files are constructed in the following way:

```
dl<architecture>_<cpu_mode><byte_order><lib_config><rwpi>.a
```

which more specifically means

```
d1<4t|5E|6M|7M>_<a|t><1|b><n|f><s.a
```

## Library files for C++ and Embedded C++ library functions

These are the functions defined by C++, compiled with support for either Standard C++ or Embedded C++.

The names of the library files are constructed in the following way:

```
dlpp<architecture>_<cpu_mode><byte_order><fp_implementation>
<lib_config><language>.a
```

which more specifically means

```
dlpp<4t|5E|6M|7M>_<a|t><1|b><_|v><n|f><c|e>.a
```

## Library files for math functions

These are the functions for floating-point arithmetic and functions with a floating-point type in its signature as defined by Standard C, for example functions like sqrt.

The names of the library files are constructed in the following way:

```
{\tt m<} architecture {\tt ><} cpu\_{\tt mode} {\tt ><} by {\tt te\_} order {\tt ><} fp\_{\tt implementation} {\tt >.} a which more specifically means
```

```
m<4t|5E|6M|7M>_<a|t><1|b><|v>.a
```

## Library files for runtime support functions

These are functions for system startup, initialization, non floating-point AEABI support routines, and some of the functions part of Standard C and C++.

The names of the library files are constructed in the following way:

```
rt<architecture>_<cpu_mode><byte_order>.a
```

which more specifically means

 $rt<4t|5E|6M|7M>_<a|t><1|b>.a$ 

## Library files for debug support functions

These are functions for debug support for the semihosting interface. The names of the library files are constructed in the following way:

sh<debug\_interface>\_<byte\_order>.a

which more specifically means

 $sh < s | b | i > _< l | b > .a$ 

## **CUSTOMIZING A PREBUILT LIBRARY WITHOUT REBUILDING**

The prebuilt libraries delivered with the compiler can be used as is. However, you can customize parts of a library without rebuilding it.

These items can be customized:

Items that can be customized	Described in
Formatters for printf and scanf	Choosing formatters for printf and scanf, page 94
Startup and termination code	System startup and termination, page 103
Low-level input and output	Standard streams for input and output, page 108
File input and output	File input and output, page 112
Low-level environment functions	Environment interaction, page 115
Low-level signal functions	Signal and raise, page 116
Low-level time functions	Time, page 116
Size of heaps, stacks, and sections	Stack considerations, page 165 Heap considerations, page 167 Placing code and data—the linker configuration file, page 71

Table 5: Customizable items

For information about how to override library modules, see *Overriding library modules*, page 101.

## Choosing formatters for printf and scanf

The linker automatically chooses an appropriate formatter for printf- and scanf-related function based on information from the compiler. If that information is missing or insufficient, for example if printf is used through a function pointer, if the

object file is old, etc, then the automatic choice is the Full formatter. In this case you might want to choose a formatter manually.

To override the default formatter for all the printf- and scanf-related functions, except for wprintf and wscanf variants, you simply set the appropriate library options. This section describes the different options available.

**Note:** If you rebuild the library, you can optimize these functions even further, see *Configuration symbols for printf and scanf*, page 110.

## **CHOOSING A PRINTF FORMATTER**

The printf function uses a formatter called \_Printf. The full version is quite large, and provides facilities not required in many embedded applications. To reduce the memory consumption, three smaller, alternative versions are also provided in the Standard C/EC++ library.

This table summarizes the capabilities of the different formatters:

Formatting capabilities	Tiny	Small/ SmallNoMb	Large/ LargeNoMb	Full/ FullNoMb
Basic specifiers c, d, i, o, p, s, u, X, x, and %	Yes	Yes	Yes	Yes
Multibyte support	No	Yes/No	Yes/No	Yes/No
Floating-point specifiers a, and A	No	No	No	Yes
Floating-point specifiers e, E, f, F, g, and ${\tt G}$	No	No	Yes	Yes
Conversion specifier n	No	No	Yes	Yes
Format flag +, -, #, 0, and space	No	Yes	Yes	Yes
Length modifiers h, 1, L, s, t, and ${\tt Z}$	No	Yes	Yes	Yes
Field width and precision, including *	No	Yes	Yes	Yes
long long support	No	No	Yes	Yes

Table 6: Formatters for printf

For information about how to fine-tune the formatting capabilities even further, see *Configuration symbols for printf and scanf*, page 110.



## Specifying the print formatter in the IDE

To explicitly specify a formatter, choose **Project>Options** and select the **General Options** category. Select the appropriate option on the **Library options** page.



## Specifying the printf formatter from the command line

To explicitly specify a formatter, use one of these ILINK command line options:

```
--redirect _Printf=_PrintfFull
--redirect _Printf=_PrintfFullNoMb
--redirect _Printf=_PrintfLarge
--redirect _Printf=_PrintfLargeNoMb
--redirect _Printf=_PrintfSmall
--redirect _Printf=_PrintfSmallNoMb
--redirect _Printf=_PrintfTiny
--redirect _Printf=_PrintfTinyNoMb
```

## **CHOOSING A SCANF FORMATTER**

In a similar way to the printf function, scanf uses a common formatter, called \_Scanf. The full version is quite large, and provides facilities that are not required in many embedded applications. To reduce the memory consumption, two smaller, alternative versions are also provided in the Standard C/C++ library.

This table summarizes the capabilities of the different formatters:

Formatting capabilities	Small/ SmallNoMB	Large/ LargeNoMb	Full/ FullNoMb
Basic specifiers c, d, i, o, p, s, u, X, x, and %	Yes	Yes	Yes
Multibyte support	Yes/No	Yes/No	Yes/No
Floating-point specifiers $a,$ and ${\mathbb A}$	No	No	Yes
Floating-point specifiers e, E, f, F, g, and G	No	No	Yes
Conversion specifier n	No	No	Yes
Scan set [ and ]	No	Yes	Yes
Assignment suppressing *	No	Yes	Yes
long long support	No	No	Yes

Table 7: Formatters for scanf

For information about how to fine-tune the formatting capabilities even further, see *Configuration symbols for printf and scanf*, page 110.



## Specifying the scanf formatter in the IDE

To explicitly specify a formatter, choose **Project>Options** and select the **General Options** category. Select the appropriate option on the **Library options** page.



## Specifying the scanf formatter from the command line

To explicitly specify a formatter, use one of these ILINK command line options:

```
--redirect _Scanf=_ScanfFull
--redirect _Scanf=_ScanfFullNoMb
--redirect _Scanf=_ScanfLarge
--redirect _Scanf=_ScanfLargeNoMb
--redirect _Scanf=_ScanfSmall
--redirect _Scanf=_ScanfSmallNoMb
```

## **Application debug support**

In addition to the tools that generate debug information, there is a debug version of the library low-level interface (typically, I/O handling and basic runtime support). Using the debug library, your application can perform things like opening a file on the host computer and redirecting stdout to the debugger Terminal I/O window.

## **INCLUDING C-SPY DEBUG SUPPORT**

You can make the library provide debug support for:

- Handling program abort, exit, and assertions
- I/O handling, which means that stdin and stdout are redirected to the C-SPY
  Terminal I/O window, and that it is possible to access files on the host computer
  during debugging.

If you build your application project with the ILINK option **Semihosted** (--semihosting) or **IAR breakpoint** (--semihosting=iar\_breakpoint), certain functions in the library are replaced by functions that communicate with the debugger.



To set linker options for debug support in the IDE, choose **Project>Options** and select the **General Options** category. On the **Library configuration** page, select the **Semihosted** option or the **IAR breakpoint** option.

Note that for some Cortex-M devices it is also possible to direct stdout/stderr via SWO. This can significantly improve stdout/stderr performance compared to semihosting. For hardware requirement, see the *C-SPY® Debugging Guide for ARM®*.



To enable stdout via SWO on the command line, use the linker option --redirect \_\_iar\_sh\_stdout=\_\_iar\_sh\_stdout\_swo.



To enable stdout via SWO in the IDE, choose **Project>Options>General Options**. On the **Library configuration** page, select the **Semihosted** option and the **stdout/stderr via SWO** option.

## THE DEBUG LIBRARY FUNCTIONALITY

The debug library is used for communication between the application being debugged and the debugger itself. The debugger provides runtime services to the application via the low-level DLIB interface; services that allow capabilities like file and terminal I/O to be performed on the host computer.

These capabilities can be valuable during the early development of an application, for example in an application that uses file I/O before any flash file system I/O drivers are implemented. Or, if you need to debug constructions in your application that use stdin and stdout without the actual hardware device for input and output being available. Another use is producing debug printouts.

The low-level debugger runtime interface provided by DLIB is compatible with the semihosting interface provided by ARM Limited. When an application invokes a semihosting call, the execution stops at a debugger breakpoint. The debugger then handles the call, performs any necessary actions on the host computer and then resumes the execution.

## The semihosting mechanism

There are three variants of semihosting mechanisms available:

- For Cortex-M, the interface uses BKPT instructions to perform semihosting calls
- For other ARM cores, SVC instructions are used for the semihosting calls
- IAR breakpoint, which is an IAR-specific alternative to semihosting that uses SVC.

To support semihosting via SVC, the debugger must set its semihosting breakpoint on the Supervisor Call vector to catch SVC calls. If your application uses SVC calls for other purposes than semihosting, the handling of this breakpoint will cause a severe performance penalty for each such call. IAR breakpoint is a way to get around this. By using a special function call instead of an SVC instruction to perform semihosting, the semihosting breakpoint can be set on that special function instead. This means that semihosting will not interfere with other uses of the Supervisor Call vector.

Note that IAR breakpoint is an IAR-specific extension of the semihosting standard. If you link your application with libraries built with toolchains from other vendors than IAR Systems and use IAR breakpoint, semihosting calls made from code in those libraries will not work.

## THE C-SPY TERMINAL I/O WINDOW

To make the Terminal I/O window available, the application must be linked with support for I/O debugging. This means that when the functions \_\_read or \_\_write are called to perform I/O operations on the streams stdin, stdout, or stderr, data will be sent to or read from the C-SPY Terminal I/O window.

**Note:** The Terminal I/O window is not opened automatically just because \_\_read or \_\_write is called; you must open it manually.

For more information about the Terminal I/O window, see the *C-SPY*® *Debugging Guide for ARM*®.

## Speeding up terminal output

On some systems, terminal output might be slow because the host computer and the target hardware must communicate for each character.

For this reason, a replacement for the \_\_write function called \_\_write\_buffered is included in the DLIB library. This module buffers the output and sends it to the debugger one line at a time, speeding up the output. Note that this function uses about 80 bytes of RAM memory.

To use this feature you can either choose **Project>Options>General Options>Library Options** and select the option **Buffered terminal output** in the IDE, or add this to the linker command line:

```
--redirect __write=__write_buffered
```

#### LOW-LEVEL FUNCTIONS IN THE DEBUG LIBRARY

The debug library contains implementations of the following low-level functions:

Function in DLIB low-level interface	Action
abort	Exits the application
clock	Returns the clock on the host computer
close	Closes the associated host file on the host computer
exit	Notifies that the end of the application was reached
open	Opens a file on the host computer
read	Directs ${\tt stdin}$ to the Terminal I/O window; all other files will read the associated host file
remove	Removes a file on the host computer
rename	Renames a file on the host computer
iar_ReportAsser	Prints an assert message to terminal I/O
t	
lseek	Searches in the associated host file on the host computer
write	Directs stdout and stderr to the Terminal I/O window, all other files will write to the associated host file

Table 8: Functions with special meanings when linked with debug library

**Note:** You should not use these low-level functions in your application. Instead you should use the high-level functions that use these functions to perform their actions. For more information, see *Library low-level interface*, page 100.

## Adapting the library for target hardware

The library uses a set of low-level functions for handling accesses to your target system. To make these accesses work, you must implement your own version of these functions. These low-level functions are referred to as the *library low-level interface*.

When you have implemented your low-level interface, you must add your version of these functions to your project. For information about this, see *Overriding library modules*, page 101.

## LIBRARY LOW-LEVEL INTERFACE

The library uses a set of low-level functions to communicate with the target system. For example, printf and all other standard output functions use the low-level function \_\_write to send the actual characters to an output device. Most of the low-level functions, like \_\_write, have no implementation. Instead, you must implement them yourself to match your hardware.

However, the library contains a debug version of the library low-level interface, where the low-level functions are implemented so that they interact with the host computer via the debugger, instead of with the target hardware. If you use the debug library, your application can perform tasks like writing to the Terminal I/O window, accessing files on the host computer, getting the time from the host computer, etc. For more information, see *The debug library functionality*, page 98.

Note that your application should not use the low-level functions directly. Instead you should use the corresponding standard library function. For example, to write to stdout, you should use standard library functions like printf or puts, instead of \_\_write.

The library files that you can override with your own versions are located in the arm\src\lib directory.

The low-level interface is further described in these sections:

- Standard streams for input and output, page 108
- File input and output, page 112
- Signal and raise, page 116
- Time, page 116
- Assert, page 117.

## **Overriding library modules**

To use the library low-level interface that you have implemented, add it to your application. See *Adapting the library for target hardware*, page 100. Or, you might want to override a default library routine with your customized version. In both cases, follow this procedure:

- Use a template source file—a library source file or another template—and copy it to your project directory.
- 2 Modify the file.
- **3** Add the customized file to your project, like any other source file.

**Note:** If you have implemented a library low-level interface and added it to a project that you have built with debug support, your low-level functions will be used and not the C-SPY debug support modules. For example, if you replace the debug support module \_\_write with your own version, the C-SPY Terminal I/O window will not be supported.

## Building and using a customized library

Building a customized library is a complex process. Therefore, consider carefully whether it is really necessary. You must build your own C/C++ standard library when you want to define your own library configuration with support for locale, file descriptors, multibyte characters, et cetera.

In those cases, you must:

- Set up a library project
- Make the required library modifications
- Build your customized library
- Finally, make sure your application project will use the customized library.

**Note:** To build IAR Embedded Workbench projects from the command line, use the IAR Command Line Build Utility (iarbuild.exe). However, no make or batch files for building the library from the command line are provided.

For information about the build process and the IAR Command Line Build Utility, see the *IDE Project Management and Building Guide for ARM*®.

## **SETTING UP A LIBRARY PROJECT**

The IDE provides a library project template which can be used for customizing the runtime environment configuration. This library template uses the Full library configuration, see Table 9, *Library configurations*, page 107.



In the IDE, modify the generic options in the created library project to suit your application, see *Basic project configuration*, page 48.

**Note:** There is one important restriction on setting options. If you set an option on file level (file level override), no options on higher levels that operate on files will affect that file.

## MODIFYING THE LIBRARY FUNCTIONALITY

You must modify the library configuration file and build your own library if you want to modify support for, for example, locale, file descriptors, and multibyte characters. This will include or exclude certain parts of the runtime environment.

The library functionality is determined by a set of *configuration symbols*. The default values of these symbols are defined in the file <code>DLib\_Defaults.h</code>. This read-only file describes the configuration possibilities. In addition, your library has its own library configuration file, which sets up that specific library with the required library configuration. For more information, see Table 5, *Customizable items*, page 94.

The library configuration file is used for tailoring a build of the runtime library, and for tailoring the system header files.

## Modifying the library configuration file

In your library project, open the library configuration file and customize it by setting the values of the configuration symbols according to the application requirements.

When you are finished, build your library project with the appropriate project options.

#### **USING A CUSTOMIZED LIBRARY**

After you build your library, you must make sure to use it in your application project.



In the IDE you must do these steps:

Choose **Project>Options** and click the **Library Configuration** tab in the **General Options** category.

- **2** Choose **Custom DLIB** from the **Library** drop-down menu.
- **3** In the **Configuration file** text box, locate your library configuration file.
- 4 Click the Library tab, also in the Linker category. Use the Additional libraries text box to locate your library file.

## System startup and termination

This section describes the runtime environment actions performed during startup and termination of your application.

The code for handling startup and termination is located in the source files cstartup.s, cmain.s, cexit.s, and low\_level\_init.c or low\_level\_init.s located in the arm\src\lib directory.

For Cortex-M, one of the following files is used instead of cstartup.s:

thumb\cstartup\_M.s or thumb\cstartup\_M.c

For information about how to customize the system startup code, see *Customizing* system initialization, page 106.

## **SYSTEM STARTUP**

During system startup, an initialization sequence is executed before the main function is entered. This sequence performs initializations required for the target hardware and the C/C++ environment.

For the hardware initialization, it looks like this:

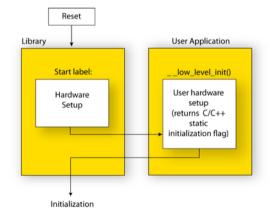


Figure 10: Target hardware initialization phase

- When the CPU is reset it will jump to the program entry label \_\_iar\_program\_start in the system startup code.
- Exception stack pointers are initialized to the end of each corresponding section
- The stack pointer is initialized to the end of the CSTACK block
- The function \_\_low\_level\_init is called if you defined it, giving the application
  a chance to perform early initializations.

**Note:** For Cortex-M devices, the second bullet in the above list is not valid. The first and the third bullets are handled slightly differently. At reset, a Cortex-M CPU initializes PC and SP from the vector table (\_\_vector\_table), which is defined in the cstartup\_M.c file.

For the C/C++ initialization, it looks like this:

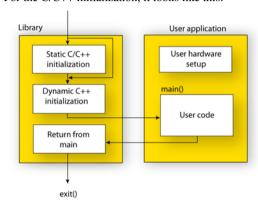


Figure 11: C/C++ initialization phase

- Static and global variables are initialized. That is, zero-initialized variables are cleared and the values of other initialized variables are copied from ROM to RAM memory. This step is skipped if \_\_low\_level\_init returns zero. For more information, see *Initialization at system startup*, page 73
- Static C++ objects are constructed
- The main function is called, which starts the application.

For information about the initialization phase, see *Application execution—an overview*, page 42.

## SYSTEM TERMINATION

This illustration shows the different ways an embedded application can terminate in a controlled way:

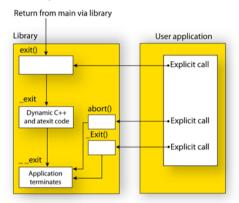


Figure 12: System termination phase

An application can terminate normally in two different ways:

- Return from the main function
- Call the exit function.

Because the C standard states that the two methods should be equivalent, the system startup code calls the exit function if main returns. The parameter passed to the exit function is the return value of main.

The default exit function is written in C. It calls a small assembler function \_exit that will perform these operations:

- Call functions registered to be executed when the application ends. This includes C++ destructors for static and global variables, and functions registered with the standard function atexit
- Close all open files
- Call \_\_exit
- When \_\_exit is reached, stop the system.

An application can also exit by calling the abort or the \_Exit function. The abort function just calls \_\_exit to halt the system, and does not perform any type of cleanup. The \_Exit function is equivalent to the abort function, except for the fact that \_Exit takes an argument for passing exit status information.

If you want your application to do anything extra at exit, for example resetting the system, you can write your own implementation of the \_\_exit(int) function.

## C-SPY interface to system termination

If your project is linked with the semihosted interface, the normal \_\_exit function is replaced with a special one. C-SPY will then recognize when this function is called and can take appropriate actions to simulate program termination. For more information, see *Application debug support*, page 97.

## **Customizing system initialization**

It is likely that you need to customize the code for system initialization. For example, your application might need to initialize memory-mapped special function registers (SFRs), or omit the default initialization of data sections performed by cstartup.

You can do this by providing a customized version of the routine <code>\_\_low\_level\_init</code>, which is called from <code>cmain.s</code> before the data sections are initialized. Modifying the file <code>cstartup.s</code> directly should be avoided.

The code for handling system startup is located in the source files cstartup.s and low\_level\_init.c, located in the arm\src\lib directory.

Note: Normally, you do not need to customize either of the files cmain.s or cexit.s.



If you intend to rebuild the library, the source files are available in the template library project, see *Building and using a customized library*, page 101.

**Note:** Regardless of whether you modify the routine \_\_low\_level\_init or the file cstartup.s, you do not have to rebuild the library.

#### LOW LEVEL INIT

Two skeleton low-level initialization files are supplied with the product: a C source file, low\_level\_init.c and an alternative assembler source file, low\_level\_init.s. The latter is part of the prebuilt runtime environment. The only limitation using the C source version is that static initialized variables cannot be used within the file, as variable initialization has not been performed at this point.

The value returned by \_\_low\_level\_init determines whether or not data sections should be initialized by the system startup code. If the function returns 0, the data sections will not be initialized.

## MODIFYING THE FILE CSTARTUP.S

As noted earlier, you should not modify the file cstartup.s if a customized version of \_\_low\_level\_init is enough for your needs. However, if you do need to modify the file cstartup.s, we recommend that you follow the general procedure for creating a modified copy of the file and adding it to your project, see *Overriding library modules*, page 101.

Note that you must make sure that the linker uses the start label used in your version of cstartup.s. For information about how to change the start label used by the linker, see --entry, page 259.

For Cortex-M, you must create a modified copy of cstartup\_M.s or cstartup\_M.c to use interrupts or other exception handlers.

## Library configurations

It is possible to configure the level of support for, for example, locale, file descriptors, multibyte characters.

The runtime library configuration is defined in the *library configuration file*. It contains information about what functionality is part of the runtime environment. The configuration file is used for tailoring a build of a runtime library, and tailoring the system header files used when compiling your application. The less functionality you need in the runtime environment, the smaller it becomes.

The library functionality is determined by a set of *configuration symbols*. The default values of these symbols are defined in the file <code>DLib\_Defaults.h</code>. This read-only file describes the configuration possibilities.

These predefined library configurations are available:

Library configuration	Description	
Normal DLIB (default)	No locale interface, C locale, no file descriptor support, and no	
	multibyte characters in printf and scanf.	
Full DLIB	Full locale interface, C locale, file descriptor support, and multibyte characters in printf and scanf.	

Table 9: Library configurations

## **CHOOSING A RUNTIME CONFIGURATION**

To choose a runtime configuration, use one of these methods:

- Default prebuilt configuration—if you do not specify a library configuration
  explicitly you will get the default configuration. A configuration file that matches
  the runtime library object file will automatically be used.
- Prebuilt configuration of your choice—to specify a runtime configuration explicitly, use the --dlib\_config compiler option. See --dlib\_config, page 224.
- Your own configuration—you can define your own configurations, which means
  that you must modify the configuration file. Note that the library configuration file
  describes how a library was built and thus cannot be changed unless you rebuild the
  library. For more information, see *Building and using a customized library*, page
  101

The prebuilt libraries are based on the default configurations, see Table 9, *Library configurations*.

## Standard streams for input and output

Standard communication channels (streams) are defined in stdio.h. If any of these streams are used by your application, for example by the functions printf and scanf, you must customize the low-level functionality to suit your hardware.

There are low-level I/O functions, which are the fundamental functions through which C and C++ performs all character-based I/O. For any character-based I/O to be available, you must provide definitions for these functions using whatever facilities the hardware environment provides. For more information about implementing low-level functions, see *Adapting the library for target hardware*, page 100.

## IMPLEMENTING LOW-LEVEL CHARACTER INPUT AND OUTPUT

To implement low-level functionality of the stdin and stdout streams, you must write the functions \_\_read and \_\_write, respectively. You can find template source code for these functions in the arm\src\lib directory.

If you intend to rebuild the library, the source files are available in the template library project, see *Building and using a customized library*, page 101. Note that customizing the low-level routines for input and output does not require you to rebuild the library.

**Note:** If you write your own variants of \_\_read or \_\_write, special considerations for the C-SPY runtime interface are needed, see *Application debug support*, page 97.

#### Example of using \_\_write

The code in this example uses memory-mapped I/O to write to an LCD display, whose port is assumed to be located at address 0x1000:

```
#include <stddef.h>
__no_init volatile unsigned char lcdIO @ 0x1000;
size_t __write(int handle,
               const unsigned char *buf,
               size_t bufSize)
 size_t nChars = 0;
 /* Check for the command to flush all handles */
 if (handle == -1)
   return 0;
  /* Check for stdout and stderr
     (only necessary if FILE descriptors are enabled.) */
 if (handle != 1 && handle != 2)
   return -1;
 for (/* Empty */; bufSize > 0; --bufSize)
   lcdI0 = *buf;
   ++buf;
    ++nChars;
 return nChars;
```

**Note:** When DLIB calls \_\_write, DLIB assumes the following interface: a call to \_\_write where buf has the value NULL is a command to flush the stream. When the handle is -1, all streams should be flushed.

#### Example of using \_\_read

The code in this example uses memory-mapped I/O to read from a keyboard, whose port is assumed to be located at 0x1000:

```
#include <stddef.h>
__no_init volatile unsigned char kbIO @ 0x1000;
size_t __read(int handle,
              unsigned char *buf,
              size_t bufSize)
 size_t nChars = 0;
  /* Check for stdin
     (only necessary if FILE descriptors are enabled) */
 if (handle != 0)
   return -1;
  for (/*Empty*/; bufSize > 0; --bufSize)
   unsigned char c = kbIO;
   if (c == 0)
     break;
    *buf++ = c;
    ++nChars;
 return nChars;
```

For information about the @ operator, see *Controlling data and function placement in memory*, page 182.

## Configuration symbols for printf and scanf

When you set up your application project, you typically need to consider what printf and scanf formatting capabilities your application requires, see *Choosing formatters* for printf and scanf, page 94.

If the provided formatters do not meet your requirements, you can customize the full formatters. However, that means you must rebuild the runtime library.

The default behavior of the printf and scanf formatters are defined by configuration symbols in the file DLib\_Defaults.h.

These configuration symbols determine what capabilities the function printf should have:

Printf configuration symbols	Includes support for
_DLIB_PRINTF_MULTIBYTE	Multibyte characters
_DLIB_PRINTF_LONG_LONG	Long long (11 qualifier)
_DLIB_PRINTF_SPECIFIER_FLOAT	Floating-point numbers
_DLIB_PRINTF_SPECIFIER_A	Hexadecimal floating-point numbers
_DLIB_PRINTF_SPECIFIER_N	Output count (%n)
_DLIB_PRINTF_QUALIFIERS	Qualifiers h, 1, L, v, t, and $\boldsymbol{z}$
_DLIB_PRINTF_FLAGS	Flags -, +, #, and 0
_DLIB_PRINTF_WIDTH_AND_PRECISION	Width and precision
_DLIB_PRINTF_CHAR_BY_CHAR	Output char by char or buffered

Table 10: Descriptions of printf configuration symbols

When you build a library, these configurations determine what capabilities the function scanf should have:

Scanf configuration symbols	Includes support for
_DLIB_SCANF_MULTIBYTE	Multibyte characters
_DLIB_SCANF_LONG_LONG	Long long (11 qualifier)
_DLIB_SCANF_SPECIFIER_FLOAT	Floating-point numbers
_DLIB_SCANF_SPECIFIER_N	Output count (%n)
_DLIB_SCANF_QUALIFIERS	Qualifiers h, j, 1, t, z, and ${\tt L}$
_DLIB_SCANF_SCANSET	Scanset ([*])
_DLIB_SCANF_WIDTH	Width
_DLIB_SCANF_ASSIGNMENT_SUPPRESSING	Assignment suppressing ([ * ])

Table 11: Descriptions of scanf configuration symbols

#### **CUSTOMIZING FORMATTING CAPABILITIES**

To customize the formatting capabilities, you must;

- I Set up a library project, see *Building and using a customized library*, page 101.
- **2** Define the configuration symbols according to your application requirements.

## File input and output

The library contains a large number of powerful functions for file I/O operations, such as fopen, fclose, fprintf, fputs, etc. All these functions call a small set of low-level functions, each designed to accomplish one particular task; for example, \_\_open opens a file, and \_\_write outputs characters. Before your application can use the library functions for file I/O operations, you must implement the corresponding low-level function to suit your target hardware. For more information, see *Adapting the library for target hardware*, page 100.

Note that file I/O capability in the library is only supported by libraries with the full library configuration, see *Library configurations*, page 107. In other words, file I/O is supported when the configuration symbol \_\_DLIB\_FILE\_DESCRIPTOR is enabled. If not enabled, functions taking a FILE \* argument cannot be used.

Template code for these I/O files is included in the product:

I/O function	File	Description
close	close.c	Closes a file.
lseek	lseek.c	Sets the file position indicator.
open	open.c	Opens a file.
read	read.c	Reads a character buffer.
write	write.c	Writes a character buffer.
remove	remove.c	Removes a file.
rename	rename.c	Renames a file.

Table 12: Low-level I/O files

The low-level functions identify I/O streams, such as an open file, with a file descriptor that is a unique integer. The I/O streams normally associated with stdin, stdout, and stderr have the file descriptors 0, 1, and 2, respectively.

**Note:** If you link your application with I/O debug support, C-SPY variants of the low-level I/O functions are linked for interaction with C-SPY. For more information, see *Application debug support*, page 97.

### Locale

*Locale* is a part of the C language that allows language- and country-specific settings for several areas, such as currency symbols, date and time, and multibyte character encoding.

Depending on what runtime library you are using you get different level of locale support. However, the more locale support, the larger your code will get. It is therefore necessary to consider what level of support your application needs.

The DLIB library can be used in two main modes:

- With locale interface, which makes it possible to switch between different locales during runtime
- Without locale interface, where one selected locale is hardwired into the application.

#### LOCALE SUPPORT IN PREBUILT LIBRARIES

The level of locale support in the prebuilt libraries depends on the library configuration.

- All prebuilt libraries support the C locale only
- All libraries with full library configuration have support for the locale interface. For
  prebuilt libraries with locale interface, it is by default only supported to switch
  multibyte character encoding at runtime.
- Libraries with normal library configuration do not have support for the locale interface.

If your application requires a different locale support, you must rebuild the library.

#### **CUSTOMIZING THE LOCALE SUPPORT**

If you decide to rebuild the library, you can choose between these locales:

- The Standard C locale
- The POSIX locale
- A wide range of European locales.

#### Locale configuration symbols

The configuration symbol \_DLIB\_FULL\_LOCALE\_SUPPORT, which is defined in the library configuration file, determines whether a library has support for a locale interface or not. The locale configuration symbols \_LOCALE\_USE\_LANG\_REGION and \_ENCODING\_USE\_ENCODING define all the supported locales and encodings:

See DLib\_Defaults.h for a list of supported locale and encoding settings.

If you want to customize the locale support, you simply define the locale configuration symbols required by your application. For more information, see *Building and using a customized library*, page 101.

**Note:** If you use multibyte characters in your C or assembler source code, make sure that you select the correct locale symbol (the local host locale).

#### Building a library without support for locale interface

The locale interface is not included if the configuration symbol \_\_DLIB\_FULL\_LOCALE\_SUPPORT is set to 0 (zero). This means that a hardwired locale is used—by default the Standard C locale—but you can choose one of the supported locale configuration symbols. The setlocale function is not available and can therefore not be used for changing locales at runtime.

#### Building a library with support for locale interface

Support for the locale interface is obtained if the configuration symbol \_\_DLIB\_FULL\_LOCALE\_SUPPORT is set to 1. By default, the Standard C locale is used, but you can define as many configuration symbols as required. Because the setlocale function will be available in your application, it will be possible to switch locales at runtime.

#### **CHANGING LOCALES AT RUNTIME**

The standard library function setlocale is used for selecting the appropriate portion of the application's locale when the application is running.

The setlocale function takes two arguments. The first one is a locale category that is constructed after the pattern LC\_CATEGORY. The second argument is a string that describes the locale. It can either be a string previously returned by setlocale, or it can be a string constructed after the pattern:

lang\_REGION

or

lang\_REGION.encoding

The lang part specifies the language code, and the REGION part specifies a region qualifier, and encoding specifies the multibyte character encoding that should be used.

The <code>lang\_REGION</code> part matches the <code>\_LOCALE\_USE\_LANG\_REGION</code> preprocessor symbols that can be specified in the library configuration file.

#### **Example**

This example sets the locale configuration symbols to Swedish to be used in Finland and UTF8 multibyte character encoding:

```
setlocale (LC_ALL, "sv_FI.Utf8");
```

#### **Environment interaction**

According to the C standard, your application can interact with the environment using the functions geteny and system.

**Note:** The putenv function is not required by the standard, and the library does not provide an implementation of it.

#### THE GETENV FUNCTION

The getenv function searches the string, pointed to by the global variable \_\_environ, for the key that was passed as argument. If the key is found, the value of it is returned, otherwise 0 (zero) is returned. By default, the string is empty.

To create or edit keys in the string, you must create a sequence of null terminated strings where each string has the format:

```
key=value\0
```

End the string with an extra null character (if you use a C string, this is added automatically). Assign the created sequence of strings to the \_\_environ variable.

For example:

```
const char MyEnv[] = "Key=Value\0Key2=Value2\0";
environ = MyEnv;
```

If you need a more sophisticated environment variable handling, you should implement your own getenv, and possibly putenv function. This does not require that you rebuild the library. You can find source templates in the files getenv.c and environ.c in the arm\src\lib directory. For information about overriding default library modules, see Overriding library modules, page 101.

#### THE SYSTEM FUNCTION

If you need to use the system function, you must implement it yourself. The system function available in the library simply returns -1.

If you decide to rebuild the library, you can find source templates in the library project template. For more information, see *Building and using a customized library*, page 101.

**Note:** If you link your application with support for I/O debugging, the system function is replaced by a C-SPY variant. For more information, see *Application debug support*, page 97.

## Signal and raise

Default implementations of the functions signal and raise are available. If these functions do not provide the functionality that you need, you can implement your own versions.

This does not require that you rebuild the library. You can find source templates in the files signal.c and raise.c in the arm\src\lib directory. For information about overriding default library modules, see *Overriding library modules*, page 101.

If you decide to rebuild the library, you can find source templates in the library project template. For more information, see *Building and using a customized library*, page 101.

#### Time

To make the \_\_time32, \_\_time64, and date functions work, you must implement the functions clock, \_\_time32, \_\_time64, and \_\_getzone. Whether you use \_\_time32 or \_\_time64 depends on which interface you use for time\_t, see *time.h*, page 378.

To implement these functions does not require that you rebuild the library. You can find source templates in the files clock.c, time.c, time64.c, and getzone.c in the arm\src\lib directory. For information about overriding default library modules, see *Overriding library modules*, page 101.

If you decide to rebuild the library, you can find source templates in the library project template. For more information, see *Building and using a customized library*, page 101.

The default implementation of \_\_getzone specifies UTC (Coordinated Universal Time) as the time zone.

**Note:** If you link your application with support for I/O debugging, the functions clock and time are replaced by C-SPY variants that return the host clock and time respectively. For more information, see *Application debug support*, page 97.

#### **Pow**

The DLIB runtime library contains an alternative power function with extended precision, powXp. The lower-precision pow function is used by default. To use the powXp function instead, link your application with the linker option --redirect pow=powXp.

#### **Assert**

If you linked your application with support for runtime debugging, an assert will print a message on stdout. If this is not the behavior you require, you must add the source file xreportassert.c to your application project. The \_\_iar\_ReportAssert function generates the assert notification. You can find template code in the arm\src\lib directory. For more information, see *Building and using a customized library*, page 101. To turn off assertions, you must define the symbol NDEBUG.



In the IDE, this symbol NDEBUG is by default defined in a Release project and *not* defined in a Debug project. If you build from the command line, you must explicitly define the symbol according to your needs. See *NDEBUG*, page 369.

#### **Atexit**

The linker allocates a static memory area for atexit function calls. By default, the number of calls to the atexit function are limited to 32. To change this limit, see *Setting up the atexit limit*, page 82.

## Managing a multithreaded environment

In a multithreaded environment, the standard library must treat all library objects according to whether they are global or local to a thread. If an object is a true global object, any updates of its state must be guarded by a locking mechanism to make sure that only one thread can update it at any given time. If an object is local to a thread, the static variables containing the object state must reside in a variable area local to that thread. This area is commonly named *thread-local storage* (TLS).

There are three possible scenarios, and you need to consider which one that applies to you:

- If you are using an RTOS that supports the multithreading provided by the DLIB library, the RTOS and the DLIB library will handle multithreading which means you do not need to adapt the DLIB library.
- If you are using an RTOS that does not support or only partly supports the
  multithreading provided by the DLIB library, you probably need to adapt both the
  RTOS and the DLIB library.
- If you are not using an RTOS, you must adapt the DLIB library to get support for multithreading.

#### MULTITHREAD SUPPORT IN THE DLIB LIBRARY

The DLIB library uses two kinds of locks—system locks and file stream locks. The file stream locks are used as guards when the state of a file stream is updated, and are only needed in the Full library configuration. The following library objects are guarded with system locks:

- The heap, in other words when malloc, new, free, delete, realloc, or calloc
  is used.
- The file system (only available in the Full library configuration), but not the file streams themselves. The file system is updated when a stream is opened or closed, in other words when fopen, fclose, fdopen, fflush, or freepen is used.
- The signal system, in other words when signal is used.
- The temporary file system, in other words when tmpnam is used.
- Initialization of static function objects.

These library objects use TLS:

Library objects using TLS	When these functions are used
Error functions	errno, strerror
Locale functions	localeconv, setlocale
Time functions	asctime, localtime, gmtime, mktime
Multibyte functions	mbrlen, mbrtowc, mbsrtowc, mbtowc, wcrtomb, wcsrtomb, wctomb
Rand functions	rand, srand
Miscellaneous functions	atexit,strtok
C++ exception engine	N/A

Table 13: Library objects using TLS

#### **ENABLING MULTITHREAD SUPPORT**

To enable multithread support in the library, you must:

- Add #define \_DLIB\_THREAD\_SUPPORT in DLib\_product.h and rebuild your library
- Implement code for the library's system locks interface
- Implement source code that handles thread creation, thread destruction, and TLS access methods for the library

- Modify the linker configuration file accordingly
- If any of the C++ variants are used, use the compiler option --guard\_calls.
   Otherwise, function static variables with dynamic initializers might be initialized simultaneously by several threads.

You can find the required declaration of functions and definitions of macros in the DLib Threads. h file, which is included by yvals. h.

#### System locks interface

This interface must be fully implemented for system locks to work:

The lock and unlock implementation must survive nested calls.

#### File streams locks interface

This interface is only needed for the Full library configuration. If file streams are used, they can either be fully implemented or they can be redirected to the system locks interface. This interface must be implemented for file streams locks to work:

The lock and unlock implementation must survive nested calls.

#### **DLIB** lock usage

The number of locks that the DLIB library assumes exist are:

- \_FOPEN\_MAX—the maximum number of file stream locks. These locks are only
  used in the Full library configuration, in other words only if both the macro symbols
  \_DLIB\_FILE\_DESCRIPTOR and \_FILE\_OP\_LOCKS are true.
- \_MAX\_LOCK—the maximum number of system locks.

Note that even if the application uses fewer locks, the DLIB library will initialize and destroy all of the locks above.

For information about the initialization and destruction code, see xsyslock.c.

#### TLS handling

The DLIB library supports TLS memory areas for two types of threads: the *main thread* (the main function including the system startup and exit code) and *secondary threads*.

The main thread's TLS memory area:

- Is automatically created and initialized by your application's startup sequence
- Is automatically destructed by the application's destruct sequence
- Is located in the section \_\_DLIB\_PERTHREAD
- Exists also for non-threaded applications.

Each secondary thread's TLS memory area:

- Must be manually created and initialized
- Must be manually destructed
- Is located in a manually allocated memory area.

If you need the runtime library to support secondary threads, you must override the function:

```
void *__iar_dlib_perthread_access(void *symbp);
```

The parameter is the address to the TLS variable to be accessed—in the main thread's TLS area—and it should return the address to the symbol in the current TLS area.

Two interfaces can be used for creating and destroying secondary threads. You can use the following interface that allocates a memory area on the heap and initializes it. At deallocation, it destroys the objects in the area and then frees the memory.

```
void *__iar_dlib_perthread_allocate(void);
void __iar_dlib_perthread_deallocate(void *);
```

Alternatively, if the application handles the TLS allocation, you can use this interface for initializing and destroying the objects in the memory area:

```
void __iar_dlib_perthread_initialize(void *);
void __iar_dlib_perthread_destroy(void *);
```

These macros can be helpful when you implement an interface for creating and destroying secondary threads:

Macro	Description
IAR_DLIB_PERTHREAD_SIZE	Returns the size needed for the TLS memory
	area.
IAR_DLIB_PERTHREAD_INIT_SIZE	Returns the initializer size for the TLS memory area. You should initialize the rest of the TLS
	memory area, up to
	IAR_DLIB_PERTHREAD_SIZE to zero.
IAR_DLIB_PERTHREAD_SYMBOL_ OFFSET(symbolptr)	Returns the offset to the symbol in the TLS memory area.

Table 14: Macros for implementing TLS allocation

Note that the size needed for TLS variables depends on which DLIB resources your application uses.

This is an example of how you can handle threads:

```
#include <yvals.h>
/* A thread's TLS pointer */
void _DLIB_TLS_MEMORY *TLSp;
/* Are we in a secondary thread? */
int InSecondaryThread = 0;
/* Allocate a thread-local TLS memory
   area and store a pointer to it in TLSp. */
void AllocateTLS()
 TLSp = __iar_dlib_perthread_allocate();
/* Deallocate the thread-local TLS memory area. */
void DeallocateTLS()
  __iar_dlib_perthread_deallocate(TLSp);
/* Access an object in the
   thread-local TLS memory area. */
void _DLIB_TLS_MEMORY *__iar_dlib_perthread_access(
 void _DLIB_TLS_MEMORY *symbp)
 char _DLIB_TLS_MEMORY *p = 0;
```

```
if (InSecondaryThread)
  p = (char _DLIB_TLS_MEMORY *) TLSp;
else
  p = (char _DLIB_TLS_MEMORY *)
    __segment_begin("__DLIB_PERTHREAD");

p += __IAR_DLIB_PERTHREAD_SYMBOL_OFFSET(symbp);
return (void _DLIB_TLS_MEMORY *) p;
}
```

The TLSp variable is unique for each thread, and must be exchanged by the RTOS or manually whenever a thread switch occurs.

#### **CHANGES IN THE LINKER CONFIGURATION FILE**

Normally, the linker automatic chooses how to initialize static data. If threads are used, the main thread's TLS memory area must be initialized by naive copying because the initializers are used for each secondary thread's TLS memory area as well. Insert the following statement in your linker configuration file:

```
initialize by copy with packing = none { section __DLIB_PERTHREAD
}:
```

## **Checking module consistency**

This section introduces the concept of runtime model attributes, a mechanism that you can use to ensure that modules are built using compatible settings.

When developing an application, it is important to ensure that incompatible modules are not used together. For example, if you have a UART that can run in two modes, you can specify a runtime model attribute, for example uart. For each mode, specify a value, for example mode1 and mode2. Declare this in each module that assumes that the UART is in a particular mode.

The tools provided by IAR Systems use a set of predefined runtime model attributes to automatically ensure module consistency.

#### **RUNTIME MODEL ATTRIBUTES**

A runtime attribute is a pair constituted of a named key and its corresponding value. In general, two modules can only be linked together if they have the same value for each key that they both define.

There is one exception: if the value of an attribute is \*, then that attribute matches any value. The reason for this is that you can specify this in a module to show that you have considered a consistency property, and this ensures that the module does not rely on that property.

**Note:** For IAR predefined runtime model attributes, the linker checks them in several ways.

#### Example

In this table, the object files could (but do not have to) define the two runtime attributes color and taste:

Object file	Color	Taste
file1	blue	not defined
file2	red	not defined
file3	red	*
file4	red	spicy
file5	red	lean

Table 15: Example of runtime model attributes

In this case, file1 cannot be linked with any of the other files, since the runtime attribute color does not match. Also, file4 and file5 cannot be linked together, because the taste runtime attribute does not match.

On the other hand, file2 and file3 can be linked with each other, and with either file4 or file5, but not with both.

#### **USING RUNTIME MODEL ATTRIBUTES**

To ensure module consistency with other object files, use the #pragma rtmodel directive to specify runtime model attributes in your C/C++ source code. For example:

```
#pragma rtmodel="uart", "model"
```

For detailed syntax information, see rtmodel, page 317.

You can also use the rtmodel assembler directive to specify runtime model attributes in your assembler source code. For example:

```
rtmodel "color", "red"
```

For syntax information, see the ARM® IAR Assembler Reference Guide.

At link time, the IAR ILINK Linker checks module consistency by ensuring that modules with conflicting runtime attributes will not be used together. If conflicts are detected, an error is issued.

Checking module consistency

# Assembler language interface

When you develop an application for an embedded system, there might be situations where you will find it necessary to write parts of the code in assembler, for example when using mechanisms in the ARM core that require precise timing and special instruction sequences.

This chapter describes the available methods for this and some C alternatives, with their advantages and disadvantages. It also describes how to write functions in assembler language that work together with an application written in C or C++.

Finally, the chapter covers how functions are called, and how you can implement support for call frame information in your assembler routines for use in the C-SPY® Call Stack window.

## Mixing C and assembler

The IAR C/C++ Compiler for ARM provides several ways to access low-level resources:

- Modules written entirely in assembler
- Intrinsic functions (the C alternative)
- Inline assembler.

It might be tempting to use simple inline assembler. However, you should carefully choose which method to use.

#### **INTRINSIC FUNCTIONS**

The compiler provides a few predefined functions that allow direct access to low-level processor operations without having to use the assembler language. These functions are known as intrinsic functions. They can be very useful in, for example, time-critical routines.

An intrinsic function looks like a normal function call, but it is really a built-in function that the compiler recognizes. The intrinsic functions compile into inline code, either as a single instruction, or as a short sequence of instructions.

The advantage of an intrinsic function compared to using inline assembler is that the compiler has all necessary information to interface the sequence properly with register allocation and variables. The compiler also knows how to optimize functions with such sequences; something the compiler is unable to do with inline assembler sequences. The result is that you get the desired sequence properly integrated in your code, and that the compiler can optimize the result.

For more information about the available intrinsic functions, see the chapter *Intrinsic functions*.

#### MIXING C AND ASSEMBLER MODULES

It is possible to write parts of your application in assembler and mix them with your C or C++ modules. This gives several benefits compared to using inline assembler:

- The function call mechanism is well-defined
- The code will be easy to read
- The optimizer can work with the C or C++ functions.

This causes some overhead in the form of a function call and return instruction sequences, and the compiler will regard some registers as scratch registers. However, the compiler will also assume that all scratch registers are destroyed by an inline assembler instruction. In many cases, the overhead of the extra instructions can be removed by the optimizer.

An important advantage is that you will have a well-defined interface between what the compiler produces and what you write in assembler. When using inline assembler, you will not have any guarantees that your inline assembler lines do not interfere with the compiler generated code.

When an application is written partly in assembler language and partly in C or C++, you are faced with several questions:

- How should the assembler code be written so that it can be called from C?
- Where does the assembler code find its parameters, and how is the return value passed back to the caller?
- How should assembler code call functions written in C?
- How are global C variables accessed from code written in assembler language?
- Why does not the debugger display the call stack when assembler code is being debugged?

The first question is discussed in the section *Calling assembler routines from C*, page 129. The following two are covered in the section *Calling convention*, page 132.

The section *Inline assembler*, page 127, covers how to use inline assembler, but it also shows how data in memory is accessed.

The answer to the final question is that the call stack can be displayed when you run assembler code in the debugger. However, the debugger requires information about the *call frame*, which must be supplied as annotations in the assembler source file. For more information, see *Call frame information*, page 138.

The recommended method for mixing C or C++ and assembler modules is described in *Calling assembler routines from C*, page 129, and *Calling assembler routines from C*++, page 131, respectively.

#### **INLINE ASSEMBLER**

It is possible to insert assembler code directly into a C or C++ function. The asm and \_\_asm keywords both insert the supplied assembler statement in-line, see *Inline assembler*, page 144 for more information. The following example demonstrates the use of the asm keyword. This example (for ARM mode) also shows the risks of using inline assembler.

```
extern volatile char UART1 SR;
#pragma required=UART1_SR
char sFlag;
void Foo(void)
 while (!sFlag)
   asm(" ldr r2, [pc, #0] \n" /* r2 = address of sFlag
       " b .+8 \n" /* jump over constant
" DCD sFlag \n" /* address of sFlag
                                                       * /
       " 1dr r3, [pc, #0] \n" /* r3 = address of UART1_SR */
        " b .+8 \n" /* jump over constant
                                                        * /
        " DCD UART1 SR \n" /* address of UART1 SR
                                                       * /
        " 1dr r0, [r3] \n" /* r0 = UART1_SR
        " str r0,[r2]"); /* sFlag = r0
 }
```

In this example, the assignment to the global variable sFlag is not noticed by the compiler, which means the surrounding code cannot be expected to rely on the inline assembler statement.

The inline assembler instruction will simply be inserted at the given location in the program flow. The consequences or side-effects the insertion might have on the surrounding code are not taken into consideration. If, for example, registers or memory locations are altered, they might have to be restored within the sequence of inline assembler instructions for the rest of the code to work properly.

Inline assembler sequences have no well-defined interface with the surrounding code generated from your C or C++ code. This makes the inline assembler code fragile, and will possibly also become a maintenance problem if you upgrade the compiler in the future. There are also several limitations to using inline assembler:

- The compiler's various optimizations will disregard any effects of the inline sequences, which will not be optimized at all
- In general, assembler directives will cause errors or have no meaning. Data definition directives will however work as expected
- Alignment cannot be controlled; this means, for example, that DC32 directives might be misaligned
- Auto variables cannot be accessed
- Alternative register names, mnemonics, and operators are not supported; read more about the -j assembler option in the ARM® IAR Assembler Reference Guide.

Inline assembler is therefore often best avoided. If no suitable intrinsic function is available, we recommend that you use modules written in assembler language instead of inline assembler, because the function call to an assembler routine normally causes less performance reduction.

The corresponding example for Thumb mode requires the Thumb2 instruction set:

```
extern volatile char UART1_SR;
#pragma required=UART1_SR

char sFlag;

void Foo(void)
{
   while (!sFlag)
   {
      /* This requires Thumb2: the Thumb1 LDR instruction
      * requires 4-bytes alignment for the LDR source label,
      * which cannot be guaranteed.
      *
      * The base address used for LDR is 4-bytes aligned, but
      * the code alignment is unknown so a label must be used
      * to have the assembler calculate the correct PC-relative
      * offset. Inline assembler is one-pass only, so the label
      * must be introduced before it is used.
```

```
*/
asm(" b.n .+11 \n" /* jump over constants */
    "const: \n" /* label is odd (Thumb) */
    " DCD sFlag \n" /* address of sFlag */
    " DCD UART1_SR \n" /* address of UART1_SR */
    " ldr.w r3,const+3 \n" /* r3 = address of UART1_SR */
    " ldr.w r2,const-1 \n" /* r2 = address of sFlag */
    " ldr r0,[r3] \n" /* r0 = UART1_SR */
    " str r0,[r2]"); /* sFlag = r0 */
}
```

## Calling assembler routines from C

An assembler routine that will be called from C must:

- Conform to the calling convention
- Have a PUBLIC entry-point label
- Be declared as external before any call, to allow type checking and optional promotion of parameters, as in these examples:

```
extern int foo(void);
or
extern int foo(int i, int j);
```

One way of fulfilling these requirements is to create skeleton code in C, compile it, and study the assembler list file.

#### **CREATING SKELETON CODE**

The recommended way to create an assembler language routine with the correct interface is to start with an assembler language source file created by the C compiler. Note that you must create skeleton code for each function prototype.

The following example shows how to create skeleton code to which you can easily add the functional body of the routine. The skeleton source code only needs to declare the variables required and perform simple accesses to them. In this example, the assembler routine takes an int and a char, and then returns an int:

```
extern int gInt;
extern char gChar;

int Func(int arg1, char arg2)
{
   int locInt = arg1;
   gInt = arg1;
   gChar = arg2;
   return locInt;
}

int main()
{
   int locInt = gInt;
   gInt = Func(locInt, gChar);
   return 0;
}
```

**Note:** In this example we use a low optimization level when compiling the code to show local and global variable access. If a higher level of optimization is used, the required references to local variables could be removed during the optimization. The actual function declaration is not changed by the optimization level.

#### **COMPILING THE CODE**



In the IDE, specify list options on file level. Select the file in the workspace window. Then choose **Project>Options**. In the **C/C++ Compiler** category, select **Override inherited settings**. On the **List** page, deselect **Output list file**, and instead select the **Output assembler file** option and its suboption **Include source**. Also, be sure to specify a low level of optimization.



Use these options to compile the skeleton code:

```
iccarm skeleton.c -1A .
```

The <code>-lA</code> option creates an assembler language output file including C or C++ source lines as assembler comments. The . (period) specifies that the assembler file should be named in the same way as the C or C++ module (<code>skeleton</code>), but with the filename extension <code>s</code>. Also remember to specify a low level of optimization, and <code>-e</code> for enabling language extensions.

The result is the assembler source output file skeleton.s.

**Note:** The -1A option creates a list file containing call frame information (CFI) directives, which can be useful if you intend to study these directives and how they are



used. If you only want to study the calling convention, you can exclude the CFI directives from the list file. In the IDE, choose **Project>Options>C/C++ Compiler>List** and deselect the suboption **Include call frame information**. On the command line, use the option -lB instead of -lA. Note that CFI information must be included in the source code to make the C-SPY Call Stack window work.

#### The output file

The output file contains the following important information:

- The calling convention
- The return values
- The global variables
- The function parameters
- How to create space on the stack (auto variables)
- Call frame information (CFI).

The CFI directives describe the call frame information needed by the Call Stack window in the debugger. For more information, see *Call frame information*, page 138.

## Calling assembler routines from C++

The C calling convention does not apply to C++ functions. Most importantly, a function name is not sufficient to identify a C++ function. The scope and the type of the function are also required to guarantee type-safe linkage, and to resolve overloading.

Another difference is that non-static member functions get an extra, hidden argument, the this pointer.

However, when using C linkage, the calling convention conforms to the C calling convention. An assembler routine can therefore be called from C++ when declared in this manner:

```
extern "C"
{
  int MyRoutine(int);
}
```

The following example shows how to achieve the equivalent to a non-static member function, which means that the implicit this pointer must be made explicit. It is also possible to "wrap" the call to the assembler routine in a member function. Use an inline member function to remove the overhead of the extra call—this assumes that function inlining is enabled:

```
class MyClass;
extern "C"
{
  void DoIt(MyClass *ptr, int arg);
}
class MyClass
{
public:
  inline void DoIt(int arg)
  {
    ::DoIt(this, arg);
  }
};
```

## **Calling convention**

A calling convention is the way a function in a program calls another function. The compiler handles this automatically, but, if a function is written in assembler language, you must know where and how its parameters can be found, how to return to the program location from where it was called, and how to return the resulting value.

It is also important to know which registers an assembler-level routine must preserve. If the program preserves too many registers, the program might be ineffective. If it preserves too few registers, the result would be an incorrect program.

This section describes the calling convention used by the compiler. These items are examined:

- Function declarations
- C and C++ linkage
- Preserved versus scratch registers
- Function entrance
- Function exit
- Return address handling.

At the end of the section, some examples are shown to describe the calling convention in practice.

Unless otherwise noted, the calling convention used by the compiler adheres to AAPCS, a part of AEABI; see *AEABI compliance*, page 174.

#### **FUNCTION DECLARATIONS**

In C, a function must be declared in order for the compiler to know how to call it. A declaration could look as follows:

```
int MyFunction(int first, char * second);
```

This means that the function takes two parameters: an integer and a pointer to a character. The function returns a value, an integer.

In the general case, this is the only knowledge that the compiler has about a function. Therefore, it must be able to deduce the calling convention from this information.

#### **USING C LINKAGE IN C++ SOURCE CODE**

In C++, a function can have either C or C++ linkage. To call assembler routines from C++, it is easiest if you make the C++ function have C linkage.

This is an example of a declaration of a function with C linkage:

```
extern "C"
{
  int F(int);
}
```

It is often practical to share header files between C and C++. This is an example of a declaration that declares a function with C linkage in both C and C++:

```
#ifdef __cplusplus
extern "C"
{
#endif
int F(int);
#ifdef __cplusplus
}
#endif
```

#### PRESERVED VERSUS SCRATCH REGISTERS

The general ARM CPU registers are divided into three separate sets, which are described in this section.

#### Scratch registers

Any function is permitted to destroy the contents of a scratch register. If a function needs the register value after a call to another function, it must store it during the call, for example on the stack.

Any of the registers R0 to R3, and R12, can be used as a scratch register by the function. Note that R12 is a scratch register also when calling between assembler functions only because of automatically inserted instructions for veneers.

#### **Preserved registers**

Preserved registers, on the other hand, are preserved across function calls. The called function can use the register for other purposes, but must save the value before using the register and restore it at the exit of the function.

The registers R4 through to R11 are preserved registers. They are preserved by the called function.

#### **Special registers**

For some registers, you must consider certain prerequisites:

- The stack pointer register, R13/SP, must at all times point to or below the last element on the stack. In the eventuality of an interrupt, everything below the point the stack pointer points to, can be destroyed. At function entry and exit, the stack pointer must be 8-byte aligned. In the function, the stack pointer must always be word aligned. At exit, SP must have the same value as it had at the entry.
- The register R15/PC is dedicated for the Program Counter.
- The link register, R14/LR, holds the return address at the entrance of the function.

#### **FUNCTION ENTRANCE**

Parameters can be passed to a function using one of two basic methods: in registers or on the stack. It is much more efficient to use registers than to take a detour via memory, so the calling convention is designed to use registers as much as possible. Only a limited number of registers can be used for passing parameters; when no more registers are available, the remaining parameters are passed on the stack. These exceptions to the rules apply:

- Interrupt functions cannot take any parameters, except software interrupt functions that accept parameters and have return values
- Software interrupt functions cannot use the stack in the same way as ordinary
  functions. When an SVC instruction is executed, the processor switches to
  supervisor mode where the supervisor stack is used. Arguments can therefore not be
  passed on the stack if your application is not running in supervisor mode previous to
  the interrupt.

#### Hidden parameters

In addition to the parameters visible in a function declaration and definition, there can be hidden parameters:

- If the function returns a structure larger than 32 bits, the memory location where the structure is to be stored is passed as an extra parameter. Notice that it is always treated as the *first parameter*.
- If the function is a non-static C++ member function, then the this pointer is passed as the first parameter (but placed after the return structure pointer, if there is one). For more information, see *Calling assembler routines from C++*, page 131.

#### Register parameters

The registers available for passing parameters are R0-R3:

Parameters	Passed in registers
Scalar and floating-point values no larger than 32 bits, and	Passed using the first free register:
single-precision (32-bits) floating-point values	R0-R3
long long and double-precision (64-bit) values	Passed in first available register pair:
	R0:R1, or R2:R3

Table 16: Registers used for passing parameters

The assignment of registers to parameters is a straightforward process. Traversing the parameters from left to right, the first parameter is assigned to the available register or registers. Should there be no more available registers, the parameter is passed on the stack in reverse order.

When functions that have parameters smaller than 32 bits are called, the values are sign or zero extended to ensure that the unused bits have consistent values. Whether the values will be sign or zero extended depends on their type—signed or unsigned.

#### Stack parameters and layout

Stack parameters are stored in memory, starting at the location pointed to by the stack pointer. Below the stack pointer (towards low memory) there is free space that the called function can use. The first stack parameter is stored at the location pointed to by the stack pointer. The next one is stored at the next location on the stack that is divisible by four, etc. It is the responsibility of the caller to clean the stack after the called function has returned.

High address

The caller's stack frame

Parameter n

...

Parameter 1

Return address

Free stack memory

Free stack memory

This figure illustrates how parameters are stored on the stack:

Figure 13: Stack image after the function call

The stack should be aligned to 8 at function entry.

#### **FUNCTION EXIT**

A function can return a value to the function or program that called it, or it can have the return type void.

The return value of a function, if any, can be scalar (such as integers and pointers), floating-point, or a structure.

#### Registers used for returning values

The registers available for returning values are RO and RO:R1.

Return values	Passed in register/register pair
Scalar and structure return values no larger than 32 bits, and single-precision (32-bit) floating-point return values	i RO
The memory address of a structure return value larger than bits	<b>32</b> R0
long long and double-precision (64-bit) return values	R0:R1
Table 17. Business of framework in the	

Table 17: Registers used for returning values

If the returned value is smaller than 32 bits, the value is sign- or zero-extended to 32 bits.

#### Stack layout at function exit

It is the responsibility of the caller to clean the stack after the called function has returned.

#### Return address handling

A function written in assembler language should, when finished, return to the caller, by jumping to the address pointed to by the register LR.

At function entry, non-scratch registers and the LR register can be pushed with one instruction. At function exit, all these registers can be popped with one instruction. The return address can be popped directly to PC.

The following example shows what this can look like:

```
name call
section .text:CODE
extern func

push {r4-r6,lr} ; Preserve stack alignment 8
bl func
; Do something here.

pop {r4-r6,pc} ; return
end
```

#### **EXAMPLES**

The following section shows a series of declaration examples and the corresponding calling conventions. The complexity of the examples increases toward the end.

#### Example I

Assume this function declaration:

```
int add1(int);
```

This function takes one parameter in the register R0, and the return value is passed back to its caller in the register R0.

This assembler routine is compatible with the declaration; it will return a value that is one number higher than the value of its parameter:

```
name return
section .text:CODE
adds r0, r0, #1
bx lr
end
```

#### Example 2

This example shows how structures are passed on the stack. Assume these declarations:

```
struct MyStruct
{
    short a;
    short b;
    short c;
    short d;
    short e;
};
int MyFunction(struct MyStruct x, int y);
```

The values of the structure members a, b, c, and d are passed in registers R0-R3. The last structure member e and the integer parameter y are passed on the stack. The calling function must reserve eight bytes on the top of the stack and copy the contents of the two stack parameters to that location. The return value is passed back to its caller in the register R0.

#### Example 3

The function below will return a structure of type struct MyStruct.

```
struct MyStruct
{
   int mA;
};
struct MyStruct MyFunction(int x);
```

It is the responsibility of the calling function to allocate a memory location for the return value and pass a pointer to it as a hidden first parameter. The pointer to the location where the return value should be stored is passed in R0. The parameter x is passed in R1.

Assume that the function instead was declared to return a pointer to the structure:

```
struct MyStruct *MyFunction(int x);
```

In this case, the return value is a scalar, so there is no hidden parameter. The parameter x is passed in R2, and the return value is returned in R0 or (R1,R0), depending on the data model.

## **Call frame information**

When you debug an application using C-SPY, you can view the *call stack*, that is, the chain of functions that called the current function. To make this possible, the compiler

supplies debug information that describes the layout of the call frame, in particular information about where the return address is stored.

If you want the call stack to be available when debugging a routine written in assembler language, you must supply equivalent debug information in your assembler source using the assembler directive CFI. This directive is described in detail in the ARM® IAR Assembler Reference Guide.

#### **CFI DIRECTIVES**

The CFI directives provide C-SPY with information about the state of the calling function(s). Most important of this is the return address, and the value of the stack pointer at the entry of the function or assembler routine. Given this information, C-SPY can reconstruct the state for the calling function, and thereby unwind the stack.

A full description about the calling convention might require extensive call frame information. In many cases, a more limited approach will suffice.

When describing the call frame information, the following three components must be present:

- A names block describing the available resources to be tracked
- A common block corresponding to the calling convention
- A data block describing the changes that are performed on the call frame. This
  typically includes information about when the stack pointer is changed, and when
  permanent registers are stored or restored on the stack.

This table lists all the resources defined in the names block used by the compiler:

Resource	Description
CFA R13	The call frames of the stack
R0-R12	Processor general-purpose 32-bit registers
R13	Stack pointer, SP
R14	Link register, LR
S0-S31	Vector Floating Point (VFP) 32-bit coprocessor registers
CPSR	Current program status register
SPSR	Saved program status register

Table 18: Call frame information resources defined in a names block

#### CREATING ASSEMBLER SOURCE WITH CFI SUPPORT

The recommended way to create an assembler language routine that handles call frame information correctly is to start with an assembler language source file created by the compiler.

I Start with suitable C source code, for example:

```
int F(int);
int cfiExample(int i)
{
   return i + F(i);
}
```

**2** Compile the C source code, and make sure to create a list file that contains call frame information—the CFI directives.



On the command line, use the option -1A.



In the IDE, choose **Project>Options>C/C++ Compiler>List** and make sure the suboption **Include call frame information** is selected.

For the source code in this example, the list file looks like this:

```
#if Compile
int F(int);
int cfiExample(int i)
 return i + F(i);
#endif
       NAME Cfi
        RTMODEL "__SystemLibrary", "DLib"
        EXTERN F
        PUBLIC cfiExample
        CFI Names cfiNames0
        CFI StackFrame CFA R13 DATA
        CFI Resource R0:32, R1:32, R2:32, R3:32, R4:32, \
                                          R5:32, R6:32, R7:32
        CFI Resource R8:32, R9:32, R10:32, R11:32, R12:32, \
                                                R13:32, R14:32
        CFI EndNames cfiNames0
        CFI Common cfiCommon0 Using cfiNames0
        CFI CodeAlign 4
```

```
CFI DataAlign 4
        CFI ReturnAddress R14 CODE
        CFI CFA R13+0
       CFI R0 Undefined
       CFI R1 Undefined
       CFI R2 Undefined
       CFI R3 Undefined
       CFI R4 SameValue
       CFI R5 SameValue
       CFI R6 SameValue
       CFI R7 SameValue
       CFI R8 SameValue
       CFI R9 SameValue
       CFI R10 SameValue
       CFI R11 SameValue
       CFI R12 Undefined
        CFI R14 SameValue
        CFI EndCommon cfiCommon0
        SECTION `.text`:CODE:NOROOT(2)
        CFI Block cfiBlock0 Using cfiCommon0
       CFI Function cfiExample
       ARM
cfiExample:
       PUSH
                {R4,LR}
       CFI R14 Frame (CFA, -4)
       CFI R4 Frame(CFA, -8)
       CFI CFA R13+8
       MOVS R4,R0
       MOVS
               R0,R4
       BL
                F
       ADDS
               R0,R0,R4
        POP
                {R4,PC}
                                ;; return
        CFI EndBlock cfiBlock0
        END
```

**Note:** The header file cfiCommon.i contains the macros CFI\_NAME\_BLOCK, CFI\_COMMON\_ARM, and CFI\_COMMON\_Thumb, which declare a typical names block and two typical common blocks. These macros declare several resources, both concrete and virtual.

Call frame information

## **Using C**

This chapter gives an overview of the compiler's support for the C language. The chapter also gives a brief overview of the IAR C language extensions.

## C language overview

The IAR C/C++ Compiler for ARM supports the ISO/IEC 9899:1999 standard (including up to technical corrigendum No.3), also known as C99. In this guide, this standard is referred to as *Standard C* and is the default standard used in the compiler. This standard is stricter than C89.

In addition, the compiler also supports the ISO 9899:1990 standard (including all technical corrigenda and addenda), also known as C94, C90, C89, and ANSI C. In this guide, this standard is referred to as C89. Use the --c89 compiler option to enable this standard.

The C99 standard is derived from C89, but adds features like these:

- The inline keyword advises the compiler that the function declared immediately
  after the directive should be inlined
- Declarations and statements can be mixed within the same scope
- A declaration in the initialization expression of a for loop
- The bool data type
- The long long data type
- The complex floating-point type
- C++ style comments
- Compound literals
- Incomplete arrays at the end of structs
- · Hexadecimal floating-point constants
- Designated initializers in structures and arrays
- The preprocessor operator \_Pragma()
- Variadic macros, which are the preprocessor macro equivalents of printf style functions
- VLA (variable length arrays) must be explicitly enabled with the compiler option
   --vla
- Inline assembler using the asm or the \_\_asm keyword.

**Note:** Even though it is a C99 feature, the IAR C/C++ Compiler for ARM does not support UCNs (universal character names).

#### Inline assembler

Inline assembler can be used for inserting assembler instructions in the generated function.

The asm extended keyword and its alias \_\_asm both insert assembler instructions. However, when you compile C source code, the asm keyword is not available when the option --strict is used. The \_\_asm keyword is always available.

**Note:** Not all assembler directives or operators can be inserted using these keywords.

The syntax is:

```
asm ("string");
```

The string can be a valid assembler instruction or a data definition assembler directive, but not a comment. You can write several consecutive inline assembler instructions, for example:

```
asm ("label: nop\n" b label");
```

where \n (new line) separates each new assembler instruction. Note that you can define and use local labels in inline assembler instructions.

For more information about inline assembler, see *Mixing C and assembler*, page 125.

## **Extensions overview**

The compiler offers the features of Standard C and a wide set of extensions, ranging from features specifically tailored for efficient programming in the embedded industry to the relaxation of some minor standards issues.

This is an overview of the available extensions:

• IAR C language extensions

For information about available language extensions, see *IAR C language extensions*, page 146. For more information about the extended keywords, see the chapter *Extended keywords*. For information about C++, the two levels of support for the language, and C++ language extensions; see the chapter *Using C*++.

Pragma directives

The #pragma directive is defined by Standard C and is a mechanism for using vendor-specific extensions in a controlled way to make sure that the source code is still portable.

The compiler provides a set of predefined pragma directives, which can be used for controlling the behavior of the compiler, for example how it allocates memory, whether it allows extended keywords, and whether it outputs warning messages. Most pragma directives are preprocessed, which means that macros are substituted in a pragma directive. The pragma directives are always enabled in the compiler. For several of them there is also a corresponding C/C++ language extension. For information about available pragma directives, see the chapter *Pragma directives*.

#### Preprocessor extensions

The preprocessor of the compiler adheres to Standard C. The compiler also makes several preprocessor-related extensions available to you. For more information, see the chapter *The preprocessor*.

#### Intrinsic functions

The intrinsic functions provide direct access to low-level processor operations and can be very useful in, for example, time-critical routines. The intrinsic functions compile into inline code, either as a single instruction or as a short sequence of instructions. For more information about using intrinsic functions, see *Mixing C and assembler*, page 125. For information about available functions, see the chapter *Intrinsic functions*.

#### • Library functions

The IAR DLIB Library provides the C and C++ library definitions that apply to embedded systems. For more information, see *IAR DLIB Library*, page 373.

**Note:** Any use of these extensions, except for the pragma directives, makes your source code inconsistent with Standard C.

#### **ENABLING LANGUAGE EXTENSIONS**

You can choose different levels of language conformance by means of project options:

Command line	IDE*	Description
strict	Strict	All IAR C language extensions are disabled; errors are issued for anything that is not part of Standard C.
None	Standard	All extensions to Standard C are enabled, but no extensions for embedded systems programming. For information about extensions, see IAR C language extensions, page 146.
-е	Standard with IAR extensions	All IAR C language extensions are enabled.

Table 19: Language extensions

<sup>\*</sup> In the IDE, choose Project>Options> C/C++ Compiler>Language>Language conformance and select the appropriate option. Note that language extensions are enabled by default.

## IAR C language extensions

The compiler provides a wide set of C language extensions. To help you to find the extensions required by your application, they are grouped like this in this section:

- Extensions for embedded systems programming—extensions specifically tailored for efficient embedded programming for the specific core you are using, typically to meet memory restrictions
- Relaxations to Standard C—that is, the relaxation of some minor Standard C issues
  and also some useful but minor syntax extensions, see Relaxations to Standard C,
  page 148.

#### **EXTENSIONS FOR EMBEDDED SYSTEMS PROGRAMMING**

The following language extensions are available both in the C and the C++ programming languages and they are well suited for embedded systems programming:

Type attributes, and object attributes
 For information about the related concepts, the general syntax rules, and for reference information, see the chapter Extended keywords.

function placement in memory, page 182, and location, page 312.

- Placement at an absolute address or in a named section
   The @ operator or the directive #pragma location can be used for placing global and static variables at absolute addresses, or placing a variable or function in a named section. For more information about using these features, see *Controlling data and*
- Alignment control

Each data type has its own alignment; for more information, see *Alignment*, page 275. If you want to change the alignment, the \_\_packed data type attribute, and the #pragma pack and #pragma data\_alignment directives are available. If you want to check the alignment of an object, use the \_\_ALIGNOF\_\_() operator.

The \_\_ALIGNOF\_\_ operator is used for accessing the alignment of an object. It takes one of two forms:

- \_\_ALIGNOF\_\_ (type)
- \_\_ALIGNOF\_\_ (expression)

In the second form, the expression is not evaluated.

• Anonymous structs and unions

C++ includes a feature called anonymous unions. The compiler allows a similar feature for both structs and unions in the C programming language. For more information, see *Anonymous structs and unions*, page 181.

• Bitfields and non-standard types

In Standard C, a bitfield must be of the type int or unsigned int. Using IAR C language extensions, any integer type or enumeration can be used. The advantage is that the struct will sometimes be smaller. For more information, see *Bitfields*, page 278.

static\_assert()

The construction static\_assert(const-expression, "message"); can be used in C/C++. The construction will be evaluated at compile time and if const-expression is false, a message will be issued including the message string.

• Parameters in variadic macros

Variadic macros are the preprocessor macro equivalents of printf style functions. The preprocessor accepts variadic macros with no arguments, which means if no parameter matches the . . . parameter, the comma is then deleted in the ", ##\_\_VA\_ARGS\_\_" macro definition. According to Standard C, the . . . parameter must be matched with at least one argument.

#### **Dedicated section operators**

The compiler supports getting the start address, end address, and size for a section with these built-in section operators:

```
__section_begin Returns the address of the first byte of the named section or block.

__section_end Returns the address of the first byte after the named section or block.

__section_size Returns the size of the named section or block in bytes.
```

```
Note: The aliases __segment_begin/_sfb, __segment_end/_sfe, and __segment_size/_sfs can also be used.
```

The operators can be used on named sections or on named blocks defined in the linker configuration file.

These operators behave syntactically as if declared like:

```
void * __section_begin(char const * section)
void * __section_end(char const * section)
size_t * __section_size(char const * section)
```

When you use the @ operator or the #pragma location directive to place a data object or a function in a user-defined section, or when you use named blocks in the linker configuration file, the section operators can be used for getting the start and end address of the memory range where the sections or blocks were placed.

The named *section* must be a string literal and it must have been declared earlier with the #pragma section directive. The type of the \_\_section\_begin operator is a pointer to void. Note that you must enable language extensions to use these operators.

The operators are implemented in terms of *symbols* with dedicated names, and will appear in the linker map file under these names:

Operator	Symbol
section_begin(sec)	sec\$\$Base
section_end(sec)	sec\$\$Limit
section_size(sec)	sec\$\$Length

Table 20: Section operators and their symbols

Note that the linker will not necessarily place sections with the same name consecutively when these operators are not used. Using one of these operators (or the equivalent symbols) will cause the linker to behave as if the sections were in a named block. This is to assure that the sections are placed consecutively, so that the operators can be assigned meaningful values. If this is in conflict with the section placement as specified in the linker configuration file, the linker will issue an error.

#### Example

```
In this example, the type of the __section_begin operator is void __huge *.
#pragma section="MYSECTION"
...
section_start_address = __section_begin("MYSECTION");
```

See also *section*, page 318, and *location*, page 312.

#### **RELAXATIONS TO STANDARD C**

This section lists and briefly describes the relaxation of some Standard C issues and also some useful but minor syntax extensions:

Arrays of incomplete types

An array can have an incomplete struct, union, or enum type as its element type. The types must be completed before the array is used (if it is), or by the end of the compilation unit (if it is not).

Forward declaration of enum types

The extensions allow you to first declare the name of an enum and later resolve it by specifying the brace-enclosed list.

Accepting missing semicolon at the end of a struct or union specifier
 A warning—instead of an error—is issued if the semicolon at the end of a struct or union specifier is missing.

• Null and void

In operations on pointers, a pointer to void is always implicitly converted to another type if necessary, and a null pointer constant is always implicitly converted to a null pointer of the right type if necessary. In Standard C, some operators allow this kind of behavior, while others do not allow it.

• Casting pointers to integers in static initializers

In an initializer, a pointer constant value can be cast to an integral type if the integral type is large enough to contain it. For more information about casting pointers, see *Casting*, page 284.

• Taking the address of a register variable

In Standard C, it is illegal to take the address of a variable specified as a register variable. The compiler allows this, but a warning is issued.

• long float means double

The type long float is accepted as a synonym for double.

• Repeated typedef declarations

Redeclarations of typedef that occur in the same scope are allowed, but a warning is issued.

Mixing pointer types

Assignment and pointer difference is allowed between pointers to types that are interchangeable but not identical; for example, unsigned char \* and char \*. This includes pointers to integral types of the same size. A warning is issued.

Assignment of a string constant to a pointer to any kind of character is allowed, and no warning is issued.

Non-top level const

Assignment of pointers is allowed in cases where the destination type has added type qualifiers that are not at the top level (for example, int \*\* to int const \*\*). Comparing and taking the difference of such pointers is also allowed.

• Non-1value arrays

A non-lvalue array expression is converted to a pointer to the first element of the array when it is used.

Comments at the end of preprocessor directives

This extension, which makes it legal to place text after preprocessor directives, is enabled unless the strict Standard C mode is used. The purpose of this language extension is to support compilation of legacy code; we do *not* recommend that you write new code in this fashion.

An extra comma at the end of enum lists

Placing an extra comma is allowed at the end of an enum list. In strict Standard C mode, a warning is issued.

• A label preceding a }

In Standard C, a label must be followed by at least one statement. Therefore, it is illegal to place the label at the end of a block. The compiler allows this, but issues a warning.

Note that this also applies to the labels of switch statements.

• Empty declarations

An empty declaration (a semicolon by itself) is allowed, but a remark is issued (provided that remarks are enabled).

• Single-value initialization

Standard C requires that all initializer expressions of static arrays, structs, and unions are enclosed in braces.

Single-value initializers are allowed to appear without braces, but a warning is issued. The compiler accepts this expression:

```
struct str
{
   int a;
} x = 10;
```

• Declarations in other scopes

External and static declarations in other scopes are visible. In the following example, the variable y can be used at the end of the function, even though it should only be visible in the body of the if statement. A warning is issued.

```
int test(int x)
{
   if (x)
   {
     extern int y;
     y = 1;
   }
   return y;
}
```

Expanding function names into strings with the function as context

Use any of the symbols \_\_func\_\_ or \_\_FUNCTION\_\_ inside a function body to make the symbol expand into a string that contains the name of the current function.

Use the symbol \_\_PRETTY\_FUNCTION\_\_ to also include the parameter types and return type. The result might, for example, look like this if you use the \_\_PRETTY\_FUNCTION\_\_ symbol:

"void func(char)"

These symbols are useful for assertions and other trace utilities and they require that language extensions are enabled, see -e, page 225.

- Static functions in function and block scopes
   Static functions may be declared in function and block scopes. Their declarations are moved to the file scope.
- Numbers scanned according to the syntax for numbers

Numbers are scanned according to the syntax for numbers rather than the pp-number syntax. Thus, 0x123e+1 is scanned as three tokens instead of one valid token. (If the --strict option is used, the pp-number syntax is used instead.)

IAR C language extensions

# Using C++

IAR Systems supports the C++ language. You can choose between these standards: Standard C++, the industry-standard Embedded C++, and Extended Embedded C++. This chapter describes what you need to consider when using the C++ language.

#### Overview—EC++ and EEC++

Embedded C++ is a proper subset of the ISO/IEC C++ standard which is intended for embedded systems programming. It was defined by an industry consortium, the Embedded C++ Technical Committee. Performance and portability are particularly important in embedded systems development, which was considered when defining the language. EC++ offers the same object-oriented benefits as C++, but without some features that can increase code size and execution time in ways that are hard to predict.

#### **EMBEDDED C++**

The following C++ features are supported:

- Classes, which are user-defined types that incorporate both data structure and behavior; the essential feature of inheritance allows data structure and behavior to be shared among classes
- Polymorphism, which means that an operation can behave differently on different classes, is provided by virtual functions
- Overloading of operators and function names, which allows several operators or functions with the same name, provided that their argument lists are sufficiently different
- Type-safe memory management using the operators new and delete
- Inline functions, which are indicated as particularly suitable for inline expansion.

C++ features that are excluded are those that introduce overhead in execution time or code size that are beyond the control of the programmer. Also excluded are features added very late before Standard C++ was defined. Embedded C++ thus offers a subset of C++ which is efficient and fully supported by existing development tools.

Embedded C++ lacks these features of C++:

- Templates
- Multiple and virtual inheritance
- Exception handling

- Runtime type information
- New cast syntax (the operators dynamic\_cast, static\_cast, reinterpret cast, and const cast)
- Namespaces
- The mutable attribute.

The exclusion of these language features makes the runtime library significantly more efficient. The Embedded C++ library furthermore differs from the full C++ library in that:

- The standard template library (STL) is excluded
- Streams, strings, and complex numbers are supported without the use of templates
- Library features which relate to exception handling and runtime type information (the headers except, stdexcept, and typeinfo) are excluded.

**Note:** The library is not in the std namespace, because Embedded C++ does not support namespaces.

#### **EXTENDED EMBEDDED C++**

IAR Systems' Extended EC++ is a slightly larger subset of C++ which adds these features to the standard EC++:

- Full template support
- Multiple and virtual inheritance
- Namespace support
- The mutable attribute
- The cast operators static\_cast, const\_cast, and reinterpret\_cast.

All these added features conform to the C++ standard.

To support Extended EC++, this product includes a version of the standard template library (STL), in other words, the C++ standard chapters utilities, containers, iterators, algorithms, and some numerics. This STL is tailored for use with the Extended EC++ language, which means no exceptions, no multiple inheritance, and no support for runtime type information (rtti). Moreover, the library is not in the std namespace.

**Note:** A module compiled with Extended EC++ enabled is fully link-compatible with a module compiled without Extended EC++ enabled.

### Overview—Standard C++

The IAR C++ implementation fully complies with the ISO/IEC 1488:2003 C++ standard. In this guide, this standard is referred to as Standard C++.

The main reason for using Standard C++ instead of EC++ or EEC++ is when there is a need for either:

- Exception support
- Runtime type information (RTTI) support
- The standard C++ library (the EC++ library is a stripped version of the C++ library where streams and strings are not templates).

If code size is important and your application does not need any of these features, EC++ (or EEC++) is the better choice.

#### MODES FOR EXCEPTIONS AND RTTI SUPPORT

Both exceptions and runtime type information result in increased code size simply by being included in your application. You might want to disable either or both of these features to avoid this increase:

- Support for runtime type information constructs can be disabled by using the compiler option --no\_rtti
- Support for exceptions can be disabled by using the compiler option
   --no\_exceptions

Even if support is enabled while compiling, the linker can avoid including the extra code and tables in the final application. If no part of your application actually throws an exception, the code and tables supporting the use of exceptions are not included in the application code image. Also, if dynamic runtime type information constructs (dynamic\_cast/typeid) are not used with polymorphic types, the objects needed to support them are not included in the application code image. To control this behavior, use the linker options --no\_exceptions, --force\_exceptions, and --no\_dynamic\_rtti\_elimination.

#### Disabling exception support

When you use the compiler option --no\_exceptions, the following will generate a compiler error:

- throw expressions
- try-catch statements
- Exception specifications on function definitions.

In addition, the extra code and tables needed to handle destruction of objects with auto storage duration when an exception is propagated through a function will not be generated when the compiler option --no\_exceptions is used.

All functionality in system headers not directly involving exceptions is supported when the compiler option --no\_exceptions is used.

The linker will produce an error if you try to link C++ modules compiled with exception support with modules compiled without exception support

For more information, see --no\_exceptions, page 234.

#### Disabling RTTI support

When you use the compiler option --no\_rtti, the following will generate a compiler error:

- The typeid operator
- The dynamic\_cast operator.

**Note:** If --no\_rtti is used but exception support is enabled, most RTTI support is still included in the compiler output object file because it is needed for exceptions to work.

For more information, see --no\_rtti, page 236.

#### **EXCEPTION HANDLING**

Exception handling can be divided into three parts:

- Exception raise mechanisms—in C++ they are the throw and rethrow expressions.
- Exception catch mechanisms—in C++ they are the try-catch statements, the
  exception specifications for a function, and the implicit catch to prevent an
  exception leaking out from main.
- Information about currently active functions—if they have try-catch statements
  and the set of auto objects whose destructors need to be run if an exception is
  propagated through the function.

When an exception is raised, the function call stack is unwound, function by function, block by block. For each function or block, the destructors of auto objects that need destruction are run, and a check is made whether there is a catch handler for the exception. If there is, the execution will continue from that catch handler.

An application that mixes C++ code with assembler and C code, and that throws exceptions from one C++ function to another via assembler routines and C functions must use the linker option --exception\_tables with the argument unwind.

#### The implementation of exceptions

Exceptions are implemented using a table method. For each function, the tables describe:

- How to unwind the function, that is, how to find its caller on the stack and restore registers that need restoring
- Which catch handlers that exist in the function
- Whether the function has an exception specification and which exceptions it allows to propagate
- The set of auto objects whose destructors must be run.

When an exception is raised, the runtime will proceed in two phases. The first phase will use the exception tables to search the stack for a function invocation containing a catch handler or exception specification that would cause stack unwinding to halt at that point. Once this point is found, the second phase is entered, doing the actual unwinding, and running the destructors of auto objects where that is needed.

The table method results in virtually no overhead in execution time or RAM usage when an exception is not actually thrown. It does incur a significant penalty in read-only memory usage for the tables and the extra code, and throwing and catching an exception is a relatively expensive operation.

The destruction of auto objects when the stack is being unwound as a result of an exception is implemented in code separated from the code that handles the normal operation of a function. This code, together with the code in catch handlers, is placed in a separate section (.exc.text) from the normal code (normally placed in .text). In some cases, for instance when there is fast and slow ROM memory, it can be advantageous to select on this difference when placing sections in the linker configuration file.

## **Enabling support for C++ and variants**



In the compiler, the default language is C.

To compile files written in Standard C++, you must use the --c++ compiler option. See --c++, page 219.

To compile files written in Embedded C++, you must use the --ec++ compiler option. See --ec++, page 225.

To take advantage of *Extended* Embedded C++ features in your source code, you must use the --eec++ compiler option. See --eec++, page 225.



To enable EC++ EEC++, or C++ in the IDE, choose **Project>Options>C/C++ Compiler>Language** and select the appropriate standard.

## C++ and EC++ feature descriptions

When you write C++ source code for the IAR C/C++ Compiler for ARM, you must be aware of some benefits and some possible quirks when mixing C++ features—such as classes, and class members—with IAR language extensions, such as IAR-specific attributes.

#### **USING IAR ATTRIBUTES WITH CLASSES**

Static data members of C++ classes are treated the same way global variables are, and can have any applicable IAR type, and object attribute.

Member functions are in general treated the same way free functions are, and can have any applicable IAR type and object attributes. Virtual member functions can only have attributes that are compatible with default function pointers, and constructors and destructors cannot have any such attributes.

The location operator @ and the #pragma location directive can be used on static data members and with all member functions.

#### Example

```
class MyClass
{
public:
    // Locate a static variable in __memattr memory at address 60
    static __no_init int mI @ 60;

    // A static Thumb function
    static __thumb void F();

    // A Thumb function
    __thumb void G();

    // Interworking assumed
    virtual __arm void ArmH();

    // Interworking assumed
    virtual __thumb void ThumbH();

    // Locate a virtual function into SPECIAL
    virtual void M() const volatile @ "SPECIAL";
};
```

#### **FUNCTION TYPES**

A function type with extern "C" linkage is compatible with a function that has C++ linkage.

#### Example

#### USING STATIC CLASS OBJECTS IN INTERRUPTS

If interrupt functions use static class objects that need to be constructed (using constructors) or destroyed (using destructors), your application will not work properly if the interrupt occurs before the objects are constructed, or after the objects are destroyed.

To avoid this, make sure that these interrupts are not enabled until the static objects have been constructed, and are disabled when returning from main or calling exit. For information about system startup, see *System startup and termination*, page 103.

Function local static class objects are constructed the first time execution passes through their declaration, and are destroyed when returning from main or when calling exit.

#### **USING NEW HANDLERS**

To handle memory exhaustion, you can use the set\_new\_handler function.

If you do not call <code>set\_new\_handler</code>, or call it with a NULL new handler, and operator new fails to allocate enough memory, operator new will throw <code>std::bad\_alloc</code> if exceptions are enabled. If exceptions are not enabled, operator new will instead call abort.

If you call set\_new\_handler with a non-NULL new handler, the provided new handler will be called by operator new if the operator new fails to allocate enough memory. The new handler must then make more memory available and return, or abort execution in some manner. If exceptions are enabled, the new handler can also throw a std::bad\_alloc exception. The nothrow variant of operator new will only return NULL in the presence of a new handler if exceptions are enabled and the new handler throws std::bad\_alloc.

#### **TEMPLATES**

C++ and Extended EC++ support templates according to the C++ standard, but not the export keyword. The implementation uses a two-phase lookup which means that the keyword typename must be inserted wherever needed. Furthermore, at each use of a template, the definitions of all possible templates must be visible. This means that the definitions of all templates must be in include files or in the actual source file.

#### **DEBUG SUPPORT IN C-SPY**

C-SPY® has debug support for some features in C++.

- C-SPY has built-in display support for the STL containers. The logical structure of
  containers is presented in the watch views in a comprehensive way that is easy to
  understand and follow.
- You can make C-SPY stop at a throw statement or if a raised exception does not have any corresponding catch statement.

For more information about this, see the *C-SPY® Debugging Guide for ARM®*.

## **EEC++** feature description

This section describes features that distinguish Extended EC++ from EC++.

#### **TEMPLATES**

#### The standard template library

The STL (standard template library) delivered with the product is tailored for Extended EC++, see *Extended Embedded C*++, page 154.

#### **VARIANTS OF CAST OPERATORS**

In Extended EC++ these additional variants of C++ cast operators can be used:

```
const_cast<to>(from)
static_cast<to>(from)
reinterpret_cast<to>(from)
```

#### **MUTABLE**

The mutable attribute is supported in Extended EC++. A mutable symbol can be changed even though the whole class object is const.

#### **NAMESPACE**

The namespace feature is only supported in *Extended* EC++. This means that you can use namespaces to partition your code. Note, however, that the library itself is not placed in the std namespace.

#### THE STD NAMESPACE

The std namespace is not used in either standard EC++ or in Extended EC++. If you have code that refers to symbols in the std namespace, simply define std as nothing; for example:

```
#define std
```

You must make sure that identifiers in your application do not interfere with identifiers in the runtime library.

## EC++ and C++ language extensions

When you use the compiler in any C++ mode and enable IAR language extensions, the following C++ language extensions are available in the compiler:

• In a friend declaration of a class, the class keyword can be omitted, for example:

• Constants of a scalar type can be defined within classes, for example:

According to the standard, initialized static data members should be used instead.

• In the declaration of a class member, a qualified name can be used, for example:

```
struct A
{
  int A::F(); // Possible when using IAR language extensions
  int G(); // According to the standard
};
```

It is permitted to use an implicit type conversion between a pointer to a function
with C linkage (extern "C") and a pointer to a function with C++ linkage
(extern "C++"), for example:

According to the standard, the pointer must be explicitly converted.

• If the second or third operands in a construction that contains the ? operator are string literals or wide string literals (which in C++ are constants), the operands can be implicitly converted to char \* or wchar\_t \*, for example:

- Default arguments can be specified for function parameters not only in the top-level function declaration, which is according to the standard, but also in typedef declarations, in pointer-to-function function declarations, and in pointer-to-member function declarations.
- In a function that contains a non-static local variable and a class that contains a non-evaluated expression (for example a sizeof expression), the expression can reference the non-static local variable. However, a warning is issued.

An anonymous union can be introduced into a containing class by a typedef name.
 It is not necessary to first declare the union. For example:

```
typedef union
{
  int i,j;
} U; // U identifies a reusable anonymous union.

class A
{
public:
  U; // OK -- references to A::i and A::j are allowed.
};
```

In addition, this extension also permits *anonymous classes* and *anonymous structs*, as long as they have no C++ features (for example, no static data members or member functions, and no non-public members) and have no nested types other than other anonymous classes, structs, or unions. For example:

```
struct A
{
   struct
   {
     int i,j;
   }; // OK -- references to A::i and A::j are allowed.
};
```

• The friend class syntax allows nonclass types as well as class types expressed through a typedef without an elaborated type name. For example:

**Note:** If you use any of these constructions without first enabling language extensions, errors are issued.

EC++ and C++ language extensions

# **Application-related** considerations

This chapter discusses a selected range of application issues related to developing your embedded application.

Typically, this chapter highlights issues that are not specifically related to only the compiler or the linker.

## **Output format considerations**

The linker produces an absolute executable image in the ELF/DWARF object file format.

You can use the IAR ELF Tool—ielftool—to convert an absolute ELF image to a format more suitable for loading directly to memory, or burning to a PROM or flash memory etc.

ielftool can produce these output formats:

- Plain binary
- Motorola S-records
- Intel hex.

**Note:** ielftool can also be used for other types of transformations, such as filling and calculating checksums in the absolute image.

The source code for ielftool is provided in the arm/src directory. For more information about ielftool, see *The IAR ELF Tool—ielftool*, page 412.

## Stack considerations

The stack is used by functions to store variables and other information that is used locally by functions, as described in the chapter *Data storage*. It is a continuous block of memory pointed to by the processor stack pointer register SP.

The data section used for holding the stack is called CSTACK. The system startup code initializes the stack pointer to the end of the stack.

#### STACK SIZE CONSIDERATIONS

The compiler uses the internal data stack for a variety of user application operations, and the required stack size depends heavily on the details of these operations. If the given stack size is too large, RAM will be wasted. If the given stack size is too small, two things can happen, depending on where in memory you located your stack. Both alternatives are likely to result in application failure. Either variable storage will be overwritten, leading to undefined behavior, or the stack will fall outside of the memory area, leading to an abnormal termination of your application. Because the second alternative is easier to detect, you should consider placing your stack so that it grows toward the end of the memory.

For more information about the stack size, see *Setting up the stack*, page 81, and *Saving stack space and RAM memory*, page 193.

#### **STACK ALIGNMENT**

The default cstartup code automatically initializes all stacks to an 8-byte aligned address.

For more information about aligning the stack, see *Calling convention*, page 132 and more specifically *Special registers*, page 134 and *Stack parameters and layout*, page 135.

#### **EXCEPTION STACKS**

The ARM architecture supports five exception modes which are entered when different exceptions occur. Each exception mode has its own stack to avoid corrupting the System/User mode stack.

The table shows proposed stack names for the various exception stacks, but any name can be used:

Processor mode	Proposed stack section name	Description
Supervisor	SVC_STACK	Operating system stack.
IRQ	IRQ_STACK	Stack for general-purpose (IRQ) interrupt handlers.
FIQ	FIQ_STACK	Stack for high-speed (FIQ) interrupt handlers.
Undefined	UND_STACK	Stack for undefined instruction interrupts. Supports software emulation of hardware coprocessors and instruction set extensions.

Table 21: Exception stacks

Processor mode	Proposed stack section name	Description
Abort	ABT_STACK	Stack for instruction fetch and data access memory abort interrupt handlers.

Table 21: Exception stacks (Continued)

For each processor mode where a stack is needed, a separate stack pointer must be initialized in your startup code, and section placement should be done in the linker configuration file. The IRQ and FIQ stacks are the only exception stacks which are preconfigured in the supplied cstartup.s and lnkarm.icf files, but other exception stacks can easily be added.

Cortex-M does not have individual exception stacks. By default, all exception stacks are placed in the CSTACK section.



To view any of these stacks in the Stack window available in the IDE, these preconfigured section names must be used instead of user-defined section names.

## **Heap considerations**

The heap contains dynamic data allocated by use of the C function malloc (or one of its relatives) or the C++ operator new.

If your application uses dynamic memory allocation, you should be familiar with:

- Linker sections used for the heap
- Allocating the heap size, see Setting up the heap, page 82.

The memory allocated to the heap is placed in the section HEAP, which is only included in the application if dynamic memory allocation is actually used.



#### Heap size and standard I/O

If you excluded FILE descriptors from the DLIB runtime environment, as in the normal configuration, there are no input and output buffers at all. Otherwise, as in the full configuration, be aware that the size of the input and output buffers is set to 512 bytes in the stdio library header file. If the heap is too small, I/O will not be buffered, which is considerably slower than when I/O is buffered. If you execute the application using the simulator driver of the IAR C-SPY® Debugger, you are not likely to notice the speed penalty, but it is quite noticeable when the application runs on an ARM core. If you use the standard I/O library, you should set the heap size to a value which accommodates the needs of the standard I/O buffer.

## Interaction between the tools and your application

The linking process and the application can interact symbolically in four ways:

- Creating a symbol by using the ILINK command line option --define\_symbol.
   ILINK will create a public absolute constant symbol that the application can use as a label, as a size, as setup for a debugger, etc.
- Creating an exported configuration symbol by using the command line option
   --config\_def or the configuration directive define symbol, and exporting the symbol using the export symbol directive. ILINK will create a public absolute constant symbol that the application can use as a label, as a size, as setup for a debugger, etc.

One advantage of this symbol definition is that this symbol can also be used in expressions in the configuration file, for example to control the placement of sections into memory ranges.

- Using the compiler operators \_\_section\_begin, \_\_section\_end, or \_\_section\_size, or the assembler operators SFB, SFE, or SIZEOF on a named section or block. These operators provide access to the start address, end address, and size of a contiguous sequence of sections with the same name, or of a linker block specified in the linker configuration file.
- The command line option --entry informs ILINK about the start label of the application. It is used by ILINK as a root symbol and to inform the debugger where to start execution.

The following lines illustrate how to use these mechanisms. Add these options to your command line:

```
--define_symbol NrOfElements=10
--config_def HeapSize=1024
```

The linker configuration file can look like this:

```
define memory Mem with size = 4G;
define region ROM = Mem:[from 0x000000 size 0x10000];
define region RAM = Mem:[from 0x200000 size 0x100000];

/* Export of symbol */
export symbol HeapSize;

/* Setup a heap area witha size defined by an ILINK option */
define block MyHEAP with size = HeapSize, alignment = 8 {};
place in RAM { block MyHEAP };
```

Add these lines to your application source code:

```
#include <stdlib.h>
/* Use symbol defined by ILINK option to dynamically allocate an
array of elements with specified size. The value takes the form
of a label.
* /
extern int NrOfElements;
typedef char Elements;
Elements *GetElementArray()
 return malloc(sizeof(Elements) * (long) &NrOfElements);
/* Use a symbol defined by ILINK option, a symbol that in the
 * configuration file was made available to the application.
extern char HeapSize;
/* Declare the section that contains the heap. */
#pragma section = "MYHEAP"
char *MyHeap()
  /* First get start of statically allocated section, */
 char *p = __section_begin("MYHEAP");
  /* ...then we zero it, using the imported size. */
  for (int i = 0; i < (int) &HeapSize; ++i)
   p[i] = 0;
 }
 return p;
```

### **Checksum calculation**

The IAR ELF Tool—ielftool—fills specific ranges of memory with a pattern and then calculates a checksum for those ranges. The calculated checksum replaces the value of an existing symbol in the input ELF image. The application can then verify that the ranges did not change.

To use checksumming to verify the integrity of your application, you must:

- Reserve a place, with an associated name and size, for the checksum calculated by
- Choose a checksum algorithm, set up ielftool for it, and include source code for the algorithm in your application
- Decide what memory ranges to verify and set up both ielftool and the source code for it in your application source code.



Note: To set up ielftool in the IDE, choose Project>Options>Linker>Checksum.

#### **CALCULATING A CHECKSUM**

In this example, a checksum is calculated for ROM memory at 0x8002 up to 0x8FFF and the 2-byte calculated checksum is placed at 0x8000.

#### Creating a place for the calculated checksum

You can create a place for the calculated checksum in two ways; by creating a global C/C++ or assembler constant symbol with a proper size, residing in a specific section (in this example .checksum), or by using the linker option --place\_holder.

For example, to create a 2-byte space for the symbol \_\_checksum in the section .checksum, with alignment 4:

```
--place_holder __checksum, 2, .checksum, 4
```

**Note:** The .checksum section will only be included in your application if the section appears to be needed. If the checksum is not needed by the application itself, you can use the linker option --keep=\_\_checksum or the linker directive keep to force the section to be included.

To place the .checksum section, you must modify the linker configuration file. It can look like this (note the handling of the block CHECKSUM):

#### **Running ielftool**

To calculate the checksum, run ielftool:

```
ielftool --fill=0x00;0x8000-0x8FFF
--checksum=__checksum:2,crc16;0x8000-0x8FFF sourceFile.out
destinationFile.out
```

To calculate a checksum you also must define a fill operation. In this example, the fill pattern  $0 \times 0$  is used. The checksum algorithm used is crc16.

Note that ielftool needs an unstripped input ELF image. If you use the --strip linker option, remove it and use the --strip ielftool option instead.

#### ADDING A CHECKSUM FUNCTION TO YOUR SOURCE CODE

To check the value of the ielftool generated checksum, it must be compared with a checksum that your application calculated. This means that you must add a function for checksum calculation (that uses the same algorithm as ielftool) to your application source code. Your application must also include a call to this function.

#### A function for checksum calculation

This function—a slow variant but with small memory footprint—uses the crc16 algorithm:

```
unsigned short SlowCrc16 (unsigned short sum,
                         unsigned char *p,
                         unsigned int len)
 while (len--)
   int i;
   unsigned char byte = *(p++);
    for (i = 0; i < 8; ++i)
      unsigned long oSum = sum;
      sum <<= 1;
      if (byte & 0x80)
       sum |= 1;
      if (oSum & 0x8000)
       sum ^= 0x1021;
      byte <<= 1;
    }
 }
 return sum;
}
```

You can find the source code for the checksum algorithms in the arm\src\linker directory of your product installation.

#### Checksum calculation

This code gives an example of how the checksum can be calculated:

```
/* Start and end of the checksum range */
unsigned long ChecksumStart = 0x8000+2;
unsigned long ChecksumEnd = 0x8FFF;

/* The checksum calculated by ielftool
 * (note that it lies on address 0x8000)
 */
extern unsigned short const __checksum;

void TestChecksum()
{
  unsigned short calc = 0;
  unsigned char zeros[2] = {0, 0};
```

#### THINGS TO REMEMBER

When calculating a checksum, you must remember that:

- The checksum must be calculated from the lowest to the highest address for every memory range
- Each memory range must be verified in the same order as defined
- It is OK to have several ranges for one checksum
- If several checksums are used, you should place them in sections with unique names and use unique symbol names
- If the a slow function variant is used, you must make a final call to the checksum calculation with as many bytes (with the value 0x00) as there are bytes in the checksum.

For more information, see also *The IAR ELF Tool—ielftool*, page 412.

#### C-SPY CONSIDERATIONS

By default, a symbol that you have allocated in memory by using the linker option <code>--place\_holder</code> is considered by C-SPY to be of the type <code>int</code>. If the size of the checksum is different than the size of an <code>int</code>, you can change the display format of the checksum symbol to match its size.



In the C-SPY Watch window, select the symbol and choose **Show As** from the context menu. Choose the display format that matches the size of the checksum symbol.

## Linker optimizations

#### VIRTUAL FUNCTION ELIMINATION

Virtual Function Elimination (VFE) is a linker optimization that removes unneeded virtual functions and dynamic runtime type information.

In order for Virtual Function Elimination to work, all relevant modules must provide information about virtual function table layout, which virtual functions are called, and for which classes dynamic runtime type information is needed. If one or more modules do not provide this information, a warning is generated by the linker and Virtual Function Elimination is not performed.

If you know that modules that lack such information do not perform any virtual function calls and do not define any virtual function tables, you can use the --vfe=forced linker option to enable Virtual Function Elimination anyway.

Currently, tools from IAR Systems and from RealView provide the information needed for Virtual Function Elimination in a way that the linker can use.

Note that you can disable Virtual Function Elimination entirely by using the --no\_vfe linker option. In this case, no warning will be issued for modules that lack VFE information.

For more information, see --vfe, page 273 and --no\_vfe, page 268.

## **AEABI** compliance

The IAR build tools for ARM support the Embedded Application Binary Interface for ARM, AEABI, defined by ARM Limited. This interface is based on the Intel IA64 ABI interface. The advantage of adhering to AEABI is that any such module can be linked with any other AEABI-compliant module, even modules produced by tools provided by other vendors.

The IAR build tools for ARM support the following parts of the AEABI:

AAPCS Procedure Call Standard for the ARM architecture

CPPABI C++ ABI for the ARM architecture (EC++ parts only)

AAELF ELF for the ARM architecture

AADWARF DWARF for the ARM architecture

RTABI Runtime ABI for the ARM architecture

CLIBABI C library ABI for the ARM architecture

The IAR build tools only support a *bare metal* platform, that is a ROM-based system that lacks an explicit operating system.

#### Note that:

- The AEABI is specified for C89 only
- The IAR build tools only support using the default and C locales
- The AEABI does not specify C++ library compatibility
- Neither the size of an enum or of wchar\_t is constant in the AEABI.

If AEABI compliance is enabled, almost all optimizations performed in the system header files are turned off, and certain preprocessor constants become real constant variables instead.

## LINKING AEABI-COMPLIANT MODULES USING THE IAR ILINK LINKER

When building an application using the IAR ILINK Linker, the following types of modules can be combined:

- Modules produced using IAR build tools, both AEABI-compliant modules as well as modules that are not AEABI-compliant
- AEABI-compliant modules produced using build tools from another vendor.

**Note:** To link a module produced by a compiler from another vendor, extra support libraries from that vendor might be required.

The IAR ILINK Linker automatically chooses the appropriate standard C/C++ libraries to use based on attributes from the object files. Imported object files might not have all these attributes. Therefore, you might need to help ILINK choose the standard library by verifying one or more of the following details:

- The used CPU by specifying the --cpu linker option
- If full I/O is needed; make sure to link with a Full library configuration in the standard library
- Explicitly specify runtime library file(s), possibly in combination with the
   --no\_library\_search linker option.

When linking, you should also consider virtual function elimination, see *Virtual Function Elimination*, page 174.

## LINKING AEABI-COMPLIANT MODULES USING A THIRD-PARTY LINKER

If you have a module produced using the IAR C/C++ Compiler and you plan to link that module using a linker from a different vendor, that module must be AEABI-compliant, see *Enabling AEABI compliance in the compiler*, page 176.

In addition, if that module uses any of the IAR-specific compiler extensions, you must make sure that those features are also supported by the tools from the other vendor. Note specifically:

- Support for the following extensions must be verified: #pragma pack, \_\_no\_init, \_\_root, and \_\_ramfunc
- The following extensions are harmless to use: #pragma location/@, \_\_arm, \_\_thumb, \_\_swi, \_\_irq, \_\_fiq, and \_\_nested.

#### **ENABLING AEABI COMPLIANCE IN THE COMPILER**

You can enable AEABI compliance in the compiler by setting the --aeabi option. In this case, you must also use the --guard\_calls option.



In the IDE, use the **Project>Options>C/C++ Compiler>Extra Options** page to specify the --aeabi and --guard\_calls options.



On the command line, use the options --aeabi and --guard\_calls to enable AEABI support in the compiler.

Alternatively, to enable support for AEABI for a specific system header file, you must define the preprocessor symbol \_AEABI\_PORTABILITY\_LEVEL to non-zero prior to including a system header file, and make sure that the symbol AEABI\_PORTABLE is set to non-zero after the inclusion of the header file:

```
#define _AEABI_PORTABILITY_LEVEL 1
#undef _AEABI_PORTABLE
#include <header.h>
#ifndef _AEABI_PORTABLE
    #error "header.h not AEABI compatible"
#endif
```

## **CMSIS** integration

The arm\CMSIS subdirectory contains CMSIS (ARM Cortex Microcontroller Software Interface Standard) and CMSIS DSP header and library files, and documentation. For more information about CMSIS, see http://www.arm.com/cmsis.

The special header file inc\c\cmsis\_iar.h is provided as an CMSIS adaptation of the current version of the IAR C/C++ Compiler.

#### **CMSIS DSP LIBRARY**

IAR Embedded Workbench comes with prebuilt CMSIS DSP libraries in the arm\CMSIS\Lib\IAR directory. The names of the library files are constructed in this way:

```
iar\_cortexM<0|3|4><1|b>[v]\_math.a
```

where <0|3|4> selects the Cortex–M variant, <1|b> selects the byte order, and [v] indicates that the library is built for FPU (Cortex–M4 only).

#### **CUSTOMIZING THE CMSIS DSP LIBRARY**

The source code of the CMSIS DSP library is provided in the arm\CMSIS\DSP\_Lib\Source directory. You can find an IAR Embedded Workbench project which is prepared for building a customized DSP library in the arm\CMSIS\DSP\_Lib\Source\IAR directory.



#### **BUILDING WITH CMSIS ON THE COMMAND LINE**

This section contains examples of command lines when building your CMSIS-compatible application.

#### CMSIS only (that is without the DSP library)

iccarm -I \$EW\_DIR\$\arm\CMSIS\Include

#### With the DSP library, for Cortex-M4, little-endian, and with FPU

```
iccarm --endian=little --cpu=Cortex-M4 --fpu=VFPv4_sp -I
$EW_DIR$\arm\CMSIS\Include -D ARM_MATH_CM4
```

ilinkarm \$EW\_DIR\$\arm\CMSIS\Lib\IAR\iar\_cortexM4lv\_math.a

#### With the DSP library, for Cortex-M3, and little-endian

iccarm --endian=little --cpu=Cortex-M3 -I
\$EW\_DIR\$\arm\CMSIS\Include -D ARM\_MATH\_CM3

ilinkarm \$EW\_DIR\$\arm\CMSIS\Lib\IAR\iar\_cortexM31\_math.a



#### **BUILDING WITH CMSIS IN IAR EMBEDDED WORKBENCH**

Choose **Project>Options>General Options>Library Configuration** to enable CMSIS support.

When enabled, CMSIS include paths and the DSP library will automatically be used. For more information, see the *IDE Project Management and Building Guide for ARM*®.

# Efficient coding for embedded applications

For embedded systems, the size of the generated code and data is very important, because using smaller external memory or on-chip memory can significantly decrease the cost and power consumption of a system.

The topics discussed are:

- Selecting data types
- Controlling data and function placement in memory
- Controlling compiler optimizations
- Facilitating good code generation.

As a part of this, the chapter also demonstrates some of the more common mistakes and how to avoid them, and gives a catalog of good coding techniques.

## Selecting data types

For efficient treatment of data, you should consider the data types used and the most efficient placement of the variables.

#### **USING EFFICIENT DATA TYPES**

The data types you use should be considered carefully, because this can have a large impact on code size and code speed.

- Use int or long instead of char or short whenever possible, to avoid sign
  extension or zero extension. In particular, loop indexes should always be int or
  long to minimize code generation. Also, in Thumb mode, accesses through the
  stack pointer (SP) is restricted to 32-bit data types, which further emphasizes the
  benefits of using one of these data types.
- Use unsigned data types, unless your application really requires signed values.
- Be aware of the costs of using 64-bit data types, such as double and long long.

- Bitfields and packed structures generate large and slow code.
- Using floating-point types on a microprocessor without a math coprocessor is very inefficient, both in terms of code size and execution speed.
- Declaring a pointer to const data tells the calling function that the data pointed to will not change, which opens for better optimizations.

For information about representation of supported data types, pointers, and structures types, see the chapter *Data representation*.

#### **FLOATING-POINT TYPES**

Using floating-point types on a microprocessor without a math coprocessor is very inefficient, both in terms of code size and execution speed. Thus, you should consider replacing code that uses floating-point operations with code that uses integers, because these are more efficient.

The compiler supports two floating-point formats—32 and 64 bits. The 32-bit floating-point type float is more efficient in terms of code size and execution speed. However, the 64-bit format double supports higher precision and larger numbers.

Unless the application requires the extra precision that 64-bit floating-point numbers give, we recommend using 32-bit floating-point numbers instead.

By default, a *floating-point constant* in the source code is treated as being of the type double. This can cause innocent-looking expressions to be evaluated in double precision. In the example below a is converted from a float to a double, the double constant 1.0 is added and the result is converted back to a float:

```
double Test(float a)
{
    return a + 1.0;
}
```

To treat a floating-point constant as a float rather than as a double, add the suffix f to it, for example:

```
double Test(float a)
{
    return a + 1.0f;
}
```

For more information about floating-point types, see Floating-point types, page 282.

#### **ALIGNMENT OF ELEMENTS IN A STRUCTURE**

The ARM core requires that data in memory must be aligned. Each element in a structure must be aligned according to its specified type requirements. This means that the compiler might need to insert *pad bytes* to keep the alignment correct.

There are situations when this can be a problem:

- There are external demands; for example, network communication protocols are usually specified in terms of data types with no padding in between
- You need to save data memory.

For information about alignment requirements, see *Alignment*, page 275.

There are two ways to solve the problem:

- Use the #pragma pack directive or the \_\_packed data type attribute for a tighter layout of the structure. The drawback is that each access to an unaligned element in the structure will use more code.
- Write your own customized functions for packing and unpacking structures. This is
  a more portable way, which will not produce any more code apart from your
  functions. The drawback is the need for two views on the structure data—packed
  and unpacked.

For more information about the #pragma pack directive, see *pack*, page 315.

#### **ANONYMOUS STRUCTS AND UNIONS**

When a structure or union is declared without a name, it becomes anonymous. The effect is that its members will only be seen in the surrounding scope.

Anonymous structures are part of the C++ language; however, they are not part of the C standard. In the IAR C/C++ Compiler for ARM they can be used in C if language extensions are enabled.



In the IDE, language extensions are enabled by default.



Use the -e compiler option to enable language extensions. See -e, page 225, for additional information.

#### Example

In this example, the members in the anonymous union can be accessed, in function F, without explicitly specifying the union name:

```
struct S
{
   char mTag;
   union
   {
     long mL;
     float mF;
   };
} St;
```

```
void F(void)
{
   St.mL = 5;
}
```

The member names must be unique in the surrounding scope. Having an anonymous struct or union at file scope, as a global, external, or static variable is also allowed. This could for instance be used for declaring I/O registers, as in this example:

```
__no_init volatile
union
{
   unsigned char IOPORT;
   struct
   {
     unsigned char way: 1;
     unsigned char out: 1;
   };
} @ 0x1000;

/* The variables are used here. */
void Test(void)
{
   IOPORT = 0;
   way = 1;
   out = 1;
}
```

This declares an I/O register byte IOPORT at address  $0 \times 1000$ . The I/O register has 2 bits declared, Way and Out. Note that both the inner structure and the outer union are anonymous.

Anonymous structures and unions are implemented in terms of objects named after the first field, with a prefix \_A\_ to place the name in the implementation part of the namespace. In this example, the anonymous union will be implemented through an object named \_A\_IOPORT.

## Controlling data and function placement in memory

The compiler provides different mechanisms for controlling placement of functions and data objects in memory. To use memory efficiently, you should be familiar with these mechanisms to know which one is best suited for different situations. You can use:

• The @ operator and the #pragma location directive for absolute placement

Use the @ operator or the #pragma location directive to place individual global and static variables at absolute addresses. The variables must be declared \_\_no\_init.

This is useful for individual data objects that must be located at a fixed address to conform to external requirements, for example to populate interrupt vectors or other hardware tables. Note that it is not possible to use this notation for absolute placement of individual functions.

- The @ operator and the #pragma location directive for section placement

  Use the @ operator or the #pragma location directive to place groups of functions or global and static variables in named sections, without having explicit control of each object. The sections can, for example, be placed in specific areas of memory, or initialized or copied in controlled ways using the section begin and end operators. This is also useful if you want an interface between separately linked units, for example an application project and a boot loader project. Use named sections when absolute control over the placement of individual variables is not needed, or not useful.
- The @ operator and the #pragma location directive for register placement

  Use the @ operator or the #pragma location directive to place individual global and static variables in registers. The variables must be declared \_\_no\_init. This is useful for individual data objects that must be located in a specific register.
- The --section option

Use the --section option to place functions and/or data objects in named sections, which is useful, for example, if you want to direct them to different fast or slow memories. For more information about the --section option, see --section, page 245.

At compile time, data and functions are placed in different sections, see page 101*Modules and sections*, page 68. At link time, one of the most important functions of the linker is to assign load addresses to the various sections used by the application. All sections, except for the sections holding absolute located data, are automatically allocated to memory according to the specifications in the linker configuration file, see *Placing code and data—the linker configuration file*, page 71.

#### DATA PLACEMENT AT AN ABSOLUTE LOCATION

The @ operator, alternatively the #pragma location directive, can be used for placing global and static variables at absolute addresses.

To place a variable at an absolute address, the argument to the @ operator and the #pragma location directive should be a literal number, representing the actual address. The absolute location must fulfill the alignment requirement for the variable that should be located.

**Note:** All declarations of \_\_no\_init variables placed at an absolute address are *tentative definitions*. Tentatively defined variables are only kept in the output from the compiler if they are needed in the module being compiled. Such variables will be

defined in all modules in which they are used, which will work as long as they are defined in the same way. The recommendation is to place all such declarations in header files that are included in all modules that use the variables.

Other variables placed at an absolute address use the normal distinction between declaration and definition. For these variables, you must provide the definition in only one module, normally with an initializer. Other modules can refer to the variable by using an extern declaration, with or without an explicit address.

#### **Examples**

In this example, a \_\_no\_init declared variable is placed at an absolute address. This is useful for interfacing between multiple processes, applications, etc:

```
__no_init volatile char alpha @ 0xFF2000;/* OK */
```

The next example contains two const declared objects. The first one is not initialized, and the second one is initialized to a specific value. Both objects are placed in ROM. This is useful for configuration parameters, which are accessible from an external interface. Note that in the second case, the compiler is not obliged to actually read from the variable, because the value is known.

In the first case, the value is not initialized by the compiler; the value must be set by other means. The typical use is for configurations where the values are loaded to ROM separately, or for special function registers that are read-only.

These examples show incorrect usage:

#### C++ considerations

In C++, module scoped const variables are static (module local), whereas in C they are global. This means that each module that declares a certain const variable will contain a separate variable with this name. If you link an application with several such modules all containing (via a header file), for instance, the declaration:

```
volatile const __no_init int x @ 0x100; /* Bad in C++ */
```

the linker will report that more than one variable is located at address 0x100.

To avoid this problem and make the process the same in C and C++, you should declare these variables extern, for example:

```
/* The extern keyword makes x public. */
extern volatile const __no_init int x @ 0x100;
```

**Note:** C++ static member variables can be placed at an absolute address just like any other static variable.

#### DATA AND FUNCTION PLACEMENT IN SECTIONS

The following methods can be used for placing data or functions in named sections other than default:

- The @ operator, alternatively the #pragma location directive, can be used for placing individual variables or individual functions in named sections. The named section can either be a predefined section, or a user-defined section.
- The --section option can be used for placing variables and functions, which are parts of the whole compilation unit, in named sections.

C++ static member variables can be placed in named sections just like any other static variable.

If you use your own sections, in addition to the predefined sections, the sections must also be defined in the linker configuration file.

**Note:** Take care when explicitly placing a variable or function in a predefined section other than the one used by default. This is useful in some situations, but incorrect placement can result in anything from error messages during compilation and linking to a malfunctioning application. Carefully consider the circumstances; there might be strict requirements on the declaration and use of the function or variable.

The location of the sections can be controlled from the linker configuration file.

For more information about sections, see the chapter Section reference.

#### Examples of placing variables in named sections

In the following examples, a data object is placed in a user-defined section.

```
__no_init int alpha @ "MY_NOINIT"; /* OK */

#pragma location="MY_CONSTANTS"

const int beta; /* OK */
```

#### Examples of placing functions in named sections

```
void f(void) @ "MY_FUNCTIONS";

void g(void) @ "MY_FUNCTIONS"
{
}

#pragma location="MY_FUNCTIONS"
void h(void);
```

#### **DATA PLACEMENT IN REGISTERS**

The @ operator, alternatively the #pragma location directive, can be used for placing global and static variables in a register.

To place a variable in a register, the argument to the @ operator and the #pragma location directive should be an identifier that corresponds to an ARM core register in the range R4-R11 (R9 cannot be specified in combination with the --rwpi command line option).

A variable can be placed in a register only if it is declared as \_\_no\_init, has file scope, and its size is four bytes. A variable placed in a register does not have a memory address, so the address operator & cannot be used.

Within a module where a variable is placed in a register, the specified register will only be used for accessing that variable. The value of the variable is preserved across function calls to other modules because the registers R14-R11 are callee saved, and as such they are restored when execution returns. However, the value of a variable placed in a register is not always preserved as expected:

- In an exception handler or library callback routine (such as the comparator function
  passed to qsort) the value might not be preserved. The value will be preserved if
  the command line option --lock\_regs is used for locking the register in all
  modules of the application, including library modules.
- In a fast interrupt handler, the value of a variable in R8-R11 is not preserved from outside the handler, because these registers are banked.
- The longjmp function and C++ exceptions might restore variables placed in registers to old values, unlike other variables with static storage duration which are not restored.

The linker does not prevent modules from placing different variables in the same register. Variables in different modules can be placed in the same register, and another module could use the register for other purposes.

**Note:** A variable placed in a register should be defined in an include file, to be included in every module that uses the variable. An unused definition in a module will cause the register to not be used in that module.

## **Controlling compiler optimizations**

The compiler performs many transformations on your application to generate the best possible code. Examples of such transformations are storing values in registers instead of memory, removing superfluous code, reordering computations in a more efficient order, and replacing arithmetic operations by cheaper operations.

The linker should also be considered an integral part of the compilation system, because some optimizations are performed by the linker. For instance, all unused functions and variables are removed and not included in the final output.

#### SCOPE FOR PERFORMED OPTIMIZATIONS

You can decide whether optimizations should be performed on your whole application or on individual files. By default, the same types of optimizations are used for an entire project, but you should consider using different optimization settings for individual files. For example, put code that must execute very quickly into a separate file and compile it for minimal execution time, and the rest of the code for minimal code size. This will give a small program, which is still fast enough where it matters.

You can also exclude individual functions from the performed optimizations. The #pragma optimize directive allows you to either lower the optimization level, or specify another type of optimization to be performed. See *optimize*, page 314, for information about the pragma directive.

#### **MULTI-FILE COMPILATION UNITS**

In addition to applying different optimizations to different source files or even functions, you can also decide what a compilation unit consists of—one or several source code files.

By default, a compilation unit consists of one source file, but you can also use multi-file compilation to make several source files in a compilation unit. The advantage is that interprocedural optimizations such as inlining, and cross jump have more source code to work on. Ideally, the whole application should be compiled as one compilation unit. However, for large applications this is not practical because of resource restrictions on the host computer. For more information, see --mfc, page 232.

If the whole application is compiled as one compilation unit, it is very useful to make the compiler also discard unused public functions and variables before the interprocedural optimizations are performed. Doing this limits the scope of the optimizations to functions and variables that are actually used. For more information, see --discard\_unused\_publics, page 223.

#### **OPTIMIZATION LEVELS**

The compiler supports different levels of optimizations. This table lists optimizations that are typically performed on each level:

Optimization level	Description
None (Best debug support)	Variables live through their entire scope
Low	Same as above but variables only live for as long as they are needed, not necessarily through their entire scope
Medium	Same as above, and: Live-dead analysis and optimization Dead code elimination Redundant label elimination Redundant branch elimination Code hoisting Peephole optimization Some register content analysis and optimization Static clustering Common subexpression elimination
High (Maximum optimization)	Same as above, and: Instruction scheduling Cross jumping Advanced register content analysis and optimization Loop unrolling Function inlining Code motion Type-based alias analysis

Table 22: Compiler optimization levels

**Note:** Some of the performed optimizations can be individually enabled or disabled. For more information about these, see *Fine-tuning enabled transformations*, page 189.

A high level of optimization might result in increased compile time, and will most likely also make debugging more difficult, because it is less clear how the generated code relates to the source code. For example, at the low, medium, and high optimization levels, variables do not live through their entire scope, which means processor registers used for storing variables can be reused immediately after they were last used. Due to this, the C-SPY Watch window might not be able to display the value of the variable throughout its scope. At any time, if you experience difficulties when debugging your code, try lowering the optimization level.

#### **SPEED VERSUS SIZE**

At the high optimization level, the compiler balances between size and speed optimizations. However, it is possible to fine-tune the optimizations explicitly for either size or speed. They only differ in what thresholds that are used; speed will trade size for speed, whereas size will trade speed for size. Note that one optimization sometimes enables other optimizations to be performed, and an application might in some cases become smaller even when optimizing for speed rather than size.

#### FINE-TUNING ENABLED TRANSFORMATIONS

At each optimization level you can disable some of the transformations individually. To disable a transformation, use either the appropriate option, for instance the command line option --no\_inline, alternatively its equivalent in the IDE **Function inlining**, or the #pragma optimize directive. These transformations can be disabled individually:

- Common subexpression elimination
- Loop unrolling
- Function inlining
- Code motion
- Type-based alias analysis
- Static clustering
- Instruction scheduling.

#### Common subexpression elimination

Redundant re-evaluation of common subexpressions is by default eliminated at optimization levels Medium and High. This optimization normally reduces both code size and execution time. However, the resulting code might be difficult to debug.

**Note:** This option has no effect at optimization levels None and Low.

For more information about the command line option, see --no\_cse, page 234.

#### Loop unrolling

Loop unrolling means that the code body of a loop, whose number of iterations can be determined at compile time, is duplicated. Loop unrolling reduces the loop overhead by amortizing it over several iterations.

This optimization is most efficient for smaller loops, where the loop overhead can be a substantial part of the total loop body.

Loop unrolling, which can be performed at optimization level High, normally reduces execution time, but increases code size. The resulting code might also be difficult to debug.

The compiler heuristically decides which loops to unroll. Only relatively small loops where the loop overhead reduction is noticeable will be unrolled. Different heuristics are used when optimizing for speed, size, or when balancing between size and speed.

**Note:** This option has no effect at optimization levels None, Low, and Medium.

To disable loop unrolling, use the command line option --no\_unroll, see --no\_unroll, page 239.

#### **Function inlining**

Function inlining means that a simple function, whose definition is known at compile time, is integrated into the body of its caller to eliminate the overhead of the call. This optimization, which is performed at optimization level High, normally reduces execution time, but the resulting code might be difficult to debug.

The compiler heuristically decides which functions to inline. Different heuristics are used when optimizing for speed, size, or when balancing between size and speed. Normally, code size does not increase when optimizing for size. To control the heuristics for individual functions, use the #pragma inline directive or the Standard C inline keyword.

If you do not want to disable inlining for a whole module, use #pragma inline=never on an individual function instead.

Note: This option has no effect at optimization levels None, Low, and Medium.

For more information about the command line option, see --no\_inline, page 235. For information about the pragma directive, see *inline*, page 311.

#### Code motion

Evaluation of loop-invariant expressions and common subexpressions are moved to avoid redundant re-evaluation. This optimization, which is performed at optimization level High, normally reduces code size and execution time. The resulting code might however be difficult to debug.

**Note:** This option has no effect at optimization levels None, and Low.

For more information about the command line option, see --no\_code\_motion, page 233.

#### Type-based alias analysis

When two or more pointers reference the same memory location, these pointers are said to be *aliases* for each other. The existence of aliases makes optimization more difficult because it is not necessarily known at compile time whether a particular value is being changed.

Type-based alias analysis optimization assumes that all accesses to an object are performed using its declared type or as a char type. This assumption lets the compiler detect whether pointers can reference the same memory location or not.

Type-based alias analysis is performed at optimization level High. For application code conforming to standard C or C++ application code, this optimization can reduce code size and execution time. However, non-standard C or C++ code might result in the compiler producing code that leads to unexpected behavior. Therefore, it is possible to turn this optimization off.

Note: This option has no effect at optimization levels None, Low, and Medium.

For more information about the command line option, see --no\_tbaa, page 238.

#### Example

```
short F(short *p1, long *p2)
{
    *p2 = 0;
    *p1 = 1;
    return *p2;
}
```

With type-based alias analysis, it is assumed that a write access to the short pointed to by p1 cannot affect the long value that p2 points to. Thus, it is known at compile time that this function returns 0. However, in non-standard-conforming C or C++ code these pointers could overlap each other by being part of the same union. If you use explicit casts, you can also force pointers of different pointer types to point to the same memory location.

#### Static clustering

When static clustering is enabled, static and global variables that are defined within the same module are arranged so that variables that are accessed in the same function are stored close to each other. This makes it possible for the compiler to use the same base pointer for several accesses.

**Note:** This option has no effect at optimization levels None and Low.

For more information about the command line option, see --no\_clustering, page 233.

#### Instruction scheduling

The compiler features an instruction scheduler to increase the performance of the generated code. To achieve that goal, the scheduler rearranges the instructions to minimize the number of pipeline stalls emanating from resource conflicts within the microprocessor. Note that not all cores benefit from scheduling. The resulting code might be difficult to debug.

**Note:** This option has no effect at optimization levels None, Low and Medium.

For more information about the command line option, see --no scheduling, page 237.

## Facilitating good code generation

This section contains hints on how to help the compiler generate good code, for example:

- · Using efficient addressing modes
- Helping the compiler optimize
- Generating more useful error message.

#### WRITING OPTIMIZATION-FRIENDLY SOURCE CODE

The following is a list of programming techniques that will, when followed, enable the compiler to better optimize the application.

- Local variables—auto variables and parameters—are preferred over static or global variables. The reason is that the optimizer must assume, for example, that called functions can modify non-local variables. When the life spans for local variables end, the previously occupied memory can then be reused. Globally declared variables will occupy data memory during the whole program execution.
- Avoid taking the address of local variables using the & operator. This is inefficient
  for two main reasons. First, the variable must be placed in memory, and thus cannot
  be placed in a processor register. This results in larger and slower code. Second, the
  optimizer can no longer assume that the local variable is unaffected over function
  calls.
- Module-local variables—variables that are declared static—are preferred over global variables (non-static). Also avoid taking the address of frequently accessed static variables.
- The compiler is capable of inlining functions, see *Function inlining*, page 190. To maximize the effect of the inlining transformation, it is good practice to place the definitions of small functions called from more than one module in the header file rather than in the implementation file. Alternatively, you can use multi-file compilation. For more information, see *Multi-file compilation units*, page 187.
- Avoid using inline assembler. Instead, try writing the code in C or C++, use intrinsic
  functions, or write a separate module in assembler language. For more information,
  see Mixing C and assembler, page 125.

#### SAVING STACK SPACE AND RAM MEMORY

The following is a list of programming techniques that will, when followed, save memory and stack space:

- If stack space is limited, avoid long call chains and recursive functions.
- Avoid using large non-scalar types, such as structures, as parameters or return type.
   To save stack space, you should instead pass them as pointers or, in C++, as references.

#### **FUNCTION PROTOTYPES**

It is possible to declare and define functions using one of two different styles:

- Prototyped
- Kernighan & Ritchie C (K&R C)

Both styles are included in the C standard; however, it is recommended to use the prototyped style, since it makes it easier for the compiler to find problems in the code. Using the prototyped style will also make it possible to generate more efficient code, since type promotion (implicit casting) is not needed. The K&R style is only supported for compatibility reasons.

To make the compiler verify that all functions have proper prototypes, use the compiler option **Require prototypes** (--require\_prototypes).

#### Prototyped style

In prototyped function declarations, the type for each parameter must be specified.

```
int Test(char, int); /* Declaration */
int Test(char ch, int i) /* Definition */
{
   return i + ch;
}
```

#### Kernighan & Ritchie style

In K&R style—pre-Standard C—it is not possible to declare a function prototyped. Instead, an empty parameter list is used in the function declaration. Also, the definition looks different.

#### For example:

#### INTEGER TYPES AND BIT NEGATION

In some situations, the rules for integer types and their conversion lead to possibly confusing behavior. Things to look out for are assignments or conditionals (test expressions) involving types with different size, and logical operations, especially bit negation. Here, *types* also includes types of constants.

In some cases there might be warnings (for example, for constant conditional or pointless comparison), in others just a different result than what is expected. Under certain circumstances the compiler might warn only at higher optimizations, for example, if the compiler relies on optimizations to identify some instances of constant conditionals. In this example an 8-bit character, a 32-bit integer, and two's complement is assumed:

```
void F1(unsigned char c1)
{
   if (c1 == ~0x80)
    ;
}
```

Here, the test is always false. On the right hand side, 0x80 is 0x00000080, and ~0x00000080 becomes 0xffffffff. On the left hand side, c1 is an 8-bit unsigned character, so it cannot be larger than 255. It also cannot be negative, which means that the integral promoted value can never have the topmost 24 bits set.

#### PROTECTING SIMULTANEOUSLY ACCESSED VARIABLES

Variables that are accessed asynchronously, for example by interrupt routines or by code executing in separate threads, must be properly marked and have adequate protection. The only exception to this is a variable that is always *read-only*.

To mark a variable properly, use the volatile keyword. This informs the compiler, among other things, that the variable can be changed from other threads. The compiler will then avoid optimizing on the variable (for example, keeping track of the variable in registers), will not delay writes to it, and be careful accessing the variable only the number of times given in the source code.

For more information about the volatile type qualifier and the rules for accessing volatile objects, see *Declaring objects volatile*, page 287.

#### **ACCESSING SPECIAL FUNCTION REGISTERS**

Specific header files for several ARM devices are included in the IAR product installation. The header files are named iodevice.h and define the processor-specific special function registers (SFRs).

**Note:** Each header file contains one section used by the compiler, and one section used by the assembler.

SFRs with bitfields are declared in the header file. This example is from ioks32c5000a.h:

```
__no_init volatile union
 unsigned short mwctl2;
 struct
   unsigned short edr : 1;
   unsigned short edw : 1;
   unsigned short lee : 2;
   unsigned short lemd : 2;
   unsigned short lep1 : 2;
 } mwctl2bit;
} @ 0x1000;
/* By including the appropriate include file in your code,
* it is possible to access either the whole register or any
 * individual bit (or bitfields) from C code as follows.
 * /
void Test()
 /* Whole register access */
 mwct12 = 0x1234;
 /* Bitfield accesses */
 mwctl2bit.edw = 1;
 mwctl2bit.lepl = 3;
```

You can also use the header files as templates when you create new header files for other ARM devices.

#### PASSING VALUES BETWEEN C AND ASSEMBLER OBJECTS

The following example shows how you in your C source code can use inline assembler to set and get values from a special purpose register:

```
#pragma diag_suppress=Pe940
#pragma optimize=no_inline
static unsigned long get_APSR( void )
{
    /* On function exit,
        function return value should be present in R0 */
    asm( "MRS R0, APSR" );
}
#pragma diag_default=Pe940

#pragma optimize=no_inline
static void set_APSR( unsigned long value)
{
    /* On function entry, the first parameter is found in R0 */
    asm( "MSR APSR, R0" );
}
```

The general purpose register R0 is used for getting and setting the value of the special purpose register APSR. As the functions only contain inline assembler, the compiler will not interfere with the register usage. The register R0 is always used for return values. The first parameter is always passed in R0 if the type is 32 bits or smaller.

The same method can be used also for accessing other special purpose registers and specific instructions.

To read more about the risks of using inline assembler, see *Inline assembler*, page 127. For reference information about using inline assembler, see *Inline assembler*, page 144.

**Note:** Before you use inline assembler, see if you can use an intrinsic function instead. See *Summary of intrinsic functions*, page 323.

#### **NON-INITIALIZED VARIABLES**

Normally, the runtime environment will initialize all global and static variables when the application is started.

The compiler supports the declaration of variables that will not be initialized, using the \_\_no\_init type modifier. They can be specified either as a keyword or using the #pragma object\_attribute directive. The compiler places such variables in a separate section.

For \_\_no\_init, the const keyword implies that an object is read-only, rather than that the object is stored in read-only memory. It is not possible to give a \_\_no\_init object an initial value.

Variables declared using the \_\_no\_init keyword could, for example, be large input buffers or mapped to special RAM that keeps its content even when the application is turned off.

For information about the \_\_no\_init keyword, see page 298. Note that to use this keyword, language extensions must be enabled; see -e, page 225. For information about the #pragma object\_attribute, see page 314.

Facilitating good code generation

# Part 2. Reference information

This part of the IAR C/C++ Development Guide for ARM® contains these chapters:

- External interface details
- Compiler options
- Linker options
- Data representation
- Extended keywords
- Pragma directives
- Intrinsic functions
- The preprocessor
- Library functions
- The linker configuration file
- Section reference
- IAR utilities
- Implementation-defined behavior.



## External interface details

This chapter provides reference information about how the compiler and linker interact with their environment. The chapter briefly lists and describes the invocation syntax, methods for passing options to the tools, environment variables, the include file search procedure, and finally the different types of compiler and linker output.

## **Invocation syntax**

You can use the compiler and linker either from the IDE or from the command line. See the *IDE Project Management and Building Guide for ARM®* for information about using the build tools from the IDE.

#### **COMPILER INVOCATION SYNTAX**

The invocation syntax for the compiler is:

```
iccarm [options] [sourcefile] [options]
```

For example, when compiling the source file prog.c, use this command to generate an object file with debug information:

```
iccarm prog.c --debug
```

The source file can be a C or C++ file, typically with the filename extension c or cpp, respectively. If no filename extension is specified, the file to be compiled must have the extension c.

Generally, the order of options on the command line, both relative to each other and to the source filename, is *not* significant. There is, however, one exception: when you use the -I option, the directories are searched in the same order as they are specified on the command line.

If you run the compiler from the command line without any arguments, the compiler version number and all available options including brief descriptions are directed to stdout and displayed on the screen.

#### ILINK INVOCATION SYNTAX

The invocation syntax for ILINK is:

```
ilinkarm [arguments]
```

Each argument is either a command-line option, an object file, or a library.

For example, when linking the object file prog.o, use this command:

```
ilinkarm prog.o --config configfile
```

If no filename extension is specified for the linker configuration file, the configuration file must have the extension icf.

Generally, the order of arguments on the command line is *not* significant. There is, however, one exception: when you supply several libraries, the libraries are searched in the same order that they are specified on the command line. The default libraries are always searched last.

The output executable image will be placed in a file named a .out, unless the -o option is used.

If you run ILINK from the command line without any arguments, the ILINK version number and all available options including brief descriptions are directed to stdout and displayed on the screen.

#### **PASSING OPTIONS**

There are three different ways of passing options to the compiler and to ILINK:

- Directly from the command line

  Specify the options on the command line after the iccarm or ilinkarm commands;
  see *Invocation syntax*, page 201.
- Via environment variables
   The compiler and linker automatically append the value of the environment variables to every command line; see *Environment variables*, page 202.
- Via a text file, using the -f option; see -f, page 227.

For general guidelines for the option syntax, an options summary, and a detailed description of each option, see the *Compiler options* chapter.

#### **ENVIRONMENT VARIABLES**

These environment variables can be used with the compiler:

Environment variable	Description	
C_INCLUDE	Specifies directories to search for include files; for example:	
	<pre>C_INCLUDE=c:\program files\iar systems\embedded</pre>	
	<pre>workbench 6.n\arm\inc;c:\headers</pre>	
QCCARM	Specifies command line options; for example: $QCCARM = -1A asm.1st$	

Table 23: Compiler environment variables

This environment variable can be used with ILINK:

Environment variable	Description
ILINKARM_CMD_LINE Specifies command line options; for example:	
	ILINKARM_CMD_LINE=config full.icf
	silent

Table 24: ILINK environment variables

## Include file search procedure

This is a detailed description of the compiler's #include file search procedure:

- If the name of the #include file is an absolute path specified in angle brackets or double quotes, that file is opened.
- If the compiler encounters the name of an #include file in angle brackets, such as:

```
#include <stdio.h>
```

it searches these directories for the file to include:

- 1 The directories specified with the -⊥ option, in the order that they were specified, see -*I*, page 229.
- 2 The directories specified using the C\_INCLUDE environment variable, if any; see *Environment variables*, page 202.
- 3 The automatically set up library system include directories. See --dlib\_config, page 224.
- If the compiler encounters the name of an #include file in double quotes, for example:

```
#include "vars.h"
```

it searches the directory of the source file in which the #include statement occurs, and then performs the same sequence as for angle-bracketed filenames.

If there are nested #include files, the compiler starts searching the directory of the file that was last included, iterating upwards for each included file, searching the source file directory last. For example:

```
src.c in directory dir\src
    #include "src.h"
    ...
src.h in directory dir\include
    #include "config.h"
    ...
```

When dir\exe is the current directory, use this command for compilation:

```
iccarm ..\src\src.c -I..\include -I..\debugconfig
```

Then the following directories are searched in the order listed below for the file config.h, which in this example is located in the dir\debugconfig directory:

dir\include Current file is src.h.

dir\src File including current file (src.c).

dir\include As specified with the first -I option.

dir\debugconfig As specified with the second -I option.

Use angle brackets for standard header files, like stdio.h, and double quotes for files that are part of your application.

For information about the syntax for including header files, see *Overview of the preprocessor*, page 365.

## **Compiler output**

The compiler can produce the following output:

• A linkable object file

The object files produced by the compiler use the industry-standard format ELF. By default, the object file has the filename extension o.

Optional list files

Various kinds of list files can be specified using the compiler option -1, see -*l*, page 230. By default, these files will have the filename extension 1st.

• Optional preprocessor output files

A preprocessor output file is produced when you use the --preprocess option; by default, the file will have the filename extension i.

Diagnostic messages

Diagnostic messages are directed to the standard error stream and displayed on the screen, and printed in an optional list file. For more information about diagnostic messages, see *Diagnostics*, page 206.

Error return codes

These codes provide status information to the operating system which can be tested in a batch file, see *Error return codes*, page 205.

#### Size information

Information about the generated amount of bytes for functions and data for each memory is directed to the standard output stream and displayed on the screen. Some of the bytes might be reported as *shared*.

Shared objects are functions or data objects that are shared between modules. If any of these occur in more than one module, only one copy is retained. For example, in some cases inline functions are not inlined, which means that they are marked as shared, because only one instance of each function will be included in the final application. This mechanism is sometimes also used for compiler-generated code or data not directly associated with a particular function or variable, and when only one instance is required in the final application.

#### **Error return codes**

The compiler and linker return status information to the operating system that can be tested in a batch file.

These command line error codes are supported:

Code	Description	
0	Compilation or linking successful, but there might have been warnings.	
I	Warnings were produced and the optionwarnings_affect_exit_code was used.	
2	Errors occurred.	
3	Fatal errors occurred, making the tool abort.	
4	Internal errors occurred, making the tool abort.	

Table 25: Error return codes

## **ILINK** output

ILINK can produce the following output:

#### An absolute executable image

The final output produced by the IAR ILINK Linker is an absolute object file containing the executable image that can be put into an EPROM, downloaded to a hardware emulator, or executed on your PC using the IAR C-SPY Debugger Simulator. By default, the file has the filename extension out. The output format is always in ELF, which optionally includes debug information in the DWARF format.

#### • Optional logging information

During operation, ILINK logs its decisions on stdout, and optionally to a file. For example, if a library is searched, whether a required symbol is found in a library

module, or whether a module will be part of the output. Timing information for each ILINK subsystem is also logged.

Optional map files

A linker map file—containing summaries of linkage, runtime attributes, memory, and placement, as well as an entry list—can be generated by the ILINK option --map, see --map, page 265. By default, the map file has the filename extension map.

• Diagnostic messages

Diagnostic messages are directed to stderr and displayed on the screen, as well as printed in the optional map file. For more information about diagnostic messages, see *Diagnostics*, page 206.

• Error return codes

ILINK returns status information to the operating system which can be tested in a batch file, see *Error return codes*, page 205.

Size information about used memory and amount of time
 Information about the generated amount of bytes for functions and data for each memory is directed to stdout and displayed on the screen.

## **Diagnostics**

This section describes the format of the diagnostic messages and explains how diagnostic messages are divided into different levels of severity.

#### MESSAGE FORMAT FOR THE COMPILER

All diagnostic messages are issued as complete, self-explanatory messages. A typical diagnostic message from the compiler is produced in the form:

filename,linenumber level[tag]: message

with these elements:

filename The name of the source file in which the issue was encountered

1 Inenumber The line number at which the compiler detected the issue

1evel The level of seriousness of the issue

tag A unique tag that identifies the diagnostic message

message An explanation, possibly several lines long

Diagnostic messages are displayed on the screen, as well as printed in the optional list file.

Use the option --diagnostics\_tables to list all possible compiler diagnostic messages.

#### MESSAGE FORMAT FOR THE LINKER

All diagnostic messages are issued as complete, self-explanatory messages. A typical diagnostic message from ILINK is produced in the form:

level[tag]: message

with these elements:

1evel The level of seriousness of the issue

tag A unique tag that identifies the diagnostic message

message An explanation, possibly several lines long

Diagnostic messages are displayed on the screen, as well as printed in the optional map file.

Use the option --diagnostics\_tables to list all possible linker diagnostic messages.

#### **SEVERITY LEVELS**

The diagnostic messages are divided into different levels of severity:

#### Remark

A diagnostic message that is produced when the compiler or linker finds a construct that can possibly lead to erroneous behavior in the generated code. Remarks are by default not issued, but can be enabled, see *--remarks*, page 244.

#### Warning

A diagnostic message that is produced when the compiler or linker finds a potential problem which is of concern, but which does not prevent completion of the compilation or linking. Warnings can be disabled by use of the command line option --no\_warnings, see page 240.

#### **Error**

A diagnostic message that is produced when the compiler or linker finds a serious error. An error will produce a non-zero exit code.

#### Fatal error

A diagnostic message that is produced when the compiler finds a condition that not only prevents code generation, but which makes further processing pointless. After the message is issued, compilation terminates. A fatal error will produce a non-zero exit code.

#### SETTING THE SEVERITY LEVEL

The diagnostic messages can be suppressed or the severity level can be changed for all diagnostics messages, except for fatal errors and some of the regular errors.

See *Summary of compiler options*, page 212, for information about the compiler options that are available for setting severity levels.

For the compiler see also the chapter *Pragma directives*, for information about the pragma directives that are available for setting severity levels.

#### **INTERNAL ERROR**

An internal error is a diagnostic message that signals that there was a serious and unexpected failure due to a fault in the compiler or linker. It is produced using this form:

Internal error: message

where *message* is an explanatory message. If internal errors occur, they should be reported to your software distributor or IAR Systems Technical Support. Include enough information to reproduce the problem, typically:

- The product name
- The version number of the compiler or of ILINK, which can be seen in the header of the list or map files generated by the compiler or by ILINK, respectively
- Your license number
- The exact internal error message text
- The files involved of the application that generated the internal error
- A list of the options that were used when the internal error occurred.

# **Compiler options**

This chapter describes the syntax of compiler options and the general syntax rules for specifying option parameters, and gives detailed reference information about each option.

## **Options syntax**

Compiler options are parameters you can specify to change the default behavior of the compiler. You can specify options from the command line—which is described in more detail in this section—and from within the IDE.



See the *IDE Project Management and Building Guide for ARM*® for information about the compiler options available in the IDE and how to set them.

#### TYPES OF OPTIONS

There are two *types of names* for command line options, *short* names and *long* names. Some options have both.

- A short option name consists of one character, and it can have parameters. You specify it with a single dash, for example -e
- A long option name consists of one or several words joined by underscores, and it can have parameters. You specify it with double dashes, for example --char\_is\_signed.

For information about the different methods for passing options, see *Passing options*, page 202.

#### **RULES FOR SPECIFYING PARAMETERS**

There are some general syntax rules for specifying option parameters. First, the rules depending on whether the parameter is *optional* or *mandatory*, and whether the option has a short or a long name, are described. Then, the rules for specifying filenames and directories are listed. Finally, the remaining rules are listed.

#### Rules for optional parameters

For options with a short name and an optional parameter, any parameter should be specified without a preceding space, for example:

-0 or -0h

For options with a long name and an optional parameter, any parameter should be specified with a preceding equal sign (=), for example:

```
--misrac2004=n
```

#### Rules for mandatory parameters

For options with a short name and a mandatory parameter, the parameter can be specified either with or without a preceding space, for example:

```
-I..\src or -I ..\src\
```

For options with a long name and a mandatory parameter, the parameter can be specified either with a preceding equal sign (=) or with a preceding space, for example:

```
--diagnostics_tables=MyDiagnostics.lst
or
--diagnostics_tables MyDiagnostics.lst
```

#### Rules for options with both optional and mandatory parameters

For options taking both optional and mandatory parameters, the rules for specifying the parameters are:

- For short options, optional parameters are specified without a preceding space
- For long options, optional parameters are specified with a preceding equal sign (=)
- For short and long options, mandatory parameters are specified with a preceding space.

For example, a short option with an optional parameter followed by a mandatory parameter:

```
-lA MyList.1st
```

For example, a long option with an optional parameter followed by a mandatory parameter:

```
--preprocess=n PreprocOutput.1st
```

#### Rules for specifying a filename or directory as parameters

These rules apply for options taking a filename or directory as parameters:

• Options that take a filename as a parameter can optionally take a file path. The path can be relative or absolute. For example, to generate a listing to the file List.lst in the directory ..\listings\:

```
iccarm prog.c -1 ..\listings\List.lst
```

• For options that take a filename as the destination for output, the parameter can be specified as a path without a specified filename. The compiler stores the output in that directory, in a file with an extension according to the option. The filename will be the same as the name of the compiled source file, unless a different name was specified with the option -o, in which case that name is used. For example:

```
iccarm prog.c -1 ..\listings\
```

The produced list file will have the default name ..\listings\prog.lst

• The *current directory* is specified with a period (.). For example:

```
iccarm prog.c -1 .
```

- / can be used instead of \ as the directory delimiter.
- By specifying -, input files and output files can be redirected to the standard input and output stream, respectively. For example:

```
iccarm prog.c -1 -
```

#### **Additional rules**

These rules also apply:

When an option takes a parameter, the parameter cannot start with a dash (-)
followed by another character. Instead, you can prefix the parameter with two
dashes; this example will create a list file called -r:

```
iccarm prog.c -1 ---r
```

• For options that accept multiple arguments of the same type, the arguments can be provided as a comma-separated list (without a space), for example:

```
--diag_warning=Be0001,Be0002
```

Alternatively, the option can be repeated for each argument, for example:

```
--diag warning=Be0001
```

<sup>--</sup>diag\_warning=Be0002

# Summary of compiler options

This table summarizes the compiler command line options:

Command line option	Description
aapcs	Specifies the calling convention
aeabi	Enables AEABI-compliant code generation
align_sp_on_irq	Generates code to align SP on entry to $\_\_irq$ functions
arm	Sets the default function mode to ARM
c89	Specifies the C89 dialect
char_is_signed	Treats char as signed
char_is_unsigned	Treats char as unsigned
cpu	Specifies a processor variant
cpu_mode	Selects the default mode for functions
C++	Specifies Standard C++
-D	Defines preprocessor symbols
debug	Generates debug information
dependencies	Lists file dependencies
diag_error	Treats these as errors
diag_remark	Treats these as remarks
diag_suppress	Suppresses these diagnostics
diag_warning	Treats these as warnings
diagnostics_tables	Lists all diagnostic messages
discard_unused_publics	Discards unused public symbols
dlib_config	Uses the system include files for the DLIB library and determines which configuration of the library to use
-e	Enables language extensions
ec++	Specifies Embedded C++
eec++	Specifies Extended Embedded C++
enable_hardware_workaround	Enables a specific hardware workaround
enable_multibytes	Enables support for multibyte characters in source files

Table 26: Compiler options summary

Command line option	Description
endian	Specifies the byte order of the generated code and data
enum_is_int	Sets the minimum size on enumeration types
error_limit	Specifies the allowed number of errors before compilation stops
-f	Extends the command line
fpu	Selects the type of floating-point unit
guard_calls	Enables guards for function static variable initialization
header_context	Lists all referred source files and header files
-I	Specifies include file path
interwork	Generates interworking code
-1	Creates a list file
legacy	Generates object code linkable with older tool chains
lock_regs	Prevents the compiler from using specified registers
macro_positions_in _diagnostics	Obtains positions inside macros in diagnostic messages
mfc	Enables multi-file compilation
migration_preprocessor _extensions	Extends the preprocessor
misrac	Enables error messages specific to MISRA-C:1998. This option is a synonym ofmisrac1998 and is only available for backwards compatibility.
misrac1998	Enables error messages specific to MISRA-C:1998. See the IAR Embedded Workbench® MISRA C:1998 Reference Guide.
misrac2004	Enables error messages specific to MISRA-C:2004. See the IAR Embedded Workbench® MISRA C:2004 Reference Guide.
misrac_verbose	Enables verbose logging of MISRA C checking. See the IAR Embedded Workbench® MISRA C:1998 Reference Guide or the IAR Embedded Workbench® MISRA C:2004 Reference Guide.

Table 26: Compiler options summary (Continued)

Command line option	Description
no_clustering	Disables static clustering optimizations
no_code_motion	Disables code motion optimization
no_const_align	Disables the alignment optimization for constants.
no_cse	Disables common subexpression elimination
no_exceptions	Disables C++ exception support
no_fragments	Disables section fragment handling
no_inline	Disables function inlining
no_loop_align	Disables alignment of labels in loops (Thumb2)
no_mem_idioms	Disables idiom recognition for memcpy/memset/memclr
no_path_in_file_macros	Removes the path from the return value of the symbolsFILE andBASE_FILE
no_rtti	Disables C++ RTTI support
no_rw_dynamic_init	Disables runtime initialization of static C variables.
no_scheduling	Disables the instruction scheduler
no_static_destruction	Disables destruction of C++ static variables at program exit
no_system_include	Disables the automatic search for system include files
no_tbaa	Disables type-based alias analysis
no_typedefs_in_diagnostics	Disables the use of typedef names in diagnostics
no_unaligned_access	Avoids unaligned accesses
no_unroll	Disables loop unrolling
no_warnings	Disables all warnings
no_wrap_diagnostics	Disables wrapping of diagnostic messages
-O	Sets the optimization level
-0	Sets the object filename. Alias foroutput.
only_stdout	Uses standard output only
output	Sets the object filename
predef_macros	Lists the predefined symbols.
preinclude	Includes an include file before reading the source file
preprocess	Generates preprocessor output

Table 26: Compiler options summary (Continued)

Command line option	Description
public_equ	Defines a global named assembler label
-r	Generates debug information. Alias fordebug.
relaxed_fp	Relaxes the rules for optimizing floating-point expressions
remarks	Enables remarks
require_prototypes	Verifies that functions are declared before they are defined
ropi	Generates code that uses PC-relative references to address code and read-only data.
rwpi	Generates code that uses an offset from the static base register to address-writable data.
section	Changes a section name
separate_cluster_for_ initialized_variables	Separates initialized and non-initialized variables
silent	Sets silent operation
strict	Checks for strict compliance with Standard C/C++
system_include_dir	Specifies the path for system include files
thumb	Sets default function mode to Thumb
use_c++_inline	Uses C++ inline semantics in C99
use_unix_directory_	Uses / as directory separator in paths
separators	
vla	Enables C99 VLA support
warnings_affect_exit_code	Warnings affect exit code
warnings_are_errors	Warnings are treated as errors
Table 26: Compiler entions summany (Continued)	

Table 26: Compiler options summary (Continued)

## **Descriptions of compiler options**

The following section gives detailed reference information about each compiler option.



Note that if you use the options page **Extra Options** to specify specific command line options, the IDE does not perform an instant check for consistency problems like conflicting options, duplication of options, or use of irrelevant options.

#### --aapcs

Syntax --aapcs={std|vfp}

**Parameters** 

std Processor registers are used for floating-point parameters and

return values in function calls according to standard AAPCS. std is

the default when the software FPU is selected.

vfp VFP registers are used for floating-point parameters and return

values. The generated code is not compatible with AEABI code.

vfp is the default when a VFP unit is used.

Description Use this option to specify the floating-point calling convention.



Project>Options>C/C++ Compiler>Extra Options.

--aeabi

Syntax --aeabi

Description Use this option to generate AEABI-compliant object code. Note that this option must be

used together with the --guard\_calls option.

See also *AEABI compliance*, page 174 and --guard\_calls, page 229.



Project>Options>C/C++ Compiler>Extra Options.

--align\_sp\_on\_irq

Syntax --align\_sp\_on\_irq

Description Use this option to align the stack pointer (SP) on entry to \_\_irq declared functions.

This is especially useful for nested interrupts, where the interrupted code uses the same SP as the interrupt handler. This means that the stack might only have 4-byte alignment, instead of the 8-byte alignment required by AEABI (and some instructions generated by

the compiler for some cores).

See also \_\_*irq*, page 296.



Project>Options>C/C++ Compiler>Extra Options.

#### --arm

Syntax --arm

Description Use this option to set default function mode to ARM. This setting must be the same for

all files included in a program, unless they are interworking.

**Note:** This option has the same effect as the --cpu\_mode=arm option.

See also --interwork, page 229 and \_\_interwork, page 296.



### Project>Options>C/C++ Compiler>Code>Processor mode>Arm

## --c89

Syntax --c89

Description Use this option to enable the C89 C dialect instead of Standard C.

**Note:** This option is mandatory when the MISRA C checking is enabled.

See also *C language overview*, page 143.



#### Project>Options>C/C++ Compiler>Language 1>C dialect>C89

## --char\_is\_signed

Syntax --char\_is\_signed

Description By default, the compiler interprets the plain char type as unsigned. Use this option to

make the compiler interpret the plain char type as signed instead. This can be useful when you, for example, want to maintain compatibility with another compiler.

Note: The runtime library is compiled without the --char\_is\_signed option and

cannot be used with code that is compiled with this option.



Project>Options>C/C++ Compiler>Language 2>Plain 'char' is

# --char\_is\_unsigned

Syntax --char\_is\_unsigned

Description Use this option to make the compiler interpret the plain char type as unsigned. This is

the default interpretation of the plain char type.



### Project>Options>C/C++ Compiler>Language 2>Plain 'char' is

## --cpu

Syntax --cpu=core

**Parameters** 

core Specifies a specific processor variant

Description

Use this option to select the processor variant for which the code is to be generated. The

default is ARM7TDMI. The following cores and processor macrocells are recognized:

ARM7TDMI	ARM946E-S	ARM1176JF (alias for ARM1176JZF)
ARM7TDMI-S	ARM966E-S	ARM1176JF-S (alias for ARM1176JZF-S)
ARM710T	ARM968E-S	Cortex-A5
ARM720T	ARM10E	Cortex-M0
ARM740T	ARM1020E	Cortex-M1
ARM7EJ-S	ARM1022E	Cortex-Ms1*
ARM9TDMI	ARM1026EJ-S	Cortex-M3
ARM920T	ARM1136J	Cortex-M4
ARM922T	ARM1136J-S	Cortex-M4F
ARM940T	ARM1136JF	Cortex-R4
ARM9E	ARM1136JF-S	Cortex-R4F
ARM9E-S	ARM1176J (alias for ARM1176JZ)	XScale
ARM926EJ-S	ARM1176J-S (alias for ARM1176JZ-S)	XScale-IR7

\* Cortex-MI with Operating System extension.

See also *Processor variant*, page 48.



#### Project>Options>General Options>Target>Processor configuration

## --cpu\_mode

**Parameters** 

arm, a (default) Selects the arm mode as the default mode for functions

thumb, t Selects the thumb mode as the default mode for functions

Description Use this option to select the default mode for functions. This setting must be the same

for all files included in a program, unless they are interworking.

See also --interwork, page 229 and \_\_interwork, page 296.

X

## Project>Options>General Options>Target>Processor mode

--c++

Syntax --c++

Description By default, the language supported by the compiler is C. If you use Standard C++, you

must use this option to set the language the compiler uses to C++.

See also -ec++, page 225, -eec++, page 225, and *Using C++*, page 153.

X

Project>Options>C/C++ Compiler>Language 1>C++

and

Project>Options>C/C++ Compiler>Language 1>C++ dialect>C++

-D

Syntax -D symbol[=value]

**Parameters** 

symbolThe name of the preprocessor symbolvalueThe value of the preprocessor symbol

Description

Use this option to define a preprocessor symbol. If no value is specified, 1 is used. This option can be used one or more times on the command line.

The option -D has the same effect as a #define statement at the top of the source file:

-Dsymbol

is equivalent to:

#define symbol 1

To get the equivalence of:

#define F00

specify the = sign but nothing after, for example:

-DFOO=



Project>Options>C/C++ Compiler>Preprocessor>Defined symbols

--debug, -r

Syntax --debug

-r

Description

Use the --debug or -r option to make the compiler include information in the object modules required by the IAR C-SPY® Debugger and other symbolic debuggers.

**Note:** Including debug information will make the object files larger than otherwise.



Project>Options>C/C++ Compiler>Output>Generate debug information

# --dependencies

Syntax --dependencies[=[i|m]] {filename|directory}

**Parameters** 

i (default) Lists only the names of files

m Lists in makefile style

For information about specifying a filename or a directory, see *Rules for specifying a filename or directory as parameters*, page 210.

Description

Use this option to make the compiler list the names of all source and header files opened for input into a file with the default filename extension i.

Example

If --dependencies or --dependencies=i is used, the name of each opened input file, including the full path, if available, is output on a separate line. For example:

```
c:\iar\product\include\stdio.h
d:\myproject\include\foo.h
```

If --dependencies=m is used, the output is in makefile style. For each input file, one line containing a makefile dependency rule is produced. Each line consists of the name of the object file, a colon, a space, and the name of an input file. For example:

```
foo.o: c:\iar\product\include\stdio.h
foo.o: d:\myproject\include\foo.h
```

An example of using --dependencies with a popular make utility, such as gmake (GNU make):

I Set up the rule for compiling files to be something like:

```
%.0 : %.c
     $(ICC) $(ICCFLAGS) $< --dependencies=m $*.d</pre>
```

That is, in addition to producing an object file, the command also produces a dependency file in makefile style (in this example, using the extension .d).

**2** Include all the dependency files in the makefile using, for example:

```
-include $(sources:.c=.d)
```

Because of the dash (-) it works the first time, when the .d files do not yet exist.



This option is not available in the IDE.

## --diag\_error

Syntax --diag\_error=tag[,tag,...]

**Parameters** 

tag The number of a diagnostic message, for example the message

number Pe117

Description

Use this option to reclassify certain diagnostic messages as errors. An error indicates a violation of the C or C++ language rules, of such severity that object code will not be generated. The exit code will be non-zero. This option may be used more than once on the command line.



#### Project>Options>C/C++ Compiler>Diagnostics>Treat these as errors

## --diag\_remark

Syntax --diag\_remark=tag[,tag,...]

**Parameters** 

tag The number of a diagnostic message, for example the message

number Pe177

Description

Use this option to reclassify certain diagnostic messages as remarks. A remark is the least severe type of diagnostic message and indicates a source code construction that may cause strange behavior in the generated code. This option may be used more than once on the command line.

**Note:** By default, remarks are not displayed; use the --remarks option to display them.



#### Project>Options>C/C++ Compiler>Diagnostics>Treat these as remarks

# --diag\_suppress

Syntax --diag\_suppress=tag[,tag,...]

**Parameters** 

tag The number of a diagnostic message, for example the message

number Pe117

Description

Use this option to suppress certain diagnostic messages. These messages will not be displayed. This option may be used more than once on the command line.



Project>Options>C/C++ Compiler>Diagnostics>Suppress these diagnostics

## --diag\_warning

Syntax --diag\_warning=tag[,tag,...]

**Parameters** 

tag The number of a diagnostic message, for example the message

number Pe826

Description Use this option to reclassify certain diagnostic messages as warnings. A warning

indicates an error or omission that is of concern, but which will not cause the compiler to stop before compilation is completed. This option may be used more than once on the

command line.



Project>Options>C/C++ Compiler>Diagnostics>Treat these as warnings

## --diagnostics\_tables

Syntax --diagnostics\_tables {filename | directory}

Parameters For information about specifying a filename or a directory, see *Rules for specifying a* 

filename or directory as parameters, page 210.

Description Use this option to list all possible diagnostic messages in a named file. This can be

convenient, for example, if you have used a pragma directive to suppress or change the

severity level of any diagnostic messages, but forgot to document why.

This option cannot be given together with other options.



This option is not available in the IDE.

## --discard\_unused\_publics

Syntax --discard\_unused\_publics

Description Use this option to discard unused public functions and variables when compiling with

the --mfc compiler option.

**Note:** Do not use this option only on parts of the application, as necessary symbols might be removed from the generated output.

See also

--mfc, page 232 and Multi-file compilation units, page 187.



#### Project>Options>C/C++ Compiler>Discard unused publics

## --dlib\_config

Syntax --dlib\_config filename.h|config

**Parameters** 

filename A DLIB configuration header file. For information about specifying

a filename, see Rules for specifying a filename or directory as

parameters, page 210.

config The default configuration file for the specified configuration will be

used. Choose between:

none, no configuration will be used

normal, the normal library configuration will be used (default)

full, the full library configuration will be used.

Description

Use this option to specify which library configuration to use, either by specifying an explicit file or by specifying a library configuration—in which case the default file for that library configuration will be used. Make sure that you specify a configuration that corresponds to the library you are using. If you do not specify this option, the default library configuration file will be used.

All prebuilt runtime libraries are delivered with corresponding configuration files. You can find the library object files and the library configuration files in the directory arm\lib. For examples and information about prebuilt runtime libraries, see *Using prebuilt libraries*, page 91.

If you build your own customized runtime library, you should also create a corresponding customized library configuration file, which must be specified to the compiler. For more information, see *Building and using a customized library*, page 101.



To set related options, choose:

Project>Options>General Options>Library Configuration

**-е** 

Syntax -e

Description In the command line version of the compiler, language extensions are disabled by

default. If you use language extensions such as extended keywords and anonymous structs and unions in your source code, you must use this option to enable them.

**Note:** The -e option and the --strict option cannot be used at the same time.

See also Enabling language extensions, page 145.

Project>Options>C/C++ Compiler>Language 1>Standard with IAR extensions

**Note:** By default, this option is selected in the IDE.

--ec++

Syntax --ec++

Description In the compiler, the default language is C. If you use Embedded C++, you must use this

option to set the language the compiler uses to Embedded C++.

Project>Options>C/C++ Compiler>Language 1>C++

and

Project>Options>C/C++ Compiler>Language 1>C++ dialect>Embedded C++

--eec++

Syntax --eec++

Description In the compiler, the default language is C. If you take advantage of Extended Embedded

C++ features like namespaces or the standard template library in your source code, you must use this option to set the language the compiler uses to Extended Embedded C++.

See also Extended Embedded C++, page 154.

Project>Options>C/C++ Compiler>Language 1>C++

and

Project>Options>C/C++ Compiler>Language 1>C++ dialect>Extended

Embedded C++

## -- enable hardware workaround

Syntax --enable\_hardware\_workaround=waid[,waid[...]]

**Parameters** 

waid The ID number of the workaround to enable. For a list of available

workarounds to enable, see the release notes.

Description Use this option to make the compiler generate a workaround for a specific hardware

problem.

See also The release notes for a list of available parameters.

X

To set this option, use **Project>Options>C/C++ Compiler>Extra Options**.

## --enable\_multibytes

Syntax --enable\_multibytes

Description By default, multibyte characters cannot be used in C or C++ source code. Use this option

to make multibyte characters in the source code be interpreted according to the host

computer's default setting for multibyte support.

Multibyte characters are allowed in C and C++ style comments, in string literals, and in

character constants. They are transferred untouched to the generated code.



#### Project>Options>C/C++ Compiler>Language 2>Enable multibyte support

#### --endian

Syntax --endian={big|b|little|1}

**Parameters** 

big, b Specifies big-endian as the default byte order

little, 1 (default) Specifies little-endian as the default byte order

Description Use this option to specify the byte order of the generated code and data. By default, the

compiler generates code in little-endian byte order.

See also Byte order, page 4, Byte order, page 276,.



#### Project>Options>General Options>Target>Endian mode

## --enum\_is\_int

Syntax --enum\_is\_int

Description Use this option to force the size of all enumeration types to be at least 4 bytes.

Note: This option will not consider the fact that an enum type can be larger than an

integer type.

See also The enum type, page 277.



To set this option, use **Project>Options>C/C++ Compiler>Extra Options**.

## --error\_limit

Syntax --error\_limit=n

n

Parameters

The number of errors before the compiler stops the compilation.

n must be a positive integer; 0 indicates no limit.

Description Use the --error\_limit option to specify the number of errors allowed before the

compiler stops the compilation. By default, 100 errors are allowed.



This option is not available in the IDE.

-f

Syntax -f filename

Parameters For information about specifying a filename, see *Rules for specifying a filename or* 

directory as parameters, page 210.

#### Descriptions

Use this option to make the compiler read command line options from the named file, with the default filename extension xcl.

In the command file, you format the items exactly as if they were on the command line itself, except that you may use multiple lines, because the newline character acts just as a space or tab character.

Both C and C++ style comments are allowed in the file. Double quotes behave in the same way as in the Microsoft Windows command line environment.



To set this option, use **Project>Options>C/C++ Compiler>Extra Options**.

## --fpu

Syntax --fpu={VFPv2|VFPv3|VFPv3\_d16|VFPv4|VFPv4\_sp|VFP9-S|none}

#### **Parameters**

	The second second second	VED 1: ( 1 1 1
VFPv2	For a system that implements a	VFP unit conforming to the

architecture VFPv2.

VFPv3 For a system that implements a VFP unit conforming to the

architecture VFPv3.

VFPv3\_d16 For a system that implements a VFP unit conforming to the D16

variant of the architecture VFPv3.

VFPv4 For a system that implements a VFP unit conforming to the

architecture VFPv4.

 $\label{eq:vfpv4_sp} VFPv4\_sp \qquad \qquad \text{For a system that implements a VFP unit conforming to the}$ 

single-precision variant of the architecture VFPv4.

VFP9-S VFP9-S is an implementation of the VFPv2 architecture that can be

used with the ARM9E family of CPU cores. Selecting the VFP9-S

coprocessor is therefore identical to selecting the VFPv2

architecture.

none (default) The software floating-point library is used.

#### Description

Use this option to generate code that performs floating-point operations using a Vector Floating Point (VFP) coprocessor. By selecting a VFP coprocessor, you will override the use of the software floating-point library for all supported floating-point operations.

See also

VFP and floating-point arithmetic, page 49.



Project>Options>General Options>Target>FPU

## --guard\_calls

Syntax --guard\_calls

Description Use this option to enable guards for function static variable initialization. This option

should be used in a threaded C++ environment.

See also *Managing a multithreaded environment*, page 117.



To set this option, use **Project>Options>C/C++ Compiler>Extra Options**.

### --header context

Syntax --header\_context

Description Occasionally, to find the cause of a problem it is necessary to know which header file

that was included from which source line. Use this option to list, for each diagnostic message, not only the source position of the problem, but also the entire include stack at

that point.



This option is not available in the IDE.

-I

Syntax -I path

**Parameters** 

path The search path for #include files

Description Use this option to specify the search paths for #include files. This option can be used

more than once on the command line.

See also *Include file search procedure*, page 203.



Project>Options>C/C++ Compiler>Preprocessor>Additional include directories

#### --interwork

Syntax --interwork

Description Use this option to generate interworking code.

In code compiled with this option, functions will by default be of the type interwork. It will be possible to mix files compiled as arm and thumb (using the --cpu\_mode option) as long as they are all compiled with the --interwork option.

**Note:** Source code compiled for an ARM architecture v5 or higher, or for AEABI compliance, is interworking by default.

See also

\_\_interwork, page 296.



### Project>Options>General Options>Target>Generate interwork code

-1

Syntax -1[a|A|b|B|c|C|D][N][H] {filename|directory}

#### **Parameters**

a (default)	Assembler list file
A	Assembler list file with C or C++ source as comments
b	Basic assembler list file. This file has the same contents as a list file produced with $-1a$ , except that no extra compiler-generated information (runtime model attributes, call frame information, frame size information) is included $^{*}$
В	Basic assembler list file. This file has the same contents as a list file produced with $-1A$ , except that no extra compiler generated information (runtime model attributes, call frame information, frame size information) is included $^{*}$
С	C or C++ list file
C (default)	C or C++ list file with assembler source as comments
D	C or C++ list file with assembler source as comments, but without instruction offsets and hexadecimal byte values
N	No diagnostics in file
Н	Include source lines from header files in output. Without this option, only source lines from the primary source file are included

<sup>\*</sup> This makes the list file less useful as input to the assembler, but more useful for reading by a human.

For information about specifying a filename or a directory, see *Rules for specifying a filename or directory as parameters*, page 210.

#### Description

Use this option to generate an assembler or C/C++ listing to a file. Note that this option can be used one or more times on the command line.



To set related options, choose:

#### Project>Options>C/C++ Compiler>List

## --legacy

Syntax --legacy={RVCT3.0}

**Parameters** 

RVCT3 . 0 Generates object code linkable with the linker in RVCT3.0. Use this

mode together with the --aeabi option to export code that

should be linked with the linker in RVCT3.0.

#### Description

Use this option to generate code compatible with older tool chains.



#### **Project>Options>C/C++ Compiler>Extra Options**

## --lock\_regs

Syntax --lock\_regs=registers

**Parameters** 

registers A comma-separated list of register names and register intervals to

be locked, in the range R4-R11.

Description Use this option to prevent the compiler from generating code that uses the specified

registers.

Example --lock\_regs=R4

--lock\_regs=R8-R11

--lock\_regs=R4,R8-R11



#### Project>Options>C/C++ Compiler>Extra Options

## --macro\_positions\_in\_diagnostics

Syntax --macro\_positions\_in\_diagnostics

Description Use this option to obtain position references inside macros in diagnostic messages. This

is useful for detecting incorrect source code constructs in macros.



To set this option, use **Project>Options>C/C++ Compiler>Extra Options**.

#### --mfc

Syntax --mfc

Description Use this option to enable *multi-file compilation*. This means that the compiler compiles

one or several source files specified on the command line as one unit, which enhances

interprocedural optimizations.

**Note:** The compiler will generate one object file per input source code file, where the first object file contains all relevant data and the other ones are empty. If you want only the first file to be produced, use the -o compiler option and specify a certain output file.

Example iccarm myfile1.c myfile2.c myfile3.c --mfc

See also --discard\_unused\_publics, page 223, --output, -o, page 241, and Multi-file compilation

units, page 187.



#### Project>Options>C/C++ Compiler>Multi-file compilation

# --migration\_preprocessor\_extensions

Syntax --migration\_preprocessor\_extensions

If you need to migrate code from an earlier IAR Systems C or C/C++ compiler, you might want to use this option. Use this option to use the following in preprocessor expressions:

TO ...

- Floating-point expressions
- Basic type names and sizeof
- All symbol names (including typedefs and variables).

**Note:** If you use this option, not only will the compiler accept code that does not conform to Standard C, but it will also reject some code that *does* conform to the standard.

Description

**Important!** Do not depend on these extensions in newly written code, because support for them might be removed in future compiler versions.



Project>Options>C/C++ Compiler>Language 1>Enable IAR migration preprocessor extensions

# --no\_clustering

Syntax --no\_clustering

**Description** Use this option to disable static clustering optimizations.

**Note:** This option has no effect at optimization levels below Medium.

See also Static clustering, page 191.



Project>Options>C/C++ Compiler>Optimizations>Enable transformations>Static clustering

## --no\_code\_motion

Syntax --no\_code\_motion

**Description** Use this option to disable code motion optimizations.

**Note:** This option has no effect at optimization levels below Medium.

See also *Code motion*, page 190.



Project>Options>C/C++ Compiler>Optimizations>Enable transformations>Code motion

# --no\_const\_align

Syntax --no\_const\_align

Description By default, the compiler uses alignment 4 for objects with a size of 4 bytes or more. Use

this option to make the compiler align const objects based on the alignment of their

type.

For example, a string literal will get alignment 1, because it is an array with elements of the type const char which has alignment 1. Using this option might save ROM space, possibly at the expense of processing speed.

See also *Alignment*, page 275.



To set this option, use **Project>Options>C/C++ Compiler>Extra Options**.

#### --no cse

Syntax --no\_cse

Description Use this option to disable common subexpression elimination.

**Note:** This option has no effect at optimization levels below Medium.

See also Common subexpression elimination, page 189.

X

Project>Options>C/C++ Compiler>Optimizations>Enable transformations>Common subexpression elimination

## --no\_exceptions

Syntax --no\_exceptions

Description Use this option to disable exception support in the C++ language. Exception statements

like throw and try-catch, and exception specifications on function definitions will generate an error message. Exception specifications on function declarations are ignored. The option is only valid when used together with the --c++ compiler option.

If exceptions are not used in your application, it is recommended to disable support for them by using this option, because exceptions cause a rather large increase in code size.

See also *Exception handling*, page 156.



Project>Options>C/C++ Compiler>Language 1>C++

and

Project>Options>C/C++ Compiler>Language 1>C++ dialect>C++>With exceptions

## --no\_fragments

Syntax --no\_fragments

Description Use this option to disable section fragment handling. Normally, the toolset uses IAR

proprietary information for transferring section fragment information to the linker. The linker uses this information to remove unused code and data, and thus further minimize the size of the executable image. The effect of using this option in the compiler is smaller

object size.

See also *Keeping symbols and sections*, page 81.



To set this option, use **Project>Options>C/C++ Compiler>Extra Options** 

### --no inline

Syntax --no\_inline

Description Use this option to disable function inlining.

**Note:** This option has no effect at optimization levels below High.

See also Function inlining, page 190.



**Project>Options>C/C++ Compiler>Optimizations>Enable transformations>Function inlining** 

# --no\_loop\_align

Syntax --no\_loop\_align

Description Use this option to disable the 4-byte alignment of labels in loops. This option is only

useful in Thumb2 mode.

In ARM/Thumb1 mode, this option is enabled but does not perform anything.

See also *Alignment*, page 275.



To set this option, use **Project>Options>C/C++ Compiler>Extra Options**.

## --no mem idioms

Syntax --no\_mem\_idioms

Description Use this option to make the compiler not optimize code sequences that clear, set, or copy

a memory region. These memory access patterns (idioms) can otherwise be aggressively optimized, in some cases using calls to the runtime library. In principle, the

transformation can involve more than a library call.

X

To set this option, use **Project>Options>C/C++ Compiler>Extra Options**.

## --no\_path\_in\_file\_macros

Syntax --no\_path\_in\_file\_macros

Description Use this option to exclude the path from the return value of the predefined preprocessor

symbols \_\_FILE\_\_ and \_\_BASE\_FILE\_\_.

See also Descriptions of predefined preprocessor symbols, page 366.

X

This option is not available in the IDE.

#### --no\_rtti

Syntax --no\_rtti

Description Use this option to disable the runtime type information (RTTI) support in the C++

language. RTTI statements like dynamic\_cast and typeid will generate an error message. This option is only valid when used together with the --c++ compiler option.

See also Using C++, page 153.

X

Project>Options>C/C++ Compiler>Language 1>C++

and

Project>Options>C/C++ Compiler>Language 1>C++ dialect>C++>With RTTI

## --no\_rw\_dynamic\_init

Syntax --no\_rw\_dynamic\_init

**Description** Use this option to disable runtime initialization of static C variables.

C source code that is compiled with --ropi or --rwpi cannot have static pointer variables and constants initialized to addresses of objects that do not have a known address at link time. To solve this for writable static variables, the compiler generates code that performs the initialization at program startup (in the same way as dynamic

initialization in C++).

See also --ropi, page 244 and --rwpi, page 245.



Project>Options>C/C++ Compiler>Code>No dynamic read/write initialization

# --no\_scheduling

Syntax --no\_scheduling

Description Use this option to disable the instruction scheduler.

**Note:** This option has no effect at optimization levels below High.

See also Instruction scheduling, page 191.



Project>Options>C/C++ Compiler>Optimizations>Enable transformations>Instruction scheduling

## --no\_static\_destruction

Syntax --no\_static\_destruction

Description Normally, the compiler emits code to destroy C++ static variables that require

destruction at program exit. Sometimes, such destruction is not needed.

Use this option to suppress the emission of such code.

See also Setting up the atexit limit, page 82.



To set this option, use **Project>Options>C/C++ Compiler>Extra Options**.

## --no\_system\_include

Syntax --no\_system\_include

Description By default, the compiler automatically locates the system include files. Use this option

to disable the automatic search for system include files. In this case, you might need to

set up the search path by using the -I compiler option.

See also --dlib\_config, page 224 and --system\_include\_dir, page 247.

X

Project>Options>C/C++ Compiler>Preprocessor>Ignore standard include directories

## --no\_tbaa

Syntax --no\_tbaa

Description Use this option to disable type-based alias analysis.

**Note:** This option has no effect at optimization levels below High.

See also *Type-based alias analysis*, page 190.

X

Project>Options>C/C++ Compiler>Optimizations>Enable transformations>Type-based alias analysis

# --no\_typedefs\_in\_diagnostics

Syntax --no\_typedefs\_in\_diagnostics

Description Use this option to disable the use of typedef names in diagnostics. Normally, when a

type is mentioned in a message from the compiler, most commonly in a diagnostic message of some kind, the typedef names that were used in the original declaration are

used whenever they make the resulting text shorter.

Example typedef int (\*MyPtr)(char const \*);

MyPtr p = "foo";

will give an error message like this:

Error[Pe144]: a value of type "char \*" cannot be used to

initialize an entity of type "MyPtr"

If the --no\_typedefs\_in\_diagnostics option is used, the error message will be like this:

Error[Pe144]: a value of type "char \*" cannot be used to initialize an entity of type "int (\*)(char const \*)"



To set this option, use **Project>Options>C/C++ Compiler>Extra Options**.

## --no\_unaligned\_access

Syntax --no\_unaligned\_access

**Description** Use this option to make the compiler avoid unaligned accesses. Data accesses are

usually performed aligned for improved performance. However, some accesses, most notably when reading from or writing to packed data structures, might be unaligned. When using this option, all such accesses will be performed using a smaller data size to avoid any unaligned accesses. This option is only useful for ARMv6 architectures and

higher.

See also Alignment, page 275.



To set this option, use **Project>Options>C/C++ Compiler>Extra Options**.

#### --no\_unroll

Syntax --no\_unroll

Description Use this option to disable loop unrolling.

**Note:** This option has no effect at optimization levels below High.

See also Loop unrolling, page 189.



Project>Options>C/C++ Compiler>Optimizations>Enable transformations>Loop unrolling

## --no\_warnings

Syntax --no\_warnings

Description By default, the compiler issues warning messages. Use this option to disable all warning

messages.

X

This option is not available in the IDE.

## --no\_wrap\_diagnostics

Syntax --no\_wrap\_diagnostics

Description By default, long lines in diagnostic messages are broken into several lines to make the

message easier to read. Use this option to disable line wrapping of diagnostic messages.



This option is not available in the IDE.

**-O** 

Syntax -O[n|1|m|h|hs|hz]

**Parameters** 

n None\* (Best debug support)

1 (default) Low\*

m Medium

h High, balanced
hs High, favoring speed
hz High, favoring size

\*The most important difference between None and Low is that at None, all non-static variables will live during their entire scope.

Description

Use this option to set the optimization level to be used by the compiler when optimizing the code. If no optimization option is specified, the optimization level Low is used by default. If only -0 is used without any parameter, the optimization level High balanced

is used.

A low level of optimization makes it relatively easy to follow the program flow in the debugger, and, conversely, a high level of optimization makes it relatively hard.

See also Controlling compiler optimizations, page 187.



#### **Project>Options>C/C++ Compiler>Optimizations**

## --only\_stdout

Syntax --only\_stdout

messages that are normally directed to the error output stream (stderr).

X

This option is not available in the IDE.

#### --output, -o

Syntax --output {filename | directory}

-o {filename|directory}

Parameters For information about specifying a filename or a directory, see *Rules for specifying a* 

filename or directory as parameters, page 210.

Description By default, the object code output produced by the compiler is located in a file with the

same name as the source file, but with the extension o. Use this option to explicitly

specify a different output filename for the object code output.



This option is not available in the IDE.

## --predef\_macros

Syntax --predef\_macros {filename | directory}

Parameters For information about specifying a filename, see *Rules for specifying a filename or* 

directory as parameters, page 210.

Description Use this option to list the predefined symbols. When using this option, make sure to also

use the same options as for the rest of your project.

If a filename is specified, the compiler stores the output in that file. If a directory is specified, the compiler stores the output in that directory, in a file with the predef filename extension.

Note that this option requires that you specify a source file on the command line.



This option is not available in the IDE.

## --preinclude

Syntax --preinclude includefile

Parameters For information about specifying a filename, see Rules for specifying a filename or

directory as parameters, page 210.

Description Use this option to make the compiler read the specified include file before it starts to

read the source file. This is useful if you want to change something in the source code

for the entire application, for instance if you want to define a new symbol.



#### Project>Options>C/C++ Compiler>Preprocessor>Preinclude file

## --preprocess

Syntax --preprocess[=[c][n][1]] {filename|directory}

**Parameters** 

C Preserve comments

n Preprocess only

1 Generate #line directives

For information about specifying a filename or a directory, see *Rules for specifying a* 

filename or directory as parameters, page 210.

Description Use this option to generate preprocessed output to a named file.



Project>Options>C/C++ Compiler>Preprocessor>Preprocessor output to file

## --public equ

Syntax --public equ symbol[=value]

**Parameters** 

symbol The name of the assembler symbol to be defined value An optional value of the defined assembler symbol

Description

This option is equivalent to defining a label in assembler language using the EOU directive and exporting it using the PUBLIC directive. This option can be used more than once on the command line.



This option is not available in the IDE.

## --relaxed\_fp

Syntax --relaxed\_fp

Description

Use this option to allow the compiler to relax the language rules and perform more aggressive optimization of floating-point expressions. This option improves performance for floating-point expressions that fulfill these conditions:

- The expression consists of both single- and double-precision values
- The double-precision values can be converted to single precision without loss of accuracy
- The result of the expression is converted to single precision.

Note that performing the calculation in single precision instead of double precision might cause a loss of accuracy.

Example

```
float F(float a, float b)
 return a + b * 3.0;
```

The C standard states that 3.0 in this example has the type double and therefore the whole expression should be evaluated in double precision. However, when the --relaxed\_fp option is used, 3.0 will be converted to float and the whole expression can be evaluated in float precision.



To set related options, choose:

Project>Options>C/C++ Compiler>Language 2>Floating-point semantics

243

#### --remarks

Syntax --remarks

Description The least severe diagnostic messages are called remarks. A remark indicates a source

code construct that may cause strange behavior in the generated code. By default, the compiler does not generate remarks. Use this option to make the compiler generate

remarks.

See also Severity levels, page 207.



#### Project>Options>C/C++ Compiler>Diagnostics>Enable remarks

## --require\_prototypes

Syntax --require\_prototypes

Description

Use this option to force the compiler to verify that all functions have proper prototypes.

Using this option means that code containing any of the following will generate an error:

- A function call of a function with no declaration, or with a Kernighan & Ritchie C declaration
- A function definition of a public function with no previous prototype declaration
- An indirect function call through a function pointer with a type that does not include a prototype.



#### Project>Options>C/C++ Compiler>Language 1>Require prototypes

### --ropi

Syntax --ropi

Description

Use this option to make the compiler generate code that uses PC-relative references to address code and read-only data.

When this option is used, these limitations apply:

- C++ constructions cannot be used
- The object attribute \_\_ramfunc cannot be used
- Pointer constants cannot be initialized with the address of another constant, a string literal, or a function. However, writable variables can be initialized to constant addresses at runtime.

See also

--no\_rw\_dynamic\_init, page 237, and Descriptions of predefined preprocessor symbols, page 366 for information about the preprocessor symbol \_\_ROPI\_\_.



Project>Options>C/C++ Compiler>Code>Code and read-only data (ropi)

#### --rwpi

Syntax

--rwpi

Description

Use this option to make the compiler generate code that uses the offset from the static base register (R9) to address-writable data.

When this option is used, these limitations apply:

- The object attribute \_\_ramfunc cannot be used
- Pointer constants cannot be initialized with the address of a writable variable.
   However, static writable variables can be initialized to writable variable addresses at runtime.

See also

--no\_rw\_dynamic\_init, page 237, and Descriptions of predefined preprocessor symbols, page 366 for information about the preprocessor symbol \_\_RWPI\_\_.



#### Project>Options>C/C++ Compiler>Code>Read/write data (rwpi)

#### --section

Syntax

--section OldName=NewName

Description

The compiler places functions and data objects into named sections which are referred to by the IAR ILINK Linker. Use this option to change the name of the section OldName to NewName.

This is useful if you want to place your code or data in different address ranges and you find the @ notation, alternatively the #pragma location directive, insufficient. Note that any changes to the section names require corresponding modifications in the linker configuration file.

Example

To place functions in the section MyText, use:

--section .text=MyText

See also *Controlling data and function placement in memory*, page 182.



#### Project>Options>C/C++ Compiler>Output>Code section name

## --separate\_cluster\_for\_initialized\_variables

Syntax --separate\_cluster\_for\_initialized\_variables

Description Use this option to separate initialized and non-initialized variables when using variable

clustering. This might reduce the number of bytes in the ROM area which are needed

for data initialization, but it might lead to larger code.

This option can be useful if you want to have your own data initialization routine, but

want the IAR tools to arrange for the zero-initialized variables.

See also *Manual initialization*, page 82 and *Initialize directive*, page 390.



To set this option, use **Project>Options>C/C++ Compiler>Extra Options**.

#### --silent

Syntax --silent

Description By default, the compiler issues introductory messages and a final statistics report. Use

this option to make the compiler operate without sending these messages to the standard

output stream (normally the screen).

This option does not affect the display of error and warning messages.



This option is not available in the IDE.

#### --strict

Syntax --strict

Description By default, the compiler accepts a relaxed superset of Standard C and C++. Use this

option to ensure that the source code of your application instead conforms to strict

Standard C and C++.

**Note:** The -e option and the --strict option cannot be used at the same time.

See also Enabling language extensions, page 145.



Project>Options>C/C++ Compiler>Language 1>Language conformance>Strict

## --system\_include\_dir

Syntax --system\_include\_dir path

**Parameters** 

path The path to the system include files. For information about

specifying a path, see Rules for specifying a filename or directory as

parameters, page 210.

Description By default, the compiler automatically locates the system include files. Use this option

to explicitly specify a different path to the system include files. This might be useful if

you have not installed IAR Embedded Workbench in the default location.

See also --dlib\_config, page 224 and --no\_system\_include, page 238.

X

This option is not available in the IDE.

#### --thumb

Syntax --thumb

Description Use this option to set default function mode to Thumb. This setting must be the same for

all files included in a program, unless they are interworking.

**Note:** This option has the same effect as the --cpu\_mode=thumb option.

See also --interwork, page 229 and \_\_interwork, page 296.

X

Project>Options>C/C++ Compiler>Code>Processor mode>Thumb

## --use\_c++\_inline

Syntax --use\_c++\_inline

Description

Standard C uses slightly different semantics for the inline keyword than C++ does. Use this option to get C++ semantics when compiling a Standard C source code file.

The main difference in semantics is that in Standard C you cannot in general simply supply an inline definition in a header file. You need to supply an external definition in one of the compilation units, possibly by designating the inline definition as being external in that compilation unit.



Project>Options>C/C++ Compiler>Language 1>C dialect>C99>C++ inline semantics

## --use\_unix\_directory\_separators

Syntax --use\_unix\_directory\_separators

separators in file paths.

This option can be useful if you have a debugger that requires directory separators in

UNIX style.



To set this option, use **Project>Options>C/C++ Compiler>Extra Options**.

--vla

Syntax --vla

Description Use this option to enable support for C99 variable length arrays. This option requires

Standard C and cannot be used together with the --c89 compiler option.

**Note:** --vla should not be used together with the longjmp library function, as that can lead to memory leakages.

See also *C language overview*, page 143.

Project>Options>C/C++ Compiler>Language 1>C dialect>Allow VLA

## --warnings\_affect\_exit\_code

Syntax --warnings\_affect\_exit\_code

Description By default, the exit code is not affected by warnings, because only errors produce a non-zero exit code. With this option, warnings will also generate a non-zero exit code.



This option is not available in the IDE.

## --warnings\_are\_errors

Syntax --warnings\_are\_errors

Description Use this option to make the compiler treat all warnings as errors. If the compiler

encounters an error, no object code is generated. Warnings that have been changed into

remarks are not treated as errors.

**Note:** Any diagnostic messages that have been reclassified as warnings by the option

 $\mbox{--diag\_warning}$  or the  $\mbox{\#pragma}$  diag\\_warning directive will also be treated as

errors when --warnings\_are\_errors is used.

See also --diag\_warning, page 223.



Project>Options>C/C++ Compiler>Diagnostics>Treat all warnings as errors

Descriptions of compiler options

# **Linker options**

This chapter gives detailed reference information about each linker option.

For general syntax rules, see Options syntax, page 209.

# **Summary of linker options**

This table summarizes the linker options:

Command line option	Description
basic_heap	Uses a basic heap instead of an advanced heap
BE8	Uses the big-endian format BE8
BE32	Uses the big-endian format BE32
config	Specifies the linker configuration file to be used by the linker
config_def	Defines symbols for the configuration file
cpp_init_routine	Specifies a user-defined C++ dynamic initialization routine
cpu	Specifies a processor variant
define_symbol	Defines symbols that can be used by the application
dependencies	Lists file dependencies
diag_error	Treats these message tags as errors
diag_remark	Treats these message tags as remarks
diag_suppress	Suppresses these diagnostic messages
diag_warning	Treats these message tags as warnings
diagnostics_tables	Lists all diagnostic messages
entry	Treats the symbol as a root symbol and as the start of the application
error_limit	Specifies the allowed number of errors before linking stops
exception_tables	Generates exception tables for C code
export_builtin_config	Produces an icf file for the default configuration

Table 27: Linker options summary

Command line option	Description
extra_init	Specifies an extra initialization routine that will be
	called if it is defined.
-f	Extends the command line
force_exceptions	Always includes exception runtime code
force_output	Produces an output file even if errors occurred
image_input	Puts an image file in a section
inline	Inlines small routines
keep	Forces a symbol to be included in the application
log	Enables log output for selected topics
log_file	Directs the log to a file
mangled_names_in_messages	Adds mangled names in messages
map	Produces a map file
misrac1998	Enables error messages specific to MISRA-C:1998. See the IAR Embedded Workbench® MISRA C:1998 Reference Guide.
misrac2004	Enables error messages specific to MISRA-C:2004. See the IAR Embedded Workbench® MISRA C:2004 Reference Guide.
misrac_verbose	Enables verbose logging of MISRA C checking. See the IAR Embedded Workbench® MISRA C:1998 Reference Guide and the IAR Embedded Workbench® MISRA C:2004 Reference Guide.
no_dynamic_rtti_elimination	Includes dynamic runtime type information even when it is not needed.
no_exceptions	Generates an error if exceptions are used
no_fragments	Disables section fragment handling
no_library_search	Disables automatic runtime library search
no_locals	Removes local symbols from the ELF executable image.
no_range_reservations	Disables range reservations for absolute symbols
no_remove	Disables removal of unused sections
no_veneers	Disables generation of veneers
no_vfe	Disables Virtual Function Elimination
no_warnings	Disables generation of warnings

Table 27: Linker options summary (Continued)

Command line option	Description
no_wrap_diagnostics	Does not wrap long lines in diagnostic messages
-0	Sets the object filename. Alias foroutput.
only_stdout	Uses standard output only
output	Sets the object filename
pi_veneers	Generates position independent veneers.
place_holder	Reserve a place in ROM to be filled by some other tool, for example a checksum calculated by ielftool.
redirect	Redirects a reference to a symbol to another symbol
remarks	Enables remarks
search	Specifies more directories to search for object and library files
semihosting	Links with debug interface
silent	Sets silent operation
strip	Removes debug information from the executable image
vfe	Controls Virtual Function Elimination
warnings_affect_exit_code	Warnings affects exit code
warnings_are_errors	Warnings are treated as errors

Table 27: Linker options summary (Continued)

# **Descriptions of linker options**

The following section gives detailed reference information about each compiler and linker option.



Note that if you use the options page **Extra Options** to specify specific command line options, the IDE does not perform an instant check for consistency problems like conflicting options, duplication of options, or use of irrelevant options.

# --basic\_heap

Syntax --basic\_heap

Description

Use this option to use a basic heap instead of an advanced heap. The basic heap introduces less overhead and is suitable for example in applications that only allocates

heap memory, but never calls free. For any other use of the heap, the advanced heap is usually more efficient.



To set this option, use **Project>Options>Linker>Extra Options**.

#### --BE8

Syntax --BE8

Description Use this option to specify the Byte Invariant Addressing mode.

This means that the linker reverses the byte order of the instructions, resulting in little-endian code and big-endian data. This is the default byte addressing mode for ARMv6 big-endian images. This is the only mode available for ARM v6M and ARM v7 with big-endian images.

Byte Invariant Addressing mode is only available on ARM processors that support ARMv6, ARM v6M, and ARM v7.

See also Byte order, page 49, Byte order, page 276, --BE32, page 254, and --endian, page 226.



### Project>Options>General Options>Target>Endian mode

#### --BE32

Syntax --BE32

**Description** Use this option to specify the legacy big-endian mode.

This produces big-endian code and data. This is the only byte-addressing mode for all big-endian images prior to ARMv6. This mode is also available for ARM v6 with big endian but not for APM v6M or APM v7.

big-endian, but not for ARM v6M or ARM v7.

See also Byte order, page 49, Byte order, page 276, --BE8, page 254, and --endian, page 226.



Project>Options>General Options>Target>Endian mode

# --config

Syntax --config filename

Parameters For information about specifying a filename, see *Rules for specifying a filename or* 

directory as parameters, page 210.

Description Use this option to specify the configuration file to be used by the linker (the default

filename extension is icf). If no configuration file is specified, a default configuration

is used. This option can only be used once on the command line.

See also The chapter *The linker configuration file*.



### Project>Options>Linker>Config>Linker configuration file

# --config\_def

Syntax --config\_def symbol[=constant\_value]

**Parameters** 

symbol The name of the symbol to be used in the configuration file. By

default, the value 0 (zero) is used.

 $constant\_value \qquad \qquad \textbf{The constant value of the configuration symbol}.$ 

Description Use this option to define a constant configuration symbol to be used in the configuration

file. This option has the same effect as the define symbol directive in the linker configuration file. This option can be used more that once on the command line.

See also --define\_symbol, page 256 and Interaction between ILINK and the application, page 85.



#### Project>Options>Linker>Config>Defined symbols for configuration file

# --cpp\_init\_routine

Syntax --cpp\_init\_routine routine

**Parameters** 

routine A user-defined C++ dynamic initialization routine.

Description When using the IAR C/C++ compiler and the standard library, C++ dynamic

initialization is handled automatically. In other cases you might need to use this option.

If any sections with the section type INIT\_ARRAY or PREINIT\_ARRAY are included in your application, the C++ dynamic initialization routine is considered to be needed. By default, this routine is named \_\_iar\_cstart\_call\_ctors and is called by the startup code in the standard library. Use this option if you are not using the standard library and require another routine to handle these section types.



To set this option, use **Project>Options>Linker>Extra Options**.

#### --cpu

Syntax --cpu=core

**Parameters** 

core Specifies a specific processor variant

Description Use this option to select the processor variant for which the code is to be generated. The

default is ARM7TDMI.

See also --cpu, page 218 for a list of recognized cores and processor macrocells.



### Project>Options>General Options>Target>Processor configuration

# --define\_symbol

Syntax --define\_symbol symbol=constant\_value

**Parameters** 

symbol The name of the constant symbol that can be used by the

application.

constant\_value The constant value of the symbol.

Description Use this option to define a constant symbol, that is a label, that can be used by your

application. This option can be used more than once on the command line. Note that his

option is different from the define symbol directive.

See also --config\_def, page 255 and Interaction between ILINK and the application, page 85.



Project>Options>Linker>#define>Defined symbols

# --dependencies

**Parameters** 

i (default) Lists only the names of files

m Lists in makefile style

For information about specifying a filename or a directory, see *Rules for specifying a filename or directory as parameters*, page 210.

Description

Use this option to make the linker list the names of the linker configuration, object, and library files opened for input into a file with the default filename extension i.

Example

If --dependencies or --dependencies=i is used, the name of each opened input file, including the full path, if available, is output on a separate line. For example:

```
c:\myproject\foo.o
d:\myproject\bar.o
```

If --dependencies=m is used, the output is in makefile style. For each input file, one line containing a makefile dependency rule is produced. Each line consists of the name of the output file, a colon, a space, and the name of an input file. For example:

```
a.out: c:\myproject\foo.o
a.out: d:\myproject\bar.o
```



This option is not available in the IDE.

# --diag\_error

Syntax --diag\_error=tag[,tag,...]

**Parameters** 

tag The number of a diagnostic message, for example the message

number Pe117

Description

Use this option to reclassify certain diagnostic messages as errors. An error indicates a problem of such severity that an executable image will not be generated. The exit code will be non-zero. This option may be used more than once on the command line.



Project>Options>Linker>Diagnostics>Treat these as errors

# --diag\_remark

Syntax --diag\_remark=tag[,tag,...]

**Parameters** 

tag The number of a diagnostic message, for example the message

number Pe177

Description Use this option to reclassify certain diagnostic messages as remarks. A remark is the

least severe type of diagnostic message and indicates a construction that may cause strange behavior in the executable image. This option may be used more than once on

the command line.

**Note:** By default, remarks are not displayed; use the --remarks option to display

them.



#### Project>Options>Linker>Diagnostics>Treat these as remarks

# --diag\_suppress

Syntax --diag\_suppress=tag[,tag,...]

**Parameters** 

tag The number of a diagnostic message, for example the message

number Pe117

Description Use this option to suppress certain diagnostic messages. These messages will not be

displayed. This option may be used more than once on the command line.



#### Project>Options>Linker>Diagnostics>Suppress these diagnostics

# --diag\_warning

Syntax --diag\_warning=tag[,tag,...]

**Parameters** 

tag The number of a diagnostic message, for example the message

number Pe826

**Description** Use this option to reclassify certain diagnostic messages as warnings. A warning

indicates an error or omission that is of concern, but which will not cause the linker to

stop before linking is completed. This option may be used more than once on the command line.



#### Project>Options>Linker>Diagnostics>Treat these as warnings

# --diagnostics\_tables

Syntax --diagnostics\_tables {filename | directory}

Parameters For information about specifying a filename or a directory, see *Rules for specifying a* 

filename or directory as parameters, page 210.

Description Use this option to list all possible diagnostic messages in a named file.

This option cannot be given together with other options.



This option is not available in the IDE.

# --entry

Syntax --entry symbol

**Parameters** 

symbol The name of the symbol to be treated as a root symbol and start

label

Description Use this option to make a symbol be treated as a root symbol and the start label of the

application. This is useful for loaders. If this option is not used, the default start symbol is \_\_iar\_program\_start. A root symbol is kept whether or not it is referenced from the rest of the application, provided its module is included. A module in an object file is

always included and a module part of a library is only included if needed.



#### Project>Options>Linker>Library>Override default program entry

#### --error limit

Syntax --error\_limit=n

n

**Parameters** 

The number of errors before the linker stops linking. n must be a

positive integer; 0 indicates no limit.

Description

Use the --error\_limit option to specify the number of errors allowed before the linker stops the linking. By default, 100 errors are allowed.



This option is not available in the IDE.

# --exception tables

Syntax --exception\_tables={nocreate|unwind|cantunwind}

**Parameters** 

nocreate (default) Does not generate entries. Uses the least amount of memory, but

the result is undefined if an exception is propagated through a

function without exception information.

unwind Generates unwind entries that enable an exception to be correctly

propagated through functions without exception information.

cantunwind Generates no-unwind entries so that any attempt to propagate an

exception through the function will result in a call to terminate.

Description Use this option to determine what the linker should do with functions that do not have

exception information but which do have correct call frame information.

The compiler ensures that C functions get correct call frame information. For functions written in assembler language you need to use assembler directives to generate call

frame information.

See also Using C++, page 153.



To set this option, use **Project>Options>Linker>Extra Options**.

# --export\_builtin\_config

Syntax --export\_builtin\_config filename

Parameters For information about specifying a filename, see *Rules for specifying a filename or* 

directory as parameters, page 210.

**Description** Exports the configuration used by default to a file.



This option is not available in the IDE.

### --extra init

Syntax --extra\_init routine

**Parameters** 

routine A user-defined initialization routine.

Description

Use this option to make the linker add an entry for the specified routine at the end of the initialization table. The routine will be called during system startup, after other initialization routines have been called and before main is called. Note that the routine must preserve the value passed to it in register R0. No entry is added if the routine is not defined.



To set this option, use **Project>Options>Linker>Extra Options**.

-f

Syntax -f filename

Parameters For information about specifying a filename, see *Rules for specifying a filename or* 

directory as parameters, page 210.

Descriptions Use this option to make the linker read command line options from the named file, with

the default filename extension xcl.

In the command file, you format the items exactly as if they were on the command line itself, except that you may use multiple lines, because the newline character acts just as a space or tab character.

Both C and C++ style comments are allowed in the file. Double quotes behave in the same way as in the Microsoft Windows command line environment.



To set this option, use **Project>Options>Linker>Extra Options**.

# --force\_exceptions

Syntax --force\_exceptions

Description Use this option to make the linker include exception tables and exception code even

when the linker heuristics indicate that exceptions are not used.

The linker considers exceptions to be used if there is a throw expression that is not a rethrow in the included code. If there is no such throw expression in the rest of the

code, the linker arranges for operator new, dynamic\_cast, and typeid to call abort instead of throwing an exception on failure. If you need to catch exceptions from these constructs but your code contains no other throws, you might need to use this option.

See also

Using C++, page 153.



#### Project>Options>Linker>Optimizations>C++ Exceptions>Allow>Always include

# --force output

Syntax --force\_output

**Description** Use this option to produce an output executable image regardless of any linking errors.



To set this option, use Project>Options>Linker>Extra Options

# --image\_input

Syntax --image\_input filename [, symbol, [section[, alignment]]]

**Parameters** 

The pure binary file containing the raw image you want to link

symbol
The symbol which the binary data can be referenced with.

section
The section where the binary data will be placed; default is .text.

Description

Use this option to link pure binary files in addition to the ordinary input files. The file's entire contents are placed in the section, which means it can only contain pure binary

The alignment of the section; default is 1.

data.

alignment

The section where the contents of the filename file are placed, is only included if the symbol symbol is required by your application. Use the --keep option if you want to force a reference to the section.

Torce a reference to the section

Example --image\_input bootstrap.abs,Bootstrap,CSTARTUPCODE,4

The contents of the pure binary file bootstrap.abs are placed in the section CSTARTUPCODE. The section where the contents are placed is 4-byte aligned and will only be included if your application (or the command line option --keep) includes a reference to the symbol Bootstrap.

See also --keep, page 263.



### Project>Options>Linker>Input>Raw binary image

#### --inline

Syntax --inline

Description Some routines are so small that they can fit in the space of the instruction that calls the

routine. Use this option to make the linker replace the call of a routine with the body of

the routine, where applicable.



#### Project>Options>Linker>Optimizations>Inline small routines

# --keep

Syntax --keep symbol

Parameters

symbol The name of the symbol to be treated as a root symbol

Description Normally, the linker keeps a symbol only if it is needed by your application. Use this

option to make a symbol always be included in the final application.



#### Project>Options>Linker>Input>Keep symbols

# --log

Syntax --log topic[,topic,...]

Parameters topic can be one of:

initialization Lists copy batches and the compression selected for each batch.

libraries Lists all decisions taken by the automatic library selector. This

might include extra symbols needed (--keep), redirections (--redirect), as well as which runtime libraries that were

selected.

modules Lists each module that is selected for inclusion in the application,

and which symbol that caused it to be included.

redirects Lists redirected symbols.

sections Lists each symbol and section fragment that is selected for

inclusion in the application, and the dependence that caused it to

be included.

unused fragments Lists those section fragments that were not included in the

application.

veneers Lists some veneer creation and usage statistics.

Description Use this option to make the linker log information to stdout. The log information can

be useful for understanding why an executable image became the way it is.

See also --log\_file, page 264.



#### Project>Options>Linker>List>Generate log

# --log\_file

Syntax --log\_file filename

Parameters For information about specifying a filename, see *Rules for specifying a filename or* 

directory as parameters, page 210.

**Description** Use this option to direct the log output to the specified file.

See also --log, page 263.



#### Project>Options>Linker>List>Generate log

# --mangled\_names\_in\_messages

Syntax --mangled\_names\_in\_messages

Descriptions Use this option to produce both mangled and unmangled names for C/C++ symbols in

messages. Mangling is a technique used for mapping a complex C name or a C++ name (for example, for overloading) into a simple name. For example, void h(int, char)

becomes \_Z1hic.

X

This option is not available in the IDE.

#### --map

Syntax

--map {filename|directory}

Description

Use this option to produce a linker memory map file. The map file has the default filename extension map. The map file contains:

- Linking summary in the map file header which lists the version of the linker, the current date and time, and the command line that was used.
- Runtime attribute summary which lists runtime attributes.
- Placement summary which lists each section/block in address order, sorted by placement directives.
- Initialization table layout which lists the data ranges, packing methods, and compression ratios.
- Module summary which lists contributions from each module to the image, sorted by directory and library.
- Entry list which lists all public and some local symbols in alphabetical order, indicating which module they came from.
- Some of the bytes might be reported as *shared*.

Shared objects are functions or data objects that are shared between modules. If any of these occur in more than one module, only one copy is retained. For example, in some cases inline functions are not inlined, which means that they are marked as shared, because only one instance of each function will be included in the final application. This mechanism is sometimes also used for compiler-generated code or data not directly associated with a particular function or variable, and when only one instance is required in the final application.

This option can only be used once on the command line.



#### Project>Options>Linker>List>Generate linker map file

# --no\_dynamic\_rtti\_elimination

Syntax

--no\_dynamic\_rtti\_elimination

Description

Use this option to make the linker include dynamic (polymorphic) runtime type information (RTTI) data in the application image even when the linker heuristics indicate that it is not needed.

The linker considers dynamic runtime type information to be needed if there is a typeid or dynamic\_cast expression for a polymorphic type in the included code. By

default, if the linker detects no such expression, RTTI data will not be included just to make dynamic RTTI requests work.

**Note:** A typeid expression for a *non*-polymorphic type results in a direct reference to a particular RTTI object and will not cause the linker to include any potentially unneeded objects.

See also Using C++, page 153.



To set this option, use **Project>Options>Linker>Extra Options**.

# --no\_exceptions

Syntax --no\_exceptions

**Description** Use this option to make the linker generate an error if there is a throw in the included

code. This option is useful for making sure that your application does not use

exceptions.

See also Using C++, page 153.



To set related options, choose:

Project>Options>Linker>Optimizations>C++ Exceptions>Allow

# --no\_fragments

Syntax --no\_fragments

Description Use this option to disable section fragment handling. Normally, the toolset uses IAR

proprietary information for transferring section fragment information to the linker. The linker uses this information to remove unused code and data, and thus further minimize

the size of the executable image.

See also *Keeping symbols and sections*, page 81.



To set this option, use Project>Options>Linker>Extra Options

# --no\_library\_search

Syntax --no\_library\_search

Description

Use this option to disable the automatic runtime library search. This option turns off the automatic inclusion of the correct standard libraries. This is useful, for example, if the application needs a user-built standard library, etc.

Note that the option disables all steps of the automatic library selection, some of which might need to be reproduced if you are using the standard libraries. Use the

--log libraries linker option together with automatic library selection enabled to determine which the steps are.



#### Project>Options>Linker>Library>Automatic runtime library selection

### --no\_locals

Syntax --no\_locals

Description Use this option to remove local symbols from the ELF executable image.

**Note:** This option does not remove any local symbols from the DWARF information in the executable image.



#### Project>Options>Linker>Output

# --no\_range\_reservations

Syntax --no\_range\_reservations

Description Normally, the linker reserves any ranges used by absolute symbols with a non-zero size,

excluding them from consideration for place in commands.

When this option is used, these reservations are disabled, and the linker is free to place sections in such a way as to overlap the extent of absolute symbols.



To set this option, use **Project>Options>Linker>Extra Options**.

#### --no remove

Syntax --no\_remove

Description When this option is used, unused sections are not removed. In other words, each module

that is included in the executable image contains all its original sections.

See also *Keeping symbols and sections*, page 81.



To set this option, use **Project>Options>Linker>Extra Options**.

#### --no veneers

Syntax --no\_veneers

**Description** Use this option to disable the insertion of veneers even though the executable image

needs it. In this case, the linker will generate a relocation error for each reference that

needs a veneer.

See also *Veneers*, page 86.



To set this option, use **Project>Options>C/C++ Compiler>Extra Options**.

# --no\_vfe

Syntax --no\_vfe

Description Use this option to disable the Virtual Function Elimination optimization. All virtual

functions in all classes with at least one instance will be kept, and Runtime Type Information data will be kept for all polymorphic classes. Also, no warning message will

be issued for modules that lack VFE information.

See also --vfe, page 273 and Virtual Function Elimination, page 174.



To set related options, choose:

Project>Options>Linker>Optimizations>Perform C++ Virtual Function Elimination

# --no\_warnings

Syntax --no\_warnings

Description By default, the linker issues warning messages. Use this option to disable all warning

messages.

X

This option is not available in the IDE.

# --no\_wrap\_diagnostics

Syntax --no\_wrap\_diagnostics

Description By default, long lines in diagnostic messages are broken into several lines to make the

message easier to read. Use this option to disable line wrapping of diagnostic messages.



This option is not available in the IDE.

# --only\_stdout

Syntax --only\_stdout

Description Use this option to make the linker use the standard output stream (stdout) also for

messages that are normally directed to the error output stream (stderr).



This option is not available in the IDE.

# --output, -o

Syntax --output {filename|directory}

-o {filename|directory}

Parameters For information about specifying a filename or a directory, see *Rules for specifying a* 

filename or directory as parameters, page 210.

Description By default, the object executable image produced by the linker is located in a file with

the name a . out. Use this option to explicitly specify a different output filename, which

by default will have the filename extension out.



Project>Options>Linker>Output>Output file

# --pi\_veneers

Syntax --pi\_veneers

Description Use this option to make the linker generate position-independent veneers. Note that this

type of veneers is bigger and slower than normal veneers.

See also *Veneers*, page 86.



To set this option, use **Project>Options>C/C++ Compiler>Extra Options**.

# --place\_holder

Syntax --place\_holder symbol[,size[,section[,alignment]]]

**Parameters** 

symbol The name of the symbol to create

size Size in ROM; by default 4 bytes

 ${\it section} \qquad \qquad {\it Section name to use; by default .} {\it text}$ 

alignment Alignment of section; by default 1

Description Use this option to reserve a place in ROM to be filled by some other tool, for example a

checksum calculated by ielftool. Each use of this linker option results in a section with the specified name, size, and alignment. The symbol can be used by your

application to refer to the section.

**Note:** Like any other section, sections created by the <code>--place\_holder</code> option will only be included in your application if the section appears to be needed. The <code>--keep</code> linker option, or the <code>keep</code> linker directive can be used for forcing such section to be

included.

See also *IAR utilities*, page 409.



To set this option, use Project>Options>Linker>Extra Options

### --redirect

Syntax --redirect from\_symbol=to\_symbol

**Parameters** 

from\_symbol The name of the source symbol

to\_symbol The name of the destination symbol

**Description** Use this option to change a reference from one symbol to another symbol.



To set this option, use Project>Options>Linker>Extra Options

#### --remarks

Syntax --remarks

Description The least severe diagnostic messages are called remarks. A remark indicates a source

code construct that may cause strange behavior in the generated code. By default, the linker does not generate remarks. Use this option to make the linker generate remarks.

See also Severity levels, page 207.



#### Project>Options>Linker>Diagnostics>Enable remarks

#### --search

Syntax --search path

Parameters

path

A path to a directory where the linker should search for object

and library files.

**Description** Use this option to specify more directories for the linker to search for object and library

files in.

By default, the linker searches for object and library files only in the working directory.

Each use of this option on the command line adds another search directory.

See also The linking process, page 69.



This option is not available in the IDE.

# --semihosting

Syntax --semihosting[=iar\_breakpoint]

**Parameters** 

iar\_breakpoint The IAR-specific mechanism can be used when debugging

applications that use SWI/SVC extensively.

Description Use this option to include the debug interface—breakpoint mechanism—in the output

image. If no parameter is specified, the SWI/SVC mechanism is included for

ARM7/9/11, and the BKPT mechanism is included for Cortex-M.

See also *Application debug support*, page 97.



### Project>Options>General Options>Library Configuration>Semihosted

### --silent

Syntax --silent

Description By default, the linker issues introductory messages and a final statistics report. Use this

option to make the linker operate without sending these messages to the standard output

stream (normally the screen).

This option does not affect the display of error and warning messages.



This option is not available in the IDE.

# --strip

Syntax --strip

Description By default, the linker retains the debug information from the input object files in the

output executable image. Use this option to remove that information.



To set related options, choose:

Project>Options>Linker>Output>Include debug information in output

### --vfe

Syntax --vfe[=forced]

**Parameters** 

forced Performs Virtual Function Elimination even if one or more

modules lack the needed virtual function elimination information.

Description Use this option to enable the Virtual Function Elimination optimization. By default, this

optimization is enabled.

Forcing the use of Virtual Function Elimination can be unsafe if some of the modules that lack the needed information perform virtual function calls or use dynamic Runtime

Type Information.

See also --no\_vfe, page 268 and Virtual Function Elimination, page 174.



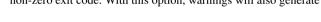
To set related options, choose:

Project>Options>Linker>Optimizations>Perform C++ Virtual Function Elimination

# --warnings\_affect\_exit\_code

Syntax --warnings\_affect\_exit\_code

Description By default, the exit code is not affected by warnings, because only errors produce a non-zero exit code. With this option, warnings will also generate a non-zero exit code.





This option is not available in the IDE.

# --warnings\_are\_errors

Syntax --warnings\_are\_errors

Description Use this option to make the linker treat all warnings as errors. If the linker encounters

an error, no executable image is generated. Warnings that have been changed into

remarks are not treated as errors.

**Note:** Any diagnostic messages that have been reclassified as warnings by the option

--diag\_warning directive will also be treated as errors when

--warnings\_are\_errors is used.

See also

--diag\_warning, page 258 and --diag\_warning, page 223.



Project>Options>Linker>Diagnostics>Treat all warnings as errors

# **Data representation**

This chapter describes the data types, pointers, and structure types supported by the compiler.

See the chapter Efficient coding for embedded applications for information about which data types and pointers provide the most efficient code for your application.

# **Alignment**

Every C data object has an alignment that controls how the object can be stored in memory. Should an object have an alignment of, for example, 4, it must be stored on an address that is divisible by 4.

The reason for the concept of alignment is that some processors have hardware limitations for how the memory can be accessed.

Assume that a processor can read 4 bytes of memory using one instruction, but only when the memory read is placed on an address divisible by 4. Then, 4-byte objects, such as long integers, will have alignment 4.

Another processor might only be able to read 2 bytes at a time; in that environment, the alignment for a 4-byte long integer might be 2.

A structure type will have the same alignment as the structure member with the most strict alignment To decrease the alignment requirements on the structure and its members, use #pragma\_pack or the \_\_packed data type attribute.

All data types must have a size that is a multiple of their alignment. Otherwise, only the first element of an array would be guaranteed to be placed in accordance with the alignment requirements. This means that the compiler might add pad bytes at the end of the structure. For more information about pad bytes, see *Packed structure types*, page 286.

Note that with the  $\#pragma\ data\_alignment\ directive\ you\ can\ increase\ the\ alignment\ demands\ on\ specific\ variables.$ 

#### **ALIGNMENT ON THE ARM CORE**

The alignment of a data object controls how it can be stored in memory. The reason for using alignment is that the ARM core can access 4-byte objects more efficiently when the object is stored at an address divisible by 4.

Objects with alignment 4 must be stored at an address divisible by 4, while objects with alignment 2 must be stored at addresses divisible by 2.

The compiler ensures this by assigning an alignment to every data type, ensuring that the ARM core will be able to read the data.

For related information, see --align\_sp\_on\_irq, page 216 and --no\_const\_align, page 233.

# **Byte order**

The ARM core stores data in either little-endian or big-endian byte order. To specify the byte order, use the --endian compiler option; see --endian, page 226.

In the little-endian byte order, which is default, the *least* significant byte is stored at the lowest address in memory. The *most* significant byte is stored at the highest address.

In the big-endian byte order, the *most* significant byte is stored at the lowest address in memory. The *least* significant byte is stored at the highest address. If you use the big-endian byte order, it might be necessary to use the

#pragma bitfields=reversed directive to be compatible with code for other compilers and I/O register definitions of some devices, see *Bitfields*, page 278.

**Note:** There are two variants of the big-endian mode, BE8 and BE32, which you specify at link time. In BE8 data is big-endian and code is little-endian. In BE32 both data and code are big-endian. In architectures before v6, the BE32 endian mode is used, and after v6 the BE8 mode is used. In the v6 (ARM11) architecture, both big-endian modes are supported.

# **Basic data types**

The compiler supports both all Standard C basic data types and some additional types.

#### **INTEGER TYPES**

This table gives the size and range of each integer data type:

Data type	Size	Range	Alignment
bool	8 bits	0 to I	I
char	8 bits	0 to 255	1
signed char	8 bits	-128 to 127	1
unsigned char	8 bits	0 to 255	1

Table 28: Integer types

Data type	Size	Range	Alignment
signed short	16 bits	-32768 to 32767	2
unsigned short	16 bits	0 to 65535	2
signed int	32 bits	-2 <sup>31</sup> to 2 <sup>31</sup> -1	4
unsigned int	32 bits	0 to 2 <sup>32</sup> -I	4
signed long	32 bits	-2 <sup>31</sup> to 2 <sup>31</sup> -1	4
unsigned long	32 bits	0 to 2 <sup>32</sup> -I	4
signed long long	64 bits	-2 <sup>63</sup> to 2 <sup>63</sup> -1	8
unsigned long long	64 bits	0 to 2 <sup>64</sup> -1	8

Table 28: Integer types (Continued)

Signed variables are represented using the two's complement form.

#### Bool

The bool data type is supported by default in the C++ language. If you have enabled language extensions, the bool type can also be used in C source code if you include the file stdbool.h. This will also enable the boolean values false and true.

# The enum type

The compiler will use the smallest type required to hold enum constants, preferring signed rather than unsigned.

When IAR Systems language extensions are enabled, and in C++, the enum constants and types can also be of the type long, unsigned long, long long, or unsigned long long.

To make the compiler use a larger type than it would automatically use, define an enum constant with a large enough value. For example:

For related information, see --enum\_is\_int, page 227.

# The char type

The char type is by default unsigned in the compiler, but the --char\_is\_signed compiler option allows you to make it signed. Note, however, that the library is compiled with the char type as unsigned.

### The wchar\_t type

The wchar\_t data type is an integer type whose range of values can represent distinct codes for all members of the largest extended character set specified among the supported locals.

The wchar\_t data type is supported by default in the C++ language. To use the wchar\_t type also in C source code, you must include the file stddef.h from the runtime library.

#### **Bitfields**

In Standard C, int, signed int, and unsigned int can be used as the base type for integer bitfields. In standard C++, and in C when language extensions are enabled in the compiler, any integer or enumeration type can be used as the base type. It is implementation defined whether a plain integer type (char, short, int, etc) results in a signed or unsigned bitfield.

In the IAR C/C++ Compiler for ARM, plain integer types are treated as unsigned.

Bitfields in expressions are treated as int if int can represent all values of the bitfield. Otherwise, they are treated as the bitfield base type.

Each bitfield is placed in the next container of its base type that has enough available bits to accommodate the bitfield. Within each container, the bitfield is placed in the first available byte or bytes, taking the byte order into account.

In addition, the compiler supports an alternative bitfield allocation strategy (disjoint types), where bitfield containers of different types are not allowed to overlap. Using this allocation strategy, each bitfield is placed in a new container if its type is different from that of the previous bitfield, or if the bitfield does not fit in the same container as the previous bitfield. Within each container, the bitfield is placed from the least significant bit to the most significant bit (disjoint types) or from the most significant bit to the least significant bit (reverse disjoint types). This allocation strategy will never use less space than the default allocation strategy (joined types), and can use significantly more space when mixing bitfield types.

Use the #pragma bitfield directive to choose which bitfield allocation strategy to use, see *bitfields*, page 307.

## Example

Assume this example:

```
struct BitfieldExample
{
  uint32_t a : 12;
  uint16_t b : 3;
  uint16_t c : 7;
  uint8_t d;
};
```

### The example in the joined types bitfield allocation strategy

To place the first bitfield, a, the compiler allocates a 32-bit container at offset 0 and puts a into the first and second bytes of the container.

For the second bitfield, b, a 16-bit container is needed and because there are still four bits free at offset 0, the bitfield is placed there.

For the third bitfield, c, as there is now only one bit left in the first 16-bit container, a new container is allocated at offset 2, and c is placed in the first byte of this container.

The fourth member, d, can be placed in the next available full byte, which is the byte at offset 3.

In little-endian mode, each bitfield is allocated starting from the least significant free bit of its container to ensure that it is placed into bytes from left to right.

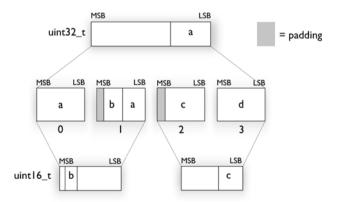


Figure 14: Layout of bitfield members for joined types in little-endian mode

In big-endian mode, each bitfield is allocated starting from the most significant free bit of its container to ensure that it is placed into bytes from left to right.

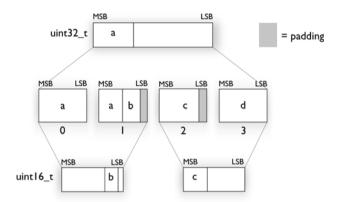


Figure 15: Layout of bitfield members for joined types in big-endian mode

#### The example in the disjoint types bitfield allocation strategy

To place the first bitfield, a, the compiler allocates a 32-bit container at offset 0 and puts a into the least significant 12 bits of the container.

To place the second bitfield, b, a new container is allocated at offset 4, because the type of the bitfield is not the same as that of the previous one. b is placed into the least significant three bits of this container.

The third bitfield, c, has the same type as b and fits into the same container.

The fourth member, d, is allocated into the byte at offset 6. d cannot be placed into the same container as b and c because it is not a bitfield, it is not of the same type, and it would not fit.

When using reverse order (reverse disjoint types), each bitfield is instead placed starting from the most significant bit of its container.

This is the layout of bitfield\_example in little-endian mode:

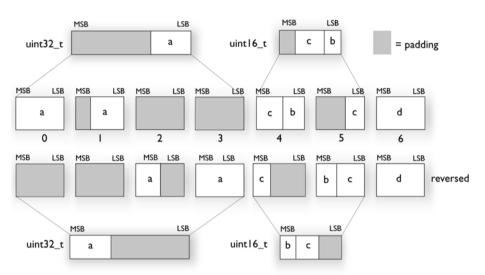


Figure 16: Layout of bitfield\_example for disjoint types in little-endian mode

This is the layout of bitfield\_example in big-endian mode:

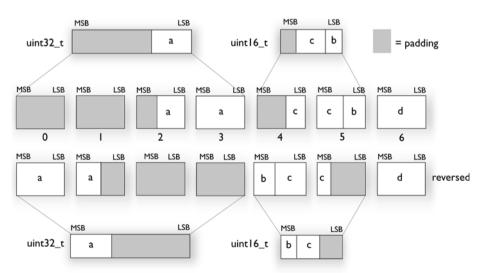


Figure 17: Layout of bitfield\_example for disjoint types in big-endian mode

#### **FLOATING-POINT TYPES**

In the IAR C/C++ Compiler for ARM, floating-point values are represented in standard IEEE 754 format. The sizes for the different floating-point types are:

Туре	Size	Range (+/-)	Decimals	Exponent	Mantissa	Alignment
float	32 bits	±1.18E-38 to ±3.40E+38	7	8 bits	23 bits	4
double	64 bits	±2.23E-308 to ±1.79E+308	15	II bits	52 bits	8
long double	64 bits	±2.23E-308 to ±1.79E+308	15	II bits	52 bits	8

Table 29: Floating-point types

For Cortex-M0 and Cortex-M1, the compiler does not support subnormal numbers. All operations that should produce subnormal numbers will instead generate zero. For information about the representation of subnormal numbers for other cores, see *Representation of special floating-point numbers*, page 283.

#### Floating-point environment

Exception flags for floating-point values are supported for devices with a VFP unit, and they are defined in the fenv.h file. For devices without a VFP unit, the functions defined in the fenv.h file exists but have no functionality.

The feraiseexcept function does not raise an inexact floating-point exception when called with FE\_OVERFLOW or FE\_UNDERFLOW.

# 32-bit floating-point format

The representation of a 32-bit floating-point number as an integer is:

31	30 23	22 0
S	Exponent	Mantissa

The exponent is 8 bits, and the mantissa is 23 bits.

The value of the number is:

The range of the number is at least:

```
±1.18E-38 to ±3.39E+38
```

The precision of the float operators (+, -, \*, and /) is approximately 7 decimal digits.

### 64-bit floating-point format

The representation of a 64-bit floating-point number as an integer is:

63	62	52 5	51	_0
S	Ехро	nent	Mantissa	

The exponent is 11 bits, and the mantissa is 52 bits.

The value of the number is:

The range of the number is at least:

```
\pm 2.23E-308 to \pm 1.79E+308
```

The precision of the float operators (+, -, \*, and /) is approximately 15 decimal digits.

# Representation of special floating-point numbers

This list describes the representation of special floating-point numbers:

- Zero is represented by zero mantissa and exponent. The sign bit signifies positive or negative zero.
- Infinity is represented by setting the exponent to the highest value and the mantissa to zero. The sign bit signifies positive or negative infinity.
- Not a number (NaN) is represented by setting the exponent to the highest positive value and at least one bit set in the 20 most significant bits of the mantissa.
   Remaining bits are zero.
- Not a number (NaN) is represented by setting the exponent to the highest positive value and the most significant bit in the mantissa to 1. The value of the sign bit is ignored.
- Subnormal numbers are used for representing values smaller than what can be
  represented by normal values. The drawback is that the precision will decrease with
  smaller values. The exponent is set to 0 to signify that the number is denormalized,
  even though the number is treated as if the exponent was 1. Unlike normal numbers,
  denormalized numbers do not have an implicit 1 as the most significant bit (the
  MSB) of the mantissa. The value of a denormalized number is:

```
(-1)^{S} * 2^{(1-BIAS)} * 0.Mantissa
```

where BIAS is 127 and 1023 for 32-bit and 64-bit floating-point values, respectively.

# **Pointer types**

The compiler has two basic types of pointers: function pointers and data pointers.

#### **FUNCTION POINTERS**

The size of function pointers is always 32 bits and the range is 0x0-0xffffffff.

When function pointer types are declared, attributes are inserted before the \* sign, for example:

```
typedef void (__thumb __interwork * IntHandler) (void);
```

This can be rewritten using #pragma directives:

```
#pragma type_attribute=__thumb __interwork
typedef void IntHandler_function(void);
typedef IntHandler_function *IntHandler;
```

#### **DATA POINTERS**

There is one data pointer available. Its size is 32 bits and the range is 0x0-0xffffffff.

#### **CASTING**

Casts between pointers have these characteristics:

- Casting a value of an integer type to a pointer of a smaller type is performed by truncation
- Casting a value of an unsigned integer type to a pointer of a larger type is performed by zero extension
- Casting a value of a signed integer type to a pointer of a larger type is performed by sign extension
- Casting a *pointer type* to a smaller integer type is performed by truncation
- Casting a *pointer type* to a larger integer type is performed by zero extension
- Casting a data pointer to a function pointer and vice versa is illegal
- Casting a function pointer to an integer type gives an undefined result

#### size\_t

size\_t is the unsigned integer type required to hold the maximum size of an object. In the IAR C/C++ Compiler for ARM, the size of size\_t is 32 bits.

# ptrdiff\_t

ptrdiff\_t is the type of the signed integer required to hold the difference between two pointers to elements of the same array. In the IAR C/C++ Compiler for ARM, the size of ptrdiff\_t is 32 bits.

#### intptr\_t

intptr\_t is a signed integer type large enough to contain a void \*. In the IAR C/C++ Compiler for ARM, the size of intptr\_t is 32 bits.

#### uintptr t

uintptr\_t is equivalent to intptr\_t, with the exception that it is unsigned.

# Structure types

The members of a struct are stored sequentially in the order in which they are declared: the first member has the lowest memory address.

#### **ALIGNMENT**

The struct and union types have the same alignment as the member with the highest alignment requirement. The size of a struct is also adjusted to allow arrays of aligned structure objects.

#### **GENERAL LAYOUT**

Members of a struct are always allocated in the order specified in the declaration. Each member is placed in the struct according to the specified alignment (offsets).

#### Example

```
struct First
{
   char c;
   short s;
} s;
```

This diagram shows the layout in memory:

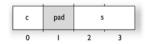


Figure 18: Structure layout

The alignment of the structure is 2 bytes, and a pad byte must be inserted to give short s the correct alignment.

#### **PACKED STRUCTURE TYPES**

The \_\_packed data type attribute or the #pragma pack directive is used for relaxing the alignment requirements of the members of a structure. This changes the layout of the structure. The members are placed in the same order as when declared, but there might be less pad space between members.

Note that accessing an object that is not correctly aligned requires code that is both larger and slower. If such structure members are accessed many times, it is usually better to construct the correct values in a struct that is not packed, and access this struct instead.

Special care is also needed when creating and using pointers to misaligned members. For direct access to misaligned members in a packed struct, the compiler will emit the correct (but slower and larger) code when needed. However, when a misaligned member is accessed through a pointer to the member, the normal (smaller and faster) code is used. In the general case, this will not work.

#### Example

This example declares a packed structure:

```
#pragma pack(1)
struct S
{
   char c;
   short s;
};
#pragma pack()
```

In this example, the structure S has this memory layout:



Figure 19: Packed structure layout

This example declares a new non-packed structure, S2, that contains the structure s declared in the previous example:

```
struct S2
{
   struct S s;
   long 1;
};
```

S2 has this memory layout



Figure 20: Packed structure layout

The structure S will use the memory layout, size, and alignment described in the previous example. The alignment of the member 1 is 4, which means that alignment of the structure S2 will become 2.

For more information, see *Alignment of elements in a structure*, page 180.

# Type qualifiers

According to the C standard, volatile and const are type qualifiers.

#### **DECLARING OBJECTS VOLATILE**

By declaring an object volatile, the compiler is informed that the value of the object can change beyond the compiler's control. The compiler must also assume that any accesses can have side effects—thus all accesses to the volatile object must be preserved.

There are three main reasons for declaring an object volatile:

- Shared access; the object is shared between several tasks in a multitasking environment
- Trigger access; as for a memory-mapped SFR where the fact that an access occurs has an effect
- Modified access; where the contents of the object can change in ways not known to the compiler.

#### Definition of access to volatile objects

The C standard defines an abstract machine, which governs the behavior of accesses to volatile declared objects. In general and in accordance to the abstract machine:

 The compiler considers each read and write access to an object declared volatile as an access  The unit for the access is either the entire object or, for accesses to an element in a composite object—such as an array, struct, class, or union—the element. For example:

```
char volatile a;
a = 5;    /* A write access */
a += 6;    /* First a read then a write access */
```

- An access to a bitfield is treated as an access to the underlying type
- Adding a const qualifier to a volatile object will make write accesses to the
  object impossible. However, the object will be placed in RAM as specified by the C
  standard.

However, these rules are not detailed enough to handle the hardware-related requirements. The rules specific to the IAR C/C++ Compiler for ARM are described below

#### Rules for accesses

In the IAR C/C++ Compiler for ARM, accesses to volatile declared objects are subject to these rules:

- All accesses are preserved
- All accesses are complete, that is, the whole object is accessed
- All accesses are performed in the same order as given in the abstract machine
- All accesses are atomic, that is, they cannot be interrupted.

The compiler adheres to these rules for accesses to all 8-, 16-, and 32-bit scalar types, except for accesses to unaligned 16- and 32-bit fields in packed structures.

For all combinations of object types not listed, only the rule that states that all accesses are preserved applies.

## **DECLARING OBJECTS VOLATILE AND CONST**

If you declare a volatile object const, it will be write-protected but it will still be stored in RAM memory as the C standard specifies.

To store the object in read-only memory instead, but still make it possible to access it as a const volatile object, define the variable like this:

```
const volatile int x @ "FLASH";
```

The compiler will generate the read/write section FLASH. That section should be placed in ROM and is used for manually initializing the variables when the application starts up.

Thereafter, the initializers can be reflashed with other values at any time.

## **DECLARING OBJECTS CONST**

The const type qualifier is used for indicating that a data object, accessed directly or via a pointer, is non-writable. A pointer to const declared data can point to both constant and non-constant objects. It is good programming practice to use const declared pointers whenever possible because this improves the compiler's possibilities to optimize the generated code and reduces the risk of application failure due to erroneously modified data.

Static and global objects declared const are allocated in ROM.

In C++, objects that require runtime initialization cannot be placed in ROM.

# Data types in C++

In C++, all plain C data types are represented in the same way as described earlier in this chapter. However, if any Embedded C++ features are used for a type, no assumptions can be made concerning the data representation. This means, for example, that it is not supported to write assembler code that accesses class members.

Data types in C++

# **Extended keywords**

This chapter describes the extended keywords that support specific features of the ARM core and the general syntax rules for the keywords. Finally the chapter gives a detailed description of each keyword.

# General syntax rules for extended keywords

To understand the syntax rules for the extended keywords, it is important to be familiar with some related concepts.

The compiler provides a set of attributes that can be used on functions or data objects to support specific features of the ARM core. There are two types of attributes—type attributes and object attributes:

- Type attributes affect the external functionality of the data object or function
- Object attributes affect the *internal functionality* of the data object or function.

The syntax for the keywords differs slightly depending on whether it is a type attribute or an object attribute, and whether it is applied to a data object or a function.

For more information about each attribute, see *Descriptions of extended keywords*, page 295.

**Note:** The extended keywords are only available when language extensions are enabled in the compiler.



In the IDE, language extensions are enabled by default.



Use the -e compiler option to enable language extensions. See -e, page 225 for more information.

#### TYPE ATTRIBUTES

Type attributes define how a function is called, or how a data object is accessed. This means that if you use a type attribute, it must be specified both when a function or data object is defined and when it is declared.

You can either place the type attributes explicitly in your declarations, or use the pragma directive #pragma type\_attribute.

#### General type attributes

These general type attributes are available:

- Function type attributes affect how the function should be called: \_\_arm, \_\_fiq, \_\_interwork, \_\_irq, \_\_swi, \_\_task, and \_\_thumb
- Data type attributes: \_\_big\_endian, const, \_\_little\_endian, \_\_packed, and volatile.

You can specify as many type attributes as required for each level of pointer indirection.

For more information about the type qualifiers const and volatile, see *Type qualifiers*, page 287.

#### Syntax for type attributes used on data objects

In general, type attributes for data objects follow the same syntax as the type qualifiers const and volatile.

The following declaration assigns the \_\_little\_endian type attribute to the variables i and j; in other words, the variable i and j will be accessed with little endian byte order. However, note that an individual member of a struct or union cannot have a type attribute. The variables k and 1 behave in the same way:

```
__little_endian int i, j;
int __little_endian k, 1;
```

Note that the attribute affects both identifiers.

This declaration of i and j is equivalent with the previous one:

```
#pragma type_attribute=__little_endian
int i, j;
```

The advantage of using pragma directives for specifying keywords is that it offers you a method to make sure that the source code is portable.

#### Syntax for type attributes on data pointers

The syntax for declaring pointers using type attributes follows the same syntax as the type qualifiers const and volatile:

#### Syntax for type attributes on functions

The syntax for using type attributes on functions differs slightly from the syntax of type attributes on data objects. For functions, the attribute must be placed either in front of the return type, or in parentheses, for example:

```
__irq __arm void my_handler(void);
or
void (__irq __arm my_handler)(void);
This declaration of my_handler is equivalent with the previous one:
#pragma type_attribute=__irq __arm
void my_handler(void);
```

#### **OBJECT ATTRIBUTES**

Normally, object attributes affect the internal functionality of functions and data objects, but not directly how the function is called or how the data is accessed. This means that an object attribute does not normally need to be present in the declaration of an object.

These object attributes are available:

- Object attributes that can be used for variables: \_\_absolute and \_\_no\_init
- Object attributes that can be used for functions and variables: location, @,
   \_\_root, and \_\_weak,
- Object attributes that can be used for functions: \_\_intrinsic, \_\_nested, \_\_noreturn, \_\_ramfunc, and \_\_stackless.

You can specify as many object attributes as required for a specific function or data object.

For more information about location and @, see *Controlling data and function placement in memory*, page 182.

## Syntax for object attributes

The object attribute must be placed in front of the type. For example, to place myarray in memory that is not initialized at startup:

```
__no_init int myarray[10];
```

The #pragma object\_attribute directive can also be used. This declaration is equivalent to the previous one:

```
#pragma object_attribute=__no_init
int myarray[10];
```

**Note:** Object attributes cannot be used in combination with the typedef keyword.

# Summary of extended keywords

This table summarizes the extended keywords:

Extended keyword	Description
absolute	Makes references to the object use absolute addressing
arm	Makes a function execute in ARM mode
big_endian	Declares a variable to use the big-endian byte order
fiq	Declares a fast interrupt function
interwork	Declares a function to be callable from both ARM and Thumb mode
intrinsic	Reserved for compiler internal use only
irq	Declares an interrupt function
little_endian	Declares a variable to use the little-endian byte order
nested	Allows an $\_\_irq$ declared interrupt function to be nested, that is, interruptible by the same type of interrupt
no_init	Supports non-volatile memory
noreturn	Informs the compiler that the function will not return
packed	Decreases data type alignment to I
pcrel	Used internally by the compiler for constant data when theropi compiler option is used
ramfunc	Makes a function execute in RAM
root	Ensures that a function or variable is included in the object code even if unused
sbrel	Used internally by the compiler for constant data when therwpi compiler option is used
stackless	Makes a function callable without a working stack
swi	Declares a software interrupt function
task	Relaxes the rules for preserving registers
thumb	Makes a function execute in Thumb mode
weak	Declares a symbol to be externally weakly linked

Table 30: Extended keywords summary

## **Descriptions of extended keywords**

These sections give detailed information about each extended keyword.

## absolute

Syntax Follows the generic syntax rules for object attributes that can be used on data, see Object

attributes, page 293.

Description The \_\_absolute keyword makes references to the object use absolute addressing.

The following limitations apply:

• Only available when the --ropi or --rwpi compiler option is used

• Can only be used on external declarations.

**Example** extern \_absolute char otherBuffer[100];

#### \_\_arm

Syntax Follows the generic syntax rules for type attributes that can be used on functions, see

Type attributes, page 291.

Description The \_\_arm keyword makes a function execute in ARM mode. An \_\_arm declared

function can, unless it is also declared \_\_interwork, only be called from functions that

also execute in ARM mode.

A function declared \_\_arm cannot be declared \_\_thumb.

**Note:** Non-interwork ARM functions cannot be called from Thumb mode.

Example \_\_arm int func1(void);

See also \_\_interwork, page 296.

## \_\_big\_endian

Syntax Follows the generic syntax rules for type attributes that can be used on data objects, see

Type attributes, page 291.

Description The \_\_big\_endian keyword is used for accessing a variable that is stored in the

big-endian byte order regardless of what byte order the rest of the application uses. The

\_\_big\_endian keyword is available when you compile for ARMv6 or higher.

Note that this keyword cannot be used on pointers. Also, this attribute cannot be used on arrays.

**Example** \_\_big\_endian long my\_variable;

See also \_\_little\_endian, page 297.

## \_\_fiq

Syntax Follows the generic syntax rules for type attributes that can be used on functions, see

Type attributes, page 291.

Description The \_\_fiq keyword declares a fast interrupt function. All interrupt functions must be

compiled in ARM mode. A function declared \_\_fiq does not accept parameters and

does not have a return value.

Example \_\_fiq \_\_arm void interrupt\_function(void);

## \_\_interwork

Syntax Follows the generic syntax rules for type attributes that can be used on functions, see

Type attributes, page 291.

Description A function declared \_\_interwork can be called from functions executing in either

ARM or Thumb mode.

**Note:** By default, functions are interwork when the --interwork compiler option is used, and when the --cpu option is used and it specifies a core where interwork is

default.

Example typedef void (\_\_thumb \_\_interwork \*IntHandler) (void);

## \_\_intrinsic

**Description** The \_\_intrinsic keyword is reserved for compiler internal use only.

## \_\_irq

Syntax Follows the generic syntax rules for type attributes that can be used on functions, see

Type attributes, page 291.

Description The \_\_irq keyword declares an interrupt function. All interrupt functions must be

compiled in ARM mode. A function declared \_\_irq does not accept parameters and

does not have a return value.

## little endian

Syntax Follows the generic syntax rules for type attributes that can be used on data objects, see

Type attributes, page 291.

Description The \_\_little\_endian keyword is used for accessing a variable that is stored in the

little-endian byte order regardless of what byte order the rest of the application uses. The \_\_little\_endian keyword is available when you compile for ARMv6 or higher.

Note that this keyword cannot be used on pointers. Also, this attribute cannot be used on

arrays.

**Example** \_\_little\_endian long my\_variable;

See also \_\_big\_endian, page 295.

#### nested

Syntax Follows the generic syntax rules for object attributes that can be used on functions, see

Object attributes, page 293.

Description The \_\_nested keyword modifies the enter and exit code of an interrupt function to

allow for nested interrupts. This allows interrupts to be enabled, which means new interrupts can be served inside an interrupt function, without overwriting the SPSR and return address in R14. Nested interrupts are only supported for \_\_irq declared

functions.

**Note:** The \_\_nested keyword requires the processor mode to be in either User or

System mode.

See also *Nested interrupts*, page 61.

## \_\_no\_init

Syntax Follows the generic syntax rules for object attributes, see *Object attributes*, page 293.

Description

Use the \_\_no\_init keyword to place a data object in non-volatile memory. This means

that the initialization of the variable, for example at system startup, is suppressed.

**Example** \_\_no\_init int myarray[10];

See also Do not initialize directive, page 392.

#### noreturn

Syntax Follows the generic syntax rules for object attributes, see *Object attributes*, page 293.

Description

The \_\_noreturn keyword can be used on a function to inform the compiler that the function will not return. If you use this keyword on such functions, the compiler can

optimize more efficiently. Examples of functions that do not return are abort and exit.

**Example** \_\_noreturn void terminate(void);

## packed

Description

Syntax Follows the generic syntax rules for type attributes that can be used on data, see *Type attributes*, page 291.

unitonies, page 2)

Use the \_\_packed keyword to decrease the data type alignment to 1. \_\_packed can be used for two purposes:

- When used with a struct or union type definition, the maximum alignment of members of that struct or union is set to 1, to eliminate any gaps between the members. The type of each members also receives the \_\_packed type attribute.
- When used with any other type, the resulting type is the same as the type without
  the \_\_packed type attribute, but with an alignment of 1. Types that already have an
  alignment of 1 are not affected by the \_\_packed type attribute.

A normal pointer can be implicitly converted to a pointer to \_\_packed, but the reverse conversion requires a cast.

**Note:** Accessing data types at other alignments than their natural alignment can result in code that is significantly larger and slower.

Example

See also

pack, page 315.

## \_\_ramfunc

Syntax

Follows the generic syntax rules for object attributes, see *Object attributes*, page 293.

Description

The \_\_ramfunc keyword makes a function execute in RAM. Two code sections will be created: one for the RAM execution (.textrw), and one for the ROM initialization (.textrw\_init).

If a function declared \_\_ramfunc tries to access ROM, the compiler will issue a warning. This behavior is intended to simplify the creation of *upgrade* routines, for instance, rewriting parts of flash memory. If this is not why you have declared the function \_\_ramfunc, you can safely ignore or disable these warnings.

Functions declared \_\_ramfunc are by default stored in the section named .textrw.

Example

\_\_ramfunc int FlashPage(char \* data, char \* page);

See also

To read more about \_\_\_ramfunc declared functions in relation to breakpoints, see the C-SPY® Debugging Guide for ARM®.

#### root

Syntax

Follows the generic syntax rules for object attributes, see *Object attributes*, page 293.

Description

A function or variable with the \_\_root attribute is kept whether or not it is referenced from the rest of the application, provided its module is included. Program modules are always included and library modules are only included if needed.

Example

\_\_root int myarray[10];

See also

For more information about root symbols and how they are kept, see *Keeping symbols and sections*, page 81.

#### stackless

Syntax

Follows the generic syntax rules for object attributes that can be used on functions, see *Object attributes*, page 293.

Description

The \_\_stackless keyword declares a function that can be called without a working stack.



**Warning:** A function declared \_\_stackless violates the calling convention in such a way that it is not possible to return from it. However, the compiler cannot reliably detect if the function returns and will not issue an error if it does.

Example

\_\_stackless void start\_application(void);

## \_\_swi

Syntax

Follows the generic syntax rules for type attributes that can be used on functions, see *Type attributes*, page 291.

Description

The \_\_swi keyword declares a software interrupt function. It inserts an svc (formerly swl) instruction and the specified software interrupt number to make a proper function call. A function declared \_\_swi accepts arguments and returns values. The \_\_swi keyword makes the compiler generate the correct return sequence for a specific software interrupt function. Software interrupt functions follow the same calling convention regarding parameters and return values as an ordinary function, except for the stack usage.

The \_\_swi keyword also expects a software interrupt number which is specified with the #pragma swi\_number=number directive. The swi\_number is used as an argument to the generated assembler SWC instruction, and can be used by the SVC interrupt handler, for example SWI\_Handler, to select one software interrupt function in a system containing several such functions. Note that the software interrupt number should only be specified in the function declaration—typically, in a header file that you include in the source code file that calls the interrupt function—not in the function definition.

**Note:** All interrupt functions must be compiled in ARM mode, except for Cortex-M. Use either the \_\_arm keyword or the #pragma type\_attribute=\_\_arm directive to alter the default behavior if needed.

#### Example

To declare your software interrupt function, typically in a header file, write for example like this:

```
__swi int swi0x23_function(int a, int b);
...

To call the function:
```

#pragma swi\_number=0x23

Somewhere in your application source code, you define your software interrupt function:

```
...
__swi __arm int the_actual_swi0x23_function(int a, int b)
{
    ...
    return 42;
}
```

See also

Software interrupts, page 62 and Calling convention, page 132.

#### task

**Syntax** 

Follows the generic syntax rules for type attributes that can be used on functions, see *Type attributes*, page 291.

Description

This keyword allows functions to relax the rules for preserving registers. Typically, the keyword is used on the start function for a task in an RTOS.

By default, functions save the contents of used preserved registers on the stack upon entry, and restore them at exit. Functions that are declared \_\_task do not save all registers, and therefore require less stack space.

Because a function declared \_\_task can corrupt registers that are needed by the calling function, you should only use \_\_task on functions that do not return or call such a function from assembler code.

The function main can be declared \_\_task, unless it is explicitly called from the application. In real-time applications with more than one task, the root function of each task can be declared \_\_task.

## \_\_thumb

Syntax Follows the generic syntax rules for type attributes that can be used on functions, see

Type attributes, page 291.

Description The \_\_thumb keyword makes a function execute in Thumb mode. Unless the function

is also declared \_\_interwork, the function declared \_\_thumb can only be called from

functions that also execute in Thumb mode.

A function declared  $\_$ \_thumb cannot be declared  $\_$ arm.

Note: Non-interwork Thumb functions cannot be called from ARM mode.

See also \_\_interwork, page 296.

## \_\_weak

Syntax

Follows the generic syntax rules for object attributes, see *Object attributes*, page 293.

Description

Using the \_\_weak object attribute on an external declaration of a symbol makes all references to that symbol in the module weak.

Using the \_\_weak object attribute on a public definition of a symbol makes that definition a weak definition.

The linker will not include a module from a library solely to satisfy weak references to a symbol, nor will the lack of a definition for a weak reference result in an error. If no definition is included, the address of the object will be zero.

When linking, a symbol can have any number of weak definitions, and at most one non-weak definition. If the symbol is needed, and there is a non-weak definition, this definition will be used. If there is no non-weak definition, one of the weak definitions will be used.

Example

```
extern __weak int foo; /* A weak reference. */
__weak void bar(void) /* A weak definition. */
{
    /* Increment foo if it was included. */
    if (&foo != 0)
        ++foo;
```

}

Descriptions of extended keywords

# **Pragma directives**

This chapter describes the pragma directives of the compiler.

The #pragma directive is defined by Standard C and is a mechanism for using vendor-specific extensions in a controlled way to make sure that the source code is still portable.

The pragma directives control the behavior of the compiler, for example how it allocates memory for variables and functions, whether it allows extended keywords, and whether it outputs warning messages.

The pragma directives are always enabled in the compiler.

# Summary of pragma directives

This table lists the pragma directives of the compiler that can be used either with the #pragma preprocessor directive or the \_Pragma() preprocessor operator:

Pragma directive	Description	
bitfields	Controls the order of bitfield members	
data_alignment	Gives a variable a higher (more strict) alignment	
diag_default	Changes the severity level of diagnostic messages	
diag_error	Changes the severity level of diagnostic messages	
diag_remark	Changes the severity level of diagnostic messages	
diag_suppress	Suppresses diagnostic messages	
diag_warning	Changes the severity level of diagnostic messages	
error	Signals an error while parsing	
include_alias	Specifies an alias for an include file	
inline	Controls inlining of a function	
language	Controls the IAR Systems language extensions	
location	Specifies the absolute address of a variable, places a variable in a register, or places groups of functions or variables in named sections	
message	Prints a message	

Table 31: Pragma directives summary

Pragma directive	Description
object_attribute	Changes the definition of a variable or a function
optimize	Specifies the type and level of an optimization
pack	Specifies the alignment of structures and union members
printf_args	Verifies that a function with a printf-style format string is called with the correct arguments
required	Ensures that a symbol that is needed by another symbol is included in the linked output
rtmodel	Adds a runtime model attribute to the module
scanf_args	Verifies that a function with a scanf-style format string is called with the correct arguments
section	Declares a section name to be used by intrinsic functions
segment	This directive is an alias for #pragma section
STDC CX_LIMITED_RANGE	Specifies whether the compiler can use normal complex mathematical formulas or not
STDC FENV_ACCESS	Specifies whether your source code accesses the floating-point environment or not.
STDC FP_CONTRACT	Specifies whether the compiler is allowed to contract floating-point expressions or not.
swi_number	Sets the interrupt number of a software interrupt function
type_attribute	Changes the declaration and definitions of a variable or function
weak	Makes a definition a weak definition, or creates a weak alias for a function or a variable

Table 31: Pragma directives summary (Continued)

**Note:** For portability reasons, the pragma directives alignment, baseaddr, codeseg, constseg, dataseg, function, memory, and warnings are recognized but will give a diagnostic message. It is important to be aware of this if you need to port existing code that contains any of those pragma directives. See also *Recognized pragma directives* (6.10.6), page 446.

# **Descriptions of pragma directives**

This section gives detailed information about each pragma directive.

#### bitfields

**Syntax** #pragma bitfields=disjoint\_types|joined\_types| reversed\_disjoint\_types|reversed|default} **Parameters** disjoint\_types Bitfield members are placed from the least significant bit to the most significant bit in the container type. Storage containers of bitfields with different base types will not overlap. joined\_types Bitfield members are placed depending on the byte order. Storage containers of bitfields will overlap other structure members. For more information, see Bitfields, page 278. reversed\_disjoint\_types Bitfield members are placed from the most significant bit to the least significant bit in the container type. Storage containers of bitfields with different base types will not overlap. reversed This is an alias for reversed\_disjoint\_types. default Restores to default layout of bitfield members. The default behavior for the compiler is joined\_types.

Description

Use this pragma directive to control the layout of bitfield members.

```
Example
```

```
#pragma bitfields=disjoint_types
/* Structure that uses disjoint bitfield types. */
struct S
{
   unsigned char error : 1;
   unsigned char size : 4;
   unsigned short code : 10;
};
#pragma bitfields=default /* Restores to default setting. */
```

See also

Bitfields, page 278.

## data\_alignment

Syntax #pragma data\_alignment=expression

**Parameters** 

expression A constant which must be a power of two (1, 2, 4, etc.).

Description

Use this pragma directive to give a variable a higher (more strict) alignment of the start address than it would otherwise have. This directive can be used on variables with static and automatic storage duration.

When you use this directive on variables with automatic storage duration, there is an upper limit on the allowed alignment for each function, determined by the calling convention used.

**Note:** Normally, the size of a variable is a multiple of its alignment. The data\_alignment directive only affects the alignment of the variable's start address, and not its size, and can thus be used for creating situations where the size is not a multiple of the alignment.

## diag\_default

Syntax #pragma diag\_default=tag[,tag,...]

**Parameters** 

tag The number of a diagnostic message, for example the message

number Pe117.

Description Use this pragma directive to change the severity level back to the default, or to the

severity level defined on the command line by any of the options --diag\_error, --diag\_remark, --diag\_suppress, or --diag\_warnings, for the diagnostic

messages specified with the tags.

See also *Diagnostics*, page 206.

# diag\_error

**Syntax** #pragma diag\_error=tag[,tag,...]

**Parameters** 

tag The number of a diagnostic message, for example the message

number Pe117.

Description Use this pragma directive to change the severity level to error for the specified

diagnostics.

See also *Diagnostics*, page 206.

diag\_remark

Syntax #pragma diag\_remark=tag[,tag,...]

**Parameters** 

tag The number of a diagnostic message, for example the message

 $\quad \text{number } \texttt{Pe} 177.$ 

Description Use this pragma directive to change the severity level to remark for the specified

diagnostic messages.

See also *Diagnostics*, page 206.

diag\_suppress

**Syntax** #pragma diag\_suppress=tag[,tag,...]

**Parameters** 

tag The number of a diagnostic message, for example the message

number Pe117.

**Description** Use this pragma directive to suppress the specified diagnostic messages.

See also *Diagnostics*, page 206.

diag\_warning

**Parameters** 

tag The number of a diagnostic message, for example the message

number Pe826.

Description Use this pragma directive to change the severity level to warning for the specified

diagnostic messages.

See also *Diagnostics*, page 206.

#### error

Syntax #pragma error message

**Parameters** 

message A string that represents the error message.

Description Use this pragma directive to cause an error message when it is parsed. This mechanism

is different from the preprocessor directive #error, because the #pragma error directive can be included in a preprocessor macro using the \_Pragma form of the

directive and only causes an error if the macro is used.

Example #if FOO\_AVAILABLE

#define FOO ...

#else

#define FOO \_Pragma("error\"Foo is not available\"")

#endif

If FOO\_AVAILABLE is zero, an error will be signaled if the FOO macro is used in actual

source code.

## include alias

#pragma include\_alias (<orig\_header> , <subst\_header>)

**Parameters** 

orig\_header The name of a header file for which you want to create an alias.

subst\_header The alias for the original header file.

**Description** Use this pragma directive to provide an alias for a header file. This is useful for

substituting one header file with another, and for specifying an absolute path to a relative

file.

This pragma directive must appear before the corresponding #include directives and

subst\_header must match its corresponding #include directive exactly.

Example #pragma include\_alias (<stdio.h> , <C:\MyHeaders\stdio.h>)

#include <stdio.h>

This example will substitute the relative file stdio.h with a counterpart located according to the specified path.

See also Include file search procedure, page 203.

#### inline

Syntax #pragma inline[=forced|=never]

**Parameters** 

No parameter Has the same effect as the inline keyword.

forced Disables the compiler's heuristics and forces inlining.

never Disables the compiler's heuristics and makes sure that the function

will not be inlined.

Description

Use #pragma inline to advise the compiler that the function whose declaration follows immediately after the directive should be expanded inline into the body of the calling function. Whether the inlining actually occurs is subject to the compiler's heuristics.

#pragma inline is similar to the C++ keyword inline. The difference is that the compiler uses C++ inline semantics for the #pragma inline directive, but uses the Standard C semantics for the inline keyword.

Specifying #pragma inline=never disables the compiler's heuristics and makes sure that the function will not be inlined.

Specifying #pragma inline=forced will force the compiler to treat the function declared immediately after the directive as a candidate for inlining, regardless of the compiler's heuristics. If the compiler fails to inline the candidate function for some reason, for example due to recursion, a warning message is emitted.

Inlining is normally performed only on the High optimization level. Specifying #pragma inline=forced will enable inlining of the function in question also on the Medium optimization level.

See also

Function inlining, page 190.

## language

**Parameters** 

extended Enables the IAR Systems language extensions from the first use of

the pragma directive and onward.

default From the first use of the pragma directive and onward, restores

the settings for the IAR Systems language extensions to whatever

that was specified by compiler options.

save restore Saves and restores, respectively, the IAR Systems language

extensions setting around a piece of source code.

Each use of save must be followed by a matching restore in the

same file without any intervening #include directive.

**Description** Use this pragma directive to control the use of language extensions.

Example I At the top of a file that needs to be compiled with IAR Systems extensions enabled:

#pragma language=extended
/\* The rest of the file. \*/

Example 2 Around a particular part of the source code that needs to be compiled with IAR Systems

extensions enabled, but where the state before the sequence cannot be assumed to be the

same as that specified by the compiler options in use:

#pragma language=save
#pragma language=extended
/\* Part of source code. \*/
#pragma language=restore

See also -e, page 225 and --strict, page 246.

#### location

Syntax #pragma location={address|register|NAME}

**Parameters** 

address The absolute address of the global or static variable for which you

want an absolute location.

register An identifier that corresponds to one of the ARM core registers

R4-R11.

NAME

A user-defined section name; cannot be a section name predefined for use by the compiler and linker.

#### Description

Use this pragma directive to specify:

- The location—the absolute address—of the global or static variable whose declaration follows the pragma directive. The variables must be declared \_\_no\_init.
- An identifier specifying a register. The variable defined after the pragma directive is
  placed in the register. The variable must be declared as \_\_no\_init and have file
  scope.
- A string specifying a section for placing either a variable or function whose
  declaration follows the pragma directive. Do not place variables that would
  normally be in different sections (for example, variables declared as \_\_no\_init
  and variables declared as const) in the same named section.

#### Example

See also

Controlling data and function placement in memory, page 182.

#### message

Syntax #pragma message(message)

**Parameters** 

message

The message that you want to direct to the standard output stream.

Description Use this pragma directive to make the compiler print a message to the standard output

stream when the file is compiled.

Example: #ifdef TESTING

#pragma message("Testing")

#endif

## object\_attribute

Syntax #pragma object\_attribute=object\_attribute[,object\_attribute,...]

Parameters For information about object attributes that can be used with this pragma directive, see

Object attributes, page 293.

Description Use this pragma directive to declare a variable or a function with an object attribute. This

directive affects the definition of the identifier that follows immediately after the directive. The object is modified, not its type. Unlike the directive #pragma

type\_attribute that specifies the storing and accessing of a variable or function, it is

not necessary to specify an object attribute in declarations.

char bar;

See also General syntax rules for extended keywords, page 291.

## optimize

Syntax #pragma optimize=[goal][level][no\_optimization...]

**Parameters** 

goal Choose between:

balanced, optimizes balanced between speed and size

size, optimizes for size speed, optimizes for speed.

1evel Specifies the level of optimization; choose between none, low,

medium, or high.

no\_optimization

Disables one or several optimizations; choose between:

no\_code\_motion, disables code motion no\_cse, disables common subexpression elimination no\_inline, disables function inlining no\_tbaa, disables type-based alias analysis no\_unroll, disables loop unrolling

no scheduling, disables instruction scheduling.

#### Description

Use this pragma directive to decrease the optimization level, or to turn off some specific optimizations. This pragma directive only affects the function that follows immediately after the directive.

The parameters speed, size, and balanced only have effect on the high optimization level and only one of them can be used as it is not possible to optimize for speed and size at the same time. It is also not possible to use preprocessor macros embedded in this pragma directive. Any such macro will not be expanded by the preprocessor.

**Note:** If you use the #pragma optimize directive to specify an optimization level that is higher than the optimization level you specify using a compiler option, the pragma directive is ignored.

#### Example

```
#pragma optimize=speed
int SmallAndUsedOften()
{
    /* Do something here. */
}

#pragma optimize=size
int BigAndSeldomUsed()
{
    /* Do something here. */
}
```

## pack

Syntax

```
#pragma pack(n)
#pragma pack()
#pragma pack({push|pop}[,name] [,n])
```

#### **Parameters**

n Sets an optional structure alignment; one of: 1, 2, 4, 8, or 16

Empty list Restores the structure alignment to default
push Sets a temporary structure alignment

pop Restores the structure alignment from a temporarily pushed

alignment

name An optional pushed or popped alignment label

**Description** Use this pragma directive to specify the maximum alignment of struct and union

members.

The #pragma pack directive affects declarations of structures following the pragma directive to the next #pragma pack or the end of the compilation unit.

Note: This can result in significantly larger and slower code when accessing members

of the structure.

See also Structure types, page 285 and \_\_packed, page 298.

## \_\_printf\_args

Syntax #pragma \_\_printf\_args

Description Use this pragma directive on a function with a printf-style format string. For any call to

that function, the compiler verifies that the argument to each conversion specifier (for

example %d) is syntactically correct.

Example #pragma \_\_printf\_args

```
int printf(char const *,...);
void PrintNumbers(unsigned short x)
{
   printf("%d", x); /* Compiler checks that x is an integer */
```

# required

Syntax #pragma required=symbol

**Parameters** 

symbol Any statically linked function or variable.

Description Use this pragma directive to ensure that a symbol which is needed by a second symbol

is included in the linked output. The directive must be placed immediately before the

second symbol.

Use the directive if the requirement for a symbol is not otherwise visible in the application, for example if a variable is only referenced indirectly through the section it resides in.

#### Example

```
const char copyright[] = "Copyright by me";
#pragma required=copyright
int main()
{
    /* Do something here. */
}
```

Even if the copyright string is not used by the application, it will still be included by the linker and available in the output.

## rtmodel

Syntax #pragma rtmodel="key","value"

**Parameters** 

" key" A text string that specifies the runtime model attribute.

" value" A text string that specifies the value of the runtime model

attribute. Using the special value st is equivalent to not defining the

attribute at all.

#### Description

Use this pragma directive to add a runtime model attribute to a module, which can be used by the linker to check consistency between modules.

This pragma directive is useful for enforcing consistency between modules. All modules that are linked together and define the same runtime attribute key must have the same value for the corresponding key, or the special value \*. It can, however, be useful to state explicitly that the module can handle any runtime model.

A module can have several runtime model definitions.

**Note:** The predefined compiler runtime model attributes start with a double underscore. To avoid confusion, this style must not be used in the user-defined attributes.

Example

```
#pragma rtmodel="I2C","ENABLED"
```

The linker will generate an error if a module that contains this definition is linked with a module that does not have the corresponding runtime model attributes defined.

See also

Checking module consistency, page 122.

## \_\_scanf\_args

Syntax #pragma \_\_scanf\_args

Description Use this pragma directive on a function with a scanf-style format string. For any call to

that function, the compiler verifies that the argument to each conversion specifier (for

example %d) is syntactically correct.

Example #pragma \_\_scanf\_args

#### section

Syntax #pragma section="NAME" [align]

alias

#pragma segment="NAME" [align]

**Parameters** 

NAME The name of the section.

align Specifies an alignment for the section. The value must be a

constant integer expression to the power of two.

**Description** Use this pragma directive to define a section name that can be used by the section

operators \_\_section\_begin, \_\_section\_end, and \_\_section\_size. All section declarations for a specific section must have the same memory type attribute and

alignment.

Example #pragma section="MYHUGE" \_\_huge 4

See also Dedicated section operators, page 147. For more information about sections, see the

chapter Linking your application.

## STDC CX\_LIMITED\_RANGE

Syntax #pragma STDC CX\_LIMITED\_RANGE {ON OFF | DEFAULT}

**Parameters** 

ON Normal complex mathematic formulas can be used.

OFF Normal complex mathematic formulas cannot be used.

DEFAULT Sets the default behavior, that is OFF.

**Description** Use this pragma directive to specify that the compiler can use the normal complex

mathematic formulas for x (multiplication), / (division), and abs.

Note: This directive is required by Standard C. The directive is recognized but has no

effect in the compiler.

## STDC FENV\_ACCESS

Syntax #pragma STDC FENV\_ACCESS {ON OFF DEFAULT}

**Parameters** 

ON Source code accesses the floating-point environment. Note that

this argument is not supported by the compiler.

OFF Source code does not access the floating-point environment.

DEFAULT Sets the default behavior, that is OFF.

**Description** Use this pragma directive to specify whether your source code accesses the

floating-point environment or not.

**Note:** This directive is required by Standard C.

## STDC FP CONTRACT

**Parameters** 

ON The compiler is allowed to contract floating-point expressions.

OFF The compiler is not allowed to contract floating-point expressions.

Note that this argument is not supported by the compiler.

DEFAULT Sets the default behavior, that is ON.

Description Use this pragma directive to specify whether the compiler is allowed to contract

floating-point expressions or not. This directive is required by Standard C.

Example #pragma STDC\_FP\_CONTRACT=ON

#### swi number

Syntax #pragma swi\_number=number

**Parameters** 

number The software interrupt number

Description Use this pragma directive together with the \_\_swi extended keyword. It is used as an

argument to the generated SWC assembler instruction, and is used for selecting one

software interrupt function in a system containing several such functions.

Example #pragma swi\_number=17

See also *Software interrupts*, page 62.

## type\_attribute

Syntax #pragma type\_attribute=type\_attribute[,type\_attribute,...]

Parameters For information about type attributes that can be used with this pragma directive, see

Type attributes, page 291.

Description Use this pragma directive to specify IAR-specific *type attributes*, which are not part of

Standard C. Note however, that a given type attribute might not be applicable to all kind

of objects.

This directive affects the declaration of the identifier, the next variable, or the next

function that follows immediately after the pragma directive.

Example In this example, thumb-mode code is generated for the function foo:

```
#pragma type_attribute=__thumb
void foo(void)
{
```

}

This declaration, which uses extended keywords, is equivalent:

```
__thumb void foo(void) {
}
```

See also

See the chapter Extended keywords for more information.

#### weak

Syntax #pragma weak symbol1={symbol2}

**Parameters** 

symbol1 A function or variable with external linkage.

symbol2 A defined function or variable.

Description

This pragma directive can be used in one of two ways:

- To make the definition of a function or variable with external linkage a weak definition. The \_\_weak attribute can also be used for this purpose.
- To create a weak alias for another function or variable. You can make more than one alias for the same function or variable.

Example

To make the definition of foo a weak definition, write:

#pragma weak foo

To make NMI\_Handler a weak alias for Default\_Handler, write:

#pragma weak NMI\_Handler=Default\_Handler

If  ${\tt NMI\_Handler}$  is not defined elsewhere in the program, all references to

NMI\_Handler will refer to Default\_Handler.

See also

\_\_weak, page 302.

Descriptions of pragma directives

# **Intrinsic functions**

This chapter gives reference information about the intrinsic functions, a predefined set of functions available in the compiler.

The intrinsic functions provide direct access to low-level processor operations and can be very useful in, for example, time-critical routines. The intrinsic functions compile into inline code, either as a single instruction or as a short sequence of instructions.

# **Summary of intrinsic functions**

To use intrinsic functions in an application, include the header file intrinsics.h.

To use Neon intrinsic functions in an application, include the header file arm\_neon.h. For more information, see

Note that the intrinsic function names start with double underscores, for example:

\_\_disable\_interrupt

This table summarizes the intrinsic functions:

Description
Inserts a CLZ instruction
Disables fast interrupt requests (fiq)
Disables interrupts
Disables interrupt requests (irq)
Inserts a DMB instruction
Inserts a DSB instruction
Enables fast interrupt requests (fiq)
Enables interrupts
Enables interrupt requests (irq)
Returns the value of the Cortex-M3/Cortex-M4 BASEPRI register
Returns the value of the Cortex-M CONTROL register

Table 32: Intrinsic functions summary

Intrinsic function	Description
get_CPSR	Returns the value of the ARM CPSR (Current Program Status Register)
get_FAULTMASK	Returns the value of the  Cortex-M3/Cortex-M4 FAULTMASK register
get_interrupt_state	Returns the interrupt state
get_IPSR	Returns the value of the IPSR register
get_LR	Returns the value of the link register
get_MSP	Returns the value of the $\mathtt{MSP}$ register
get_PRIMASK	Returns the value of the Cortex-M PRIMASK register
get_PSP	Returns the value of the PSP register
get_PSR	Returns the value of the PSR register
get_SB	Returns the value of the static base register
get_SP	Returns the value of the stack pointer register
ISB	Inserts an ISB instruction
LDC	Inserts the coprocessor load instruction $\mathtt{LDC}$
LDCL	Inserts the coprocessor load instruction LDCL
LDC2	Inserts the coprocessor load instruction LDC2
LDC2L	Inserts the coprocessor load instruction ${\tt LDC2L}$
LDC_noidx	Inserts the coprocessor load instruction $\mathtt{LDC}$
LDCL_noidx	Inserts the coprocessor load instruction ${\tt LDCL}$
LDC2_noidx	Inserts the coprocessor load instruction LDC2
LDC2L_noidx	Inserts the coprocessor load instruction LDC2L
LDREX	Inserts an LDREX instruction
MCR	Inserts the coprocessor write instruction $\ensuremath{\mathtt{MCR}}$

Table 32: Intrinsic functions summary (Continued)

ntrinsic function	Description
MRC	Inserts the coprocessor read instruction MRC
_no_operation	Inserts a NOP instruction
РКНВТ	Inserts a PKHBT instruction
_РКНТВ	Inserts a PKHTB instruction
_QADD	Inserts a QADD instruction
_QADD8	Inserts a QADD8 instruction
_QADD16	Inserts a QADD16 instruction
_QASX	Inserts a QASX instruction
_QCF1ag	Returns the value of the cumulative saturation flag of the FPSCR register
_QDADD	Inserts a QDADD instruction
_QDOUBLE	Inserts a QADD instruction
_QDSUB	Inserts a QDSUB instruction
_QF1ag	Returns the $\mathbb Q$ flag that indicates if overflow/saturation has occurred
_QSAX	Inserts a QSAX instruction
_QSUB	Inserts a QSUB instruction
_QSUB8	Inserts a QSUB8 instruction
_QSUB16	Inserts a QSUB16 instruction
_reset_Q_flag	Clears the $\mathbb Q$ flag that indicates if overflow/saturation has occurred
_reset_QC_flag	Clears the value of the cumulative saturation flag QC of the FPSCR register
_REV	Inserts an REV instruction
_REVSH	Inserts an REVSH instruction
_SADD8	Inserts an SADD8 instruction
_SADD16	Inserts an SADD16 instruction
_SASX	Inserts an SASX instruction
_SEL	Inserts an SEL instruction
_set_BASEPRI	Sets the value of the Cortex-M3/Cortex-M4 BASEPRI register

Table 32: Intrinsic functions summary (Continued)

Intrinsic function	Description
set_CONTROL	Sets the value of the Cortex-M CONTROL register
set_CPSR	Sets the value of the ARM CPSR (Current Program Status Register)
set_FAULTMASK	Sets the value of the Cortex-M3/Cortex-M4 FAULTMASK register
set_interrupt_state	Restores the interrupt state
set_LR	Assigns a new address to the link register
set_MSP	Sets the value of the ${\tt MSP}$ register
set_PRIMASK	Sets the value of the Cortex-M PRIMASK register
set_PSP	Sets the value of the PSP register
set_SB	Assigns a new address to the static base register
set_SP	Assigns a new address to the stack pointer register
SHADD8	Inserts an SHADD8 instruction
SHADD16	Inserts an SHADD16 instruction
SHASX	Inserts an SHASX instruction
SHSAX	Inserts an SHSAX instruction
SHSUB8	Inserts an SHSUB8 instruction
SHSUB16	Inserts an SHSUB16 instruction
SMLABB	Inserts an SMLABB instruction
SMLABT	Inserts an SMLABT instruction
SMLAD	Inserts an SMLAD instruction
SMLADX	Inserts an SMLADX instruction
SMLALBB	Inserts an SMLALBB instruction
SMLALBT	Inserts an SMLALBT instruction
SMLALD	Inserts an SMLALD instruction
SMLALDX	Inserts an SMLALDX instruction
SMLALTB	Inserts an SMLALTB instruction
SMLALTT	Inserts an SMLALTT instruction
SMLATB	Inserts an SMLATB instruction

Table 32: Intrinsic functions summary (Continued)

rinsic function	Description
SMLATT	Inserts an SMLATT instruction
_SMLAWB	Inserts an SMLAWB instruction
_SMLAWT	Inserts an SMLAWT instruction
_SMLSD	Inserts an SMLSD instruction
_SMLSDX	Inserts an SMLSDX instruction
_SMLSLD	Inserts an SMLSLD instruction
_SMLSLDX	Inserts an SMLSLDX instruction
_SMMLA	Inserts an SMMLA instruction
_SMMLAR	Inserts an SMMLAR instruction
_SMMLS	Inserts an SMMLS instruction
_SMMLSR	Inserts an SMMLSR instruction
SMMUL	Inserts an SMMUL instruction
SMMULR	Inserts an SMMULR instruction
SMUAD	Inserts an SMUAD instruction
_SMUADX	Inserts an SMUADX instruction
SMUL	Inserts a signed 16-bit multiplication
_SMULBB	Inserts an SMULBB instruction
SMULBT	Inserts an SMULBT instruction
_SMULTB	Inserts an SMULTB instruction
SMULTT	Inserts an SMULTT instruction
_SMULWB	Inserts an SMULWB instruction
SMULWT	Inserts an SMULWT instruction
SMUSD	Inserts an SMUSD instruction
_SMUSDX	Inserts an SMUSDX instruction
_SSAT	Inserts an SSAT instruction
_SSAT16	Inserts an SSAT16 instruction
_SSAX	Inserts an SSAX instruction
_SSUB8	Inserts an SSUB8 instruction
_SSUB16	Inserts an SSUB16 instruction
_STC	Inserts the coprocessor store instruction STC

Table 32: Intrinsic functions summary (Continued)

Intrinsic function	Description
STCL	Inserts the coprocessor store instruction STCL
STC2	Inserts the coprocessor store instruction STC2
STC2L	Inserts the coprocessor store instruction STC2L
STC_noidx	Inserts the coprocessor store instruction ${\tt STC}$
STCL_noidx	Inserts the coprocessor store instruction ${\tt STCL}$
STC2_noidx	Inserts the coprocessor store instruction STC2
STC2L_noidx	Inserts the coprocessor store instruction ${\tt STC2L}$
STREX	Inserts a STREX instruction
SWP	Inserts an SWP instruction
SWPB	Inserts an SWPB instruction
SXTAB	Inserts an SXTAB instruction
SXTAB16	Inserts an SXTAB16 instruction
SXTAH	Inserts an SXTAH instruction
SXTB16	Inserts an SXTB16 instruction
UADD8	Inserts a UADD8 instruction
UADD16	Inserts a UADD16 instruction
UASX	Inserts a UASX instruction
UHADD8	Inserts a UHADD8 instruction
UHADD16	Inserts a UHADD16 instruction
UHASX	Inserts a UHASX instruction
UHSAX	Inserts a UHSAX instruction
UHSUB8	Inserts a UHSUB8 instruction
UHSUB16	Inserts a UHSUB16 instruction
UMAAL	Inserts a UMAAL instruction
UQADD8	Inserts a UQADD8 instruction
UQADD16	Inserts a UQADD16 instruction

Table 32: Intrinsic functions summary (Continued)

Intrinsic function	Description
UQASX	Inserts a UQASX instruction
UQSAX	Inserts a UQSAX instruction
UQSUB8	Inserts a UQSUB8 instruction
UQSUB16	Inserts a UQSUB16 instruction
USAD8	Inserts a USAD8 instruction
USADA8	Inserts a USAD8A8 instruction
USAT	Inserts a USAT instruction
USAT16	Inserts a USAT16 instruction
USAX	Inserts a USAX instruction
USUB8	Inserts a USUB8 instruction
USUB16	Inserts a USUB16 instruction
UXTAB	Inserts a UXTAB instruction
UXTAB16	Inserts a UXTAB16 instruction
UXTAH	Inserts a UXTAH instruction
UXTB16	Inserts a UXTB16 instruction

Table 32: Intrinsic functions summary (Continued)

#### INTRINSIC FUNCTIONS FOR NEON INSTRUCTIONS

The Neon co-processor implements the Advanced SIMD instruction set extension, as defined by the ARM architecture. To use Neon intrinsic functions in an application, include the header file <code>arm\_neon.h</code>. The functions use vector types that are named according to this pattern:

<type><size>x<number\_of\_lanes>\_t

#### where:

- type is int, unsigned int, float, or poly
- size is 8, 16, 32, or 64
- number\_of\_lanes is 1, 2, 4, 8, or 16.

The total bit width of a vector type is <code>size</code> times <code>number\_of\_lanes</code>, and should fit in a D register (64 bits) or a Q register (128 bits).

#### For example:

```
__intrinsic float32x2_t vsub_f32(float32x2_t. float32x2_t);
```

The intrinsic function vsub\_f32 inserts a VSUB.F32 instruction that operates on two 64-bit vectors (D registers), each with two elements (lanes) of 32-bit floating-point type.

Some functions use an array of vector types. As an example, the definition of an array type with four elements of type float32x2\_t is:

```
typedef struct
{
  float32x2_t val[4];
}
float32x2x4_t;
```

## **Descriptions of intrinsic functions**

This section gives reference information about each intrinsic function.

### CLZ

Syntax unsigned char \_\_CLZ(unsigned long);

**Description** Inserts a CLZ instruction.

This intrinsic function requires an ARM v5 architecture or higher for ARM mode, and

ARM v6T2 or higher for Thumb mode.

## \_\_disable\_fiq

Syntax void \_\_disable\_fiq(void);

Description Disables fast interrupt requests (fiq).

This intrinsic function can only be used in privileged mode and is not available for

Cortex-M devices.

## \_\_disable\_interrupt

Syntax void \_\_disable\_interrupt(void);

Description Disables interrupts. For Cortex-M devices, it raises the execution priority level to 0 by

setting the priority mask bit, PRIMASK. For other devices, it disables interrupt requests

(irq) and fast interrupt requests (fiq).

This intrinsic function can only be used in privileged mode.

# \_\_disable\_irq

Syntax void \_\_disable\_irq(void);

Description Disables interrupt requests (irq).

This intrinsic function can only be used in privileged mode and is not available for

Cortex-M devices.

### \_\_DMB

Syntax void \_\_DMB(void);

Description Inserts a DMB instruction. This intrinsic function requires an ARM v6M architecture, or

an ARM v7 architecture or higher.

### \_\_DSB

Syntax void \_\_DSB(void);

Description Inserts a DSB instruction. This intrinsic function requires an ARM v6M architecture, or

an ARM v7 architecture or higher.

## \_\_enable\_fiq

Syntax void \_\_enable\_fiq(void);

Description Enables fast interrupt requests (fiq).

This intrinsic function can only be used in privileged mode, and it is not available for

Cortex-M devices.

## \_\_enable\_interrupt

Syntax void \_\_enable\_interrupt(void);

Description Enables interrupts. For Cortex-M devices, it resets the execution priority level to default

by clearing the priority mask bit, PRIMASK. For other devices, it enables interrupt

requests (irg) and fast interrupt requests (fig).

This intrinsic function can only be used in privileged mode.

### \_\_enable\_irq

Syntax void \_\_enable\_irq(void);

Description Enables interrupt requests (irq).

This intrinsic function can only be used in privileged mode, and it is not available for

Cortex-M devices.

### \_\_get\_BASEPRI

Syntax unsigned long \_\_get\_BASEPRI(void);

Description Returns the value of the BASEPRI register. This intrinsic function can only be used in

privileged mode and it requires a Cortex-M3 or Cortex-M4 device.

### \_\_get\_CONTROL

Syntax unsigned long \_\_get\_CONTROL(void);

Description Returns the value of the CONTROL register. This intrinsic function can only be used in

privileged mode and it requires a Cortex-M device.

## \_\_get\_CPSR

Syntax unsigned long \_\_get\_CPSR(void);

Description Returns the value of the ARM CPSR (Current Program Status Register). This intrinsic

function can only be used in privileged mode, is not available for Cortex-M devices, and

it requires ARM mode.

## \_\_get\_FAULTMASK

Syntax unsigned long \_\_get\_FAULTMASK(void);

Description Returns the value of the FAULTMASK register. This intrinsic function can only be used in

privileged mode and it requires a Cortex-M3 or Cortex-M4 device.

### \_\_get\_interrupt\_state

Syntax \_\_istate\_t \_\_get\_interrupt\_state(void);

Description Returns the global interrupt state. The return value can be used as an argument to the

\_\_set\_interrupt\_state intrinsic function, which will restore the interrupt state.

This intrinsic function can only be used in privileged mode, and cannot be used when using the --aeabi compiler option.

Example #include "intrinsics.h"

```
void CriticalFn()
{
    __istate_t s = __get_interrupt_state();
    __disable_interrupt();

    /* Do something here. */
    __set_interrupt_state(s);
}
```

The advantage of using this sequence of code compared to using

# \_\_get\_IPSR

Syntax unsigned long \_\_get\_IPSR(void);

Description Returns the value of the IPSR register (Interrupt Program Status Register). This intrinsic

function can only be used in privileged mode, and is only available for Cortex-M

devices.

## \_\_get\_LR

Syntax unsigned long \_\_get\_LR(void);

**Description** Returns the value of the link register (R14).

### \_\_get\_MSP

Syntax unsigned long \_\_get\_MSP(void);

Description Returns the value of the MSP register (Main Stack Pointer). This intrinsic function can

only be used in privileged mode, and is only available for Cortex-M devices.

## \_\_get\_PRIMASK

Syntax unsigned long \_\_get\_PRIMASK(void);

Description Returns the value of the PRIMASK register. This intrinsic function can only be used in

privileged mode and it requires a Cortex-M device.

# \_\_get\_PSP

Syntax unsigned long \_\_get\_PSP(void);

Description Returns the value of the PSP register (Process Stack Pointer). This intrinsic function can

only be used in privileged mode, and is only available for Cortex-M devices.

## \_\_get\_PSR

Syntax unsigned long \_\_get\_PSR(void);

Description Returns the value of the PSR register (combined Program Status Register). This intrinsic

function can only be used in privileged mode, and is only available for Cortex-M

devices.

## \_\_get\_SB

Syntax unsigned long \_\_get\_SB(void);

**Description** Returns the value of the static base register (R9).

Syntax unsigned long \_\_get\_SP(void);

Description Returns the value of the stack pointer register (R13).

\_\_ISB
Syntax void \_\_ISB(void);

Description Inserts an ISB instruction. This intrinsic function requires an ARM v6M architecture, or an ARM v7 architecture or higher.

\_\_LDC
\_\_LDCL
\_\_LDC2

Syntax void \_\_nnn(\_\_ul coproc, \_\_ul CRn, \_\_ul const \*src);

where nnn can be one of LDC, LDCL, LDC2, or LDC2L.

**Parameters** 

LDC2L

coproc The coprocessor number 0..15.

CRn The coprocessor register to load.

src A pointer to the data to load.

Description Inserts the coprocessor load instruction LDC—or one of its variants—which means that

a value will be loaded into a coprocessor register. The parameters coproc and CRn will

be encoded in the instruction and must therefore be constants.

LDC_noidx
LDCL_noidx
LDC2_noidx
LDC2L noidx

Syntax void \_\_nnn\_noidx(\_\_ul coproc, \_\_ul CRn, \_\_ul const \*src, \_\_ul

option);

where nnn can be one of LDC, LDCL, LDC2, or LDC2L.

**Parameters** 

coprocThe coprocessor number 0..15.CRnThe coprocessor register to load.srcA pointer to the data to load.

option Additional coprocessor option 0..255.

**Description** Inserts the coprocessor

Inserts the coprocessor load instruction LDC, or one of its variants. A value will be loaded into a coprocessor register. The parameters *coproc*, *CRn*, and *option* will be

encoded in the instruction and must therefore be constants.

### LDREX

Syntax unsigned long \_\_LDREX(unsigned long \*);

**Description** Inserts an LDREX instruction.

This intrinsic function requires an ARM v6 architecture or higher for ARM mode, and

ARM v6T2 or higher for Thumb mode.

## \_\_MCR

Syntax void \_\_MCR(\_\_ul coproc, \_\_ul opcode\_1, \_\_ul src, \_\_ul CRn, \_\_ul

CRm, \_\_ul opcode\_2);

**Parameters** 

coproc The coprocessor number 0..15.

opcode\_1 Coprocessor-specific operation code.

src The value to be written to the coprocessor.

CRn The coprocessor register to write to.

CRm Additional coprocessor register; set to zero if not used.

Additional coprocessor-specific operation code; set to zero if not used. opcode\_2

Description

Inserts a coprocessor write instruction (MCR). A value will be written to a coprocessor register. The parameters coproc, opcode\_1, CRn, CRm, and opcode\_2 will be encoded in the MCR instruction operation code and must therefore be constants.

This intrinsic function requires either ARM mode, or an ARM v6T2 or higher for Thumb mode.

#### **MRC**

unsigned long \_\_MRC(\_\_ul coproc, \_\_ul opcode\_1, \_\_ul CRn, \_\_ul Syntax

CRm, \_\_ul opcode\_2);

**Parameters** 

The coprocessor number 0..15. coproc

opcode\_1 Coprocessor-specific operation code.

CRn The coprocessor register to write to.

CRm Additional coprocessor register; set to zero if not used.

Additional coprocessor-specific operation code; set to zero if not used. opcode\_2

Description Inserts a coprocessor read instruction (MRC). Returns the value of the specified

> coprocessor register. The parameters coproc, opcode\_1, CRn, CRm, and opcode\_2 will be encoded in the MRC instruction operation code and must therefore be constants.

This intrinsic function requires either ARM mode, or an ARM v6T2 or higher for Thumb mode.

### no\_operation

Syntax void \_\_no\_operation(void);

Description Inserts a NOP instruction.

#### PKHBT

Syntax unsigned long  $\_$ \_PKHBT(unsigned long x, unsigned long y, unsigned

long count);

**Parameters** 

x First operand.

y Second operand, optionally shifted left.

count Shift count 0-31, where 0 means no shift.

Description Inserts a PKHBT instruction, with an optionally shifted operand (LSL) for count in the

range 1-31.

This intrinsic function requires an ARM v6 architecture or higher for ARM mode, and

ARM v7A, ARM v7R, or ARM v7E-M for Thumb mode.

### \_\_PKHTB

Syntax unsigned long  $\_$ PKHTB(unsigned long x, unsigned long y, unsigned

long count);

**Parameters** 

x First operand.

y Second operand, optionally shifted right (arithmetic shift).

count Shift count 0-32, where 0 means no shift.

Description Inserts a PKHTB instruction, with an optionally shifted operand (ASR) for count in the

range 1-32.

This intrinsic function requires an ARM v6 architecture or higher for ARM mode, and

ARM v7A, ARM v7R, or ARM v7E-M for Thumb mode.

## \_\_QADD

Syntax signed long \_\_QADD(signed long, signed long);

**Description** Inserts a QADD instruction.

This intrinsic function requires an ARM v5E architecture or higher for ARM mode, and

#### \_\_QADD8

Syntax unsigned long \_\_QADD8(unsigned long, unsigned long);

**Description** Inserts a QADD8 instruction.

This intrinsic function requires an ARM v6 architecture or higher for ARM mode, and

ARM v7A, ARM v7R, or ARM v7E-M for Thumb mode.

### QADD16

Syntax unsigned long \_\_QADD16(unsigned long, unsigned long);

**Description** Inserts a QADD16 instruction.

This intrinsic function requires an ARM v6 architecture or higher for ARM mode, and

ARM v7A, ARM v7R, or ARM v7E-M for Thumb mode.

### \_\_QASX

Syntax unsigned long \_\_QASX(unsigned long, unsigned long);

**Description** Inserts a QASX instruction.

This intrinsic function requires an ARM v6 architecture or higher for ARM mode, and

ARM v7A, ARM v7R, or ARM v7E-M for Thumb mode.

## \_\_QCFlag

Syntax unsigned long \_\_QCFlag(void);

Description Returns the value of the cumulative saturation flag QC of the FPSCR register

(Floating-point Status and Control Register). This intrinsic function is only available for

devices with Neon (Advanced SIMD).

## \_\_QDADD

Syntax signed long \_\_QDADD(signed long, signed long);

**Description** Inserts a QDADD instruction.

This intrinsic function requires an ARM v5E architecture or higher for ARM mode, and ARM v7A, ARM v7R, or ARM v7E-M for Thumb mode.

### **QDOUBLE**

Syntax signed long \_\_QDOUBLE(signed long);

**Description** Inserts an instruction QADD Rd, Rs, Rs for a source register Rs, and a destination register

Rd.

This intrinsic function requires an ARM v5E architecture or higher for ARM mode, and

ARM v7A, ARM v7R, or ARM v7E-M for Thumb mode.

### \_\_QDSUB

Syntax signed long \_\_QDSUB(signed long, signed long);

**Description** Inserts a QDSUB instruction.

This intrinsic function requires an ARM v5E architecture or higher for ARM mode, and

ARM v7A, ARM v7R, or ARM v7E-M for Thumb mode.

## \_\_QFlag

Syntax int \_\_QFlag(void);

**Description** Returns the Q flag that indicates if overflow/saturation has occurred.

This intrinsic function requires an ARM v5E architecture or higher for ARM mode, and

ARM v7A, ARM v7R, or ARM v7E-M for Thumb mode.

## \_\_QSAX

Syntax unsigned long \_\_QSAX(unsigned long, unsigned long);

**Description** Inserts a QSAX instruction.

This intrinsic function requires an ARM v6 architecture or higher for ARM mode, and

### \_\_QSUB

Syntax signed long \_\_QSUB(signed long, signed long);

**Description** Inserts a QSUB instruction.

This intrinsic function requires an ARM v5E architecture or higher for ARM mode, and

ARM v7A, ARM v7R, or ARM v7E-M for Thumb mode.

### QSUB8

Syntax unsigned long \_\_QSUB8(unsigned long, unsigned long);

**Description** Inserts a QSUB8 instruction.

This intrinsic function requires an ARM v6 architecture or higher for ARM mode, and

ARM v7A, ARM v7R, or ARM v7E-M for Thumb mode.

### \_\_QSUB16

Syntax unsigned long \_\_QSUB16(unsigned long, unsigned long);

**Description** Inserts a QSUB16 instruction.

This intrinsic function requires an ARM v6 architecture or higher for ARM mode, and

ARM v7A, ARM v7R, or ARM v7E-M for Thumb mode.

## \_\_reset\_Q\_flag

Syntax void \_\_reset\_Q\_flag(void);

Description Clears the Q flag that indicates if overflow/saturation has occurred.

This intrinsic function requires an ARM v5E architecture or higher for ARM mode, and

## \_\_reset\_QC\_flag

Syntax void \_\_reset\_QC\_flag(void);

Description Clears the value of the cumulative saturation flag QC of the FPSCR register

(Floating-point Status and Control Register). This intrinsic function is only available for

devices with Neon (Advanced SIMD).

### \_\_REV

Syntax unsigned long \_\_REV(unsigned long);

Description Inserts an REV instruction. This intrinsic function requires an ARM v6 architecture or

higher.

#### \_\_REVSH

Syntax signed long \_\_REVSH(short);

**Description** Inserts an REVSH instruction. This intrinsic function requires an ARM v6 architecture or

higher.

#### \_\_SADD8

Syntax unsigned long \_\_SADD8(unsigned long, unsigned long);

**Description** Inserts an SADD8 instruction.

This intrinsic function requires an ARM v6 architecture or higher for ARM mode, and

ARM v7A, ARM v7R, or ARM v7E-M for Thumb mode.

## \_\_SADD16

Syntax unsigned long \_\_SADD16(unsigned long, unsigned long);

**Description** Inserts an SADD16 instruction.

This intrinsic function requires an ARM v6 architecture or higher for ARM mode, and

#### SASX

Syntax unsigned long \_\_SASX(unsigned long, unsigned long);

**Description** Inserts an SASX instruction.

This intrinsic function requires an ARM v6 architecture or higher for ARM mode, and

ARM v7A, ARM v7R, or ARM v7E-M for Thumb mode.

### \_\_SEL

Syntax unsigned long \_\_SEL(unsigned long, unsigned long);

**Description** Inserts an SEL instruction.

This intrinsic function requires an ARM v6 architecture or higher for ARM mode, and

ARM v7A, ARM v7R, or ARM v7E-M for Thumb mode.

### \_\_set\_BASEPRI

Syntax void \_\_set\_BASEPRI(unsigned long);

Description Sets the value of the BASEPRI register. This intrinsic function can only be used in

privileged mode and it requires a Cortex-M3 or Cortex-M4 device.

### \_\_set\_CONTROL

Syntax void \_\_set\_CONTROL(unsigned long);

Description Sets the value of the CONTROL register. This intrinsic function can only be used in

privileged mode and it requires a Cortex-M device.

#### \_\_set\_CPSR

Syntax void \_\_set\_CPSR(unsigned long);

Description Sets the value of the ARM CPSR (Current Program Status Register). Only the control

field is changed (bits 0-7). This intrinsic function can only be used in privileged mode,

is not available for Cortex-M devices, and it requires ARM mode.

### \_\_set\_FAULTMASK

Syntax void \_\_set\_FAULTMASK(unsigned long);

Description Sets the value of the FAULTMASK register. This intrinsic function can only be used in

privileged mode and it requires a Cortex-M3 or Cortex-M4 device.

### \_\_set\_interrupt\_state

Syntax void \_\_set\_interrupt\_state(\_\_istate\_t);

Descriptions Restores the interrupt state to a value previously returned by the

\_\_get\_interrupt\_state function.

For information about the \_\_istate\_t type, see \_\_get\_interrupt\_state, page 333.

### \_\_set\_LR

Syntax void \_\_set\_LR(unsigned long);

Description Assigns a new address to the link register (R14).

### set MSP

Syntax void \_\_set\_MSP(unsigned long);

Description Sets the value of the MSP register (Main Stack Pointer). This intrinsic function can only

be used in privileged mode, and is only available for Cortex-M devices.

## set PRIMASK

Syntax void \_\_set\_PRIMASK(unsigned long);

Description Sets the value of the PRIMASK register. This intrinsic function can only be used in

privileged mode and it requires a Cortex-M device.

### \_\_set\_PSP

Syntax void \_\_set\_PSP(unsigned long);

Description Sets the value of the PSP register (Process Stack Pointer). This intrinsic function can

only be used in privileged mode, and is only available for Cortex-M devices.

#### set SB

Syntax void \_\_set\_SB(unsigned long);

**Description** Assigns a new address to the static base register (R9).

### \_\_set\_SP

Syntax void \_\_set\_SP(unsigned long);

Description Assigns a new address to the stack pointer register (R13).

### \_\_SHADD8

Syntax unsigned long \_\_SHADD8(unsigned long, unsigned long);

**Description** Inserts an SHADD8 instruction.

This intrinsic function requires an ARM v6 architecture or higher for ARM mode, and

ARM v7A, ARM v7R, or ARM v7E-M for Thumb mode.

### \_\_SHADD16

Syntax unsigned long \_\_SHADD16(unsigned long, unsigned long);

**Description** Inserts an SHADD16 instruction.

This intrinsic function requires an ARM v6 architecture or higher for ARM mode, and

### \_\_SHASX

Syntax unsigned long \_\_SHASX(unsigned long, unsigned long);

**Description** Inserts an SHASX instruction.

This intrinsic function requires an ARM v6 architecture or higher for ARM mode, and

ARM v7A, ARM v7R, or ARM v7E-M for Thumb mode.

### \_\_SHSAX

Syntax unsigned long \_\_SHSAX(unsigned long, unsigned long);

**Description** Inserts an SHSAX instruction.

This intrinsic function requires an ARM v6 architecture or higher for ARM mode, and

ARM v7A, ARM v7R, or ARM v7E-M for Thumb mode.

### \_\_SHSUB8

Syntax unsigned long \_\_SHSUB8(unsigned long, unsigned long);

Description Inserts an SHSUB8 instruction.

This intrinsic function requires an ARM v6 architecture or higher for ARM mode, and

ARM v7A, ARM v7R, or ARM v7E-M for Thumb mode.

## \_\_SHSUB16

Syntax unsigned long \_\_SHSUB16(unsigned long, unsigned long);

**Description** Inserts an SHSUB16 instruction.

This intrinsic function requires an ARM v6 architecture or higher for ARM mode, and

ARM v7A, ARM v7R, or ARM v7E-M for Thumb mode.

## \_\_SMLABB

Syntax unsigned long \_\_SMLABB(unsigned long, unsigned long, unsigned

long);

**Description** Inserts an SMLABB instruction.

This intrinsic function requires an ARM v6 architecture or higher for ARM mode, and ARM v7A, ARM v7R, or ARM v7E-M for Thumb mode.

### \_\_SMLABT

Syntax unsigned long \_\_SMLABT(unsigned long, unsigned long, unsigned

long);

**Description** Inserts an SMLABT instruction.

This intrinsic function requires an ARM v6 architecture or higher for ARM mode, and

ARM v7A, ARM v7R, or ARM v7E-M for Thumb mode.

### \_\_SMLAD

Syntax unsigned long \_\_SMLAD(unsigned long, unsigned long, unsigned

long);

**Description** Inserts an SMLAD instruction.

This intrinsic function requires an ARM v6 architecture or higher for ARM mode, and

ARM v7A, ARM v7R, or ARM v7E-M for Thumb mode.

### \_\_SMLADX

Syntax unsigned long \_\_SMLADX(unsigned long, unsigned long, unsigned

long);

**Description** Inserts an SMLADX instruction.

This intrinsic function requires an ARM v6 architecture or higher for ARM mode, and

ARM v7A, ARM v7R, or ARM v7E-M for Thumb mode.

### \_\_SMLALBB

Syntax unsigned long long \_\_SMLALBB(unsigned long, unsigned long,

unsigned long);

**Description** Inserts an SMLALBB instruction.

This intrinsic function requires an ARM v6 architecture or higher for ARM mode, and

### \_\_SMLALBT

Syntax unsigned long long \_\_SMLALBT(unsigned long, unsigned long,

unsigned long);

**Description** Inserts an SMLALBT instruction.

This intrinsic function requires an ARM v6 architecture or higher for ARM mode, and

ARM v7A, ARM v7R, or ARM v7E-M for Thumb mode.

### SMLALD

Syntax unsigned long long \_\_SMLALD(unsigned long, unsigned long,

unsigned long);

**Description** Inserts an SMLALD instruction.

This intrinsic function requires an ARM v6 architecture or higher for ARM mode, and

ARM v7A, ARM v7R, or ARM v7E-M for Thumb mode.

### **SMLALDX**

Syntax unsigned long long \_\_SMLALDX(unsigned long, unsigned long,

unsigned long);

**Description** Inserts an SMLALDX instruction.

This intrinsic function requires an ARM v6 architecture or higher for ARM mode, and

ARM v7A, ARM v7R, or ARM v7E-M for Thumb mode.

### \_\_SMLALTB

Syntax unsigned long long \_\_SMLALTB(unsigned long, unsigned long,

unsigned long);

Description Inserts an SMLALTB instruction.

This intrinsic function requires an ARM v6 architecture or higher for ARM mode, and

### \_\_SMLALTT

Syntax unsigned long long \_\_SMLALTT(unsigned long, unsigned long,

unsigned long);

**Description** Inserts an SMLALTT instruction.

This intrinsic function requires an ARM v6 architecture or higher for ARM mode, and

ARM v7A, ARM v7R, or ARM v7E-M for Thumb mode.

### \_\_SMLATB

Syntax unsigned long \_\_SMLATB(unsigned long, unsigned long, unsigned

long);

**Description** Inserts an SMLATB instruction.

This intrinsic function requires an ARM v6 architecture or higher for ARM mode, and

ARM v7A, ARM v7R, or ARM v7E-M for Thumb mode.

#### SMLATT

Syntax unsigned long \_\_SMLATT(unsigned long, unsigned long, unsigned

long);

**Description** Inserts an SMLATT instruction.

This intrinsic function requires an ARM v6 architecture or higher for ARM mode, and

ARM v7A, ARM v7R, or ARM v7E-M for Thumb mode.

### \_\_SMLAWB

Syntax unsigned long \_\_SMLAWB(unsigned long, unsigned long, unsigned

long);

**Description** Inserts an SMLAWB instruction.

This intrinsic function requires an ARM v6 architecture or higher for ARM mode, and

### \_\_SMLAWT

Syntax unsigned long \_\_SMLAWT(unsigned long, unsigned long, unsigned

long);

**Description** Inserts an SMLAWT instruction.

This intrinsic function requires an ARM v6 architecture or higher for ARM mode, and

ARM v7A, ARM v7R, or ARM v7E-M for Thumb mode.

### SMLSD

Syntax unsigned long \_\_SMLSD(unsigned long, unsigned long, unsigned

long);

**Description** Inserts an SMLSD instruction.

This intrinsic function requires an ARM v6 architecture or higher for ARM mode, and

ARM v7A, ARM v7R, or ARM v7E-M for Thumb mode.

### SMLSDX

Syntax unsigned long \_\_SMLSDX(unsigned long, unsigned long, unsigned

long);

**Description** Inserts an SMLSDX instruction.

This intrinsic function requires an ARM v6 architecture or higher for ARM mode, and

ARM v7A, ARM v7R, or ARM v7E-M for Thumb mode.

### \_\_SMLSLD

Syntax unsigned long long \_\_SMLSLD(unsigned long, unsigned long,

unsigned long);

Description Inserts an SMLSLD instruction.

This intrinsic function requires an ARM v6 architecture or higher for ARM mode, and

### \_\_SMLSLDX

Syntax unsigned long long \_\_SMLSLDX(unsigned long, unsigned long,

unsigned long);

Description Inserts an SMLSLDX instruction.

This intrinsic function requires an ARM v6 architecture or higher for ARM mode, and

ARM v7A, ARM v7R, or ARM v7E-M for Thumb mode.

### SMMLA

Syntax unsigned long \_\_SMMLA(unsigned long, unsigned long, unsigned

long);

**Description** Inserts an SMMLA instruction.

This intrinsic function requires an ARM v6 architecture or higher for ARM mode, and

ARM v7A, ARM v7R, or ARM v7E-M for Thumb mode.

### SMMLAR

Syntax unsigned long \_\_SMMLAR(unsigned long, unsigned long, unsigned

long);

Description Inserts an SMMLAR instruction.

This intrinsic function requires an ARM v6 architecture or higher for ARM mode, and

ARM v7A, ARM v7R, or ARM v7E-M for Thumb mode.

### \_\_SMMLS

Syntax unsigned long \_\_SMMLS(unsigned long, unsigned long, unsigned

long);

**Description** Inserts an SMMLS instruction.

This intrinsic function requires an ARM v6 architecture or higher for ARM mode, and

### \_\_SMMLSR

Syntax unsigned long \_\_SMMLSR(unsigned long, unsigned long, unsigned

long);

**Description** Inserts an SMMLSR instruction.

This intrinsic function requires an ARM v6 architecture or higher for ARM mode, and

ARM v7A, ARM v7R, or ARM v7E-M for Thumb mode.

### SMMUL

Syntax unsigned long \_\_SMMUL(unsigned long, unsigned long);

Description Inserts an SMMUL instruction.

This intrinsic function requires an ARM v6 architecture or higher for ARM mode, and

ARM v7A, ARM v7R, or ARM v7E-M for Thumb mode.

### SMMULR

Syntax unsigned long \_\_SMMULR(unsigned long, unsigned long);

**Description** Inserts an SMMULR instruction.

This intrinsic function requires an ARM v6 architecture or higher for ARM mode, and

ARM v7A, ARM v7R, or ARM v7E-M for Thumb mode.

#### SMUAD

Syntax unsigned long \_\_SMUAD(unsigned long, unsigned long);

**Description** Inserts an SMUAD instruction.

This intrinsic function requires an ARM v6 architecture or higher for ARM mode, and

ARM v7A, ARM v7R, or ARM v7E-M for Thumb mode.

## \_\_SMUADX

Syntax unsigned long \_\_SMUADX(unsigned long, unsigned long);

**Description** Inserts an SMUADX instruction.

This intrinsic function requires an ARM v6 architecture or higher for ARM mode, and ARM v7A, ARM v7R, or ARM v7E-M for Thumb mode.

### \_\_SMUL

Syntax signed long \_\_SMUL(signed short, signed short);

**Description** Inserts a signed 16-bit multiplication.

This intrinsic function requires an ARM v5E architecture or higher for ARM mode, and ARM v7A ARM v7P, or ARM v7E M for Thumb mode.

ARM v7A, ARM v7R, or ARM v7E-M for Thumb mode.

### \_\_SMULBB

Syntax unsigned long \_\_SMULBB(unsigned long, unsigned long);

Description Inserts an SMULBB instruction.

This intrinsic function requires an ARM v6 architecture or higher for ARM mode, and

ARM v7A, ARM v7R, or ARM v7E-M for Thumb mode.

## **SMULBT**

Syntax unsigned long \_\_SMULBT(unsigned long, unsigned long);

**Description** Inserts an SMULBT instruction.

This intrinsic function requires an ARM v6 architecture or higher for ARM mode, and

ARM v7A, ARM v7R, or ARM v7E-M for Thumb mode.

## \_\_SMULTB

Syntax unsigned long \_\_SMULTB(unsigned long, unsigned long);

**Description** Inserts an SMULTB instruction.

This intrinsic function requires an ARM v6 architecture or higher for ARM mode, and

### \_\_SMULTT

Syntax unsigned long \_\_SMULTT(unsigned long, unsigned long);

**Description** Inserts an SMULTT instruction.

This intrinsic function requires an ARM v6 architecture or higher for ARM mode, and

ARM v7A, ARM v7R, or ARM v7E-M for Thumb mode.

### \_\_SMULWB

Syntax unsigned long \_\_SMULWB(unsigned long, unsigned long);

**Description** Inserts an SMULWB instruction.

This intrinsic function requires an ARM v6 architecture or higher for ARM mode, and

ARM v7A, ARM v7R, or ARM v7E-M for Thumb mode.

### \_\_SMULWT

Syntax unsigned long \_\_SMULWT(unsigned long, unsigned long);

**Description** Inserts an SMULWT instruction.

This intrinsic function requires an ARM v6 architecture or higher for ARM mode, and

ARM v7A, ARM v7R, or ARM v7E-M for Thumb mode.

### \_\_SMUSD

Syntax unsigned long \_\_SMUSD(unsigned long, unsigned long);

**Description** Inserts an SMUSD instruction.

This intrinsic function requires an ARM v6 architecture or higher for ARM mode, and

ARM v7A, ARM v7R, or ARM v7E-M for Thumb mode.

## \_\_SMUSDX

Syntax unsigned long \_\_SMUSDX(unsigned long, unsigned long);

**Description** Inserts an SMUSDX instruction.

This intrinsic function requires an ARM v6 architecture or higher for ARM mode, and ARM v7A, ARM v7R, or ARM v7E-M for Thumb mode.

#### SSAT

Syntax unsigned long \_\_SSAT(unsigned long, unsigned long);

**Description** Inserts an SSAT instruction.

The compiler will incorporate a shift instruction into the operand when possible. For example,  $\_\_SSAT(x << 3.11)$  compiles to SSAT Rd, #11, Rn, LSL #3, where the value of x has been placed in register Rn and the return value of  $\_\_SSAT$  will be placed in register Rd.

This intrinsic function requires an ARM v6 architecture or higher for ARM mode, and ARM v7A, ARM v7R, or ARM v7-M for Thumb mode.

### SSAT16

Syntax unsigned long \_\_SSAT16(unsigned long, unsigned long);

**Description** Inserts an SSAT16 instruction.

This intrinsic function requires an ARM v6 architecture or higher for ARM mode, and ARM v7A, ARM v7R, or ARM v7E-M for Thumb mode.

### \_\_SSAX

Syntax unsigned long \_\_SSAX(unsigned long, unsigned long);

Description Inserts an SSAX instruction.

This intrinsic function requires an ARM v6 architecture or higher for ARM mode, and ARM v7A, ARM v7R, or ARM v7E-M for Thumb mode.

### \_\_SSUB8

Syntax unsigned long \_\_SSUB8(unsigned long, unsigned long);

**Description** Inserts an SSUB8 instruction.

This intrinsic function requires an ARM v6 architecture or higher for ARM mode, and ARM v7A, ARM v7R, or ARM v7E-M for Thumb mode.

#### SSUB16

Syntax unsigned long \_\_SSUB16(unsigned long, unsigned long);

**Description** Inserts an SSUB16 instruction.

This intrinsic function requires an ARM v6 architecture or higher for ARM mode, and ARM v7A, ARM v7R, or ARM v7E-M for Thumb mode.

\_\_STC \_\_STCL \_\_STC2 STC2L

Syntax void \_\_nnn(\_\_ul coproc, \_\_ul CRn, \_\_ul const \*dst);

where nnn can be one of STC, STCL, STC2, or STC2L.

**Parameters** 

COPY The coprocessor number 0..15.

CRN The coprocessor register to load.

dst A pointer to the destination.

Description

Inserts the coprocessor store instruction STC—or one of its variants—which means that the value of the specified coprocessor register will be written to a memory location. The parameters <code>coproc</code> and <code>CRn</code> will be encoded in the instruction and must therefore be constants.

\_\_STC\_noidx \_\_STCL\_noidx \_\_STC2\_noidx \_\_STC2L\_noidx

Syntax

void \_\_nnn\_noidx(\_\_ul coproc, \_\_ul CRn, \_\_ul const \*dst, \_\_ul

option);

where nnn can be one of STC, STCL, STC2, or STC2L.

**Parameters** 

coproc The coprocessor number 0..15.

CRn The coprocessor register to load.

dst A pointer to the destination.

option Additional coprocessor option 0..255.

Description

Inserts the coprocessor store instruction STC—or one of its variants—which means that the value of the specified coprocessor register will be written to a memory location. The parameters <code>coproc</code>, <code>CRn</code>, and <code>option</code> will be encoded in the instruction and must therefore be constants.

#### STREX

Syntax unsigned long \_\_STREX(unsigned long, unsigned long \*);

**Description** Inserts an STREX instruction.

This intrinsic function requires an ARM v6 architecture or higher for ARM mode, and

ARM v6T2 or higher for Thumb mode.

#### \_\_SWP

Syntax unsigned long \_\_SWP(unsigned long, unsigned long \*);

Description Inserts an SWP instruction. This intrinsic function requires ARM mode.

### \_\_SWPB

Syntax char \_\_SWPB(unsigned char, unsigned char \*);

Description Inserts an SWPB instruction. This intrinsic function requires ARM mode.

## \_\_SXTAB

Syntax unsigned long \_\_SXTAB(unsigned long, unsigned long);

**Description** Inserts an SXTAB instruction.

This intrinsic function requires an ARM v6 architecture or higher for ARM mode, and ARM v7A, ARM v7R, or ARM v7E-M for Thumb mode.

#### SXTAB16

Syntax unsigned long \_\_SXTAB16(unsigned long, unsigned long);

**Description** Inserts an SXTAB16 instruction.

This intrinsic function requires an ARM v6 architecture or higher for ARM mode, and

ARM v7A, ARM v7R, or ARM v7E-M for Thumb mode.

#### SXTAH

Syntax unsigned long \_\_SXTAH(unsigned long, unsigned long);

**Description** Inserts an SXTAH instruction.

This intrinsic function requires an ARM v6 architecture or higher for ARM mode, and

ARM v7A, ARM v7R, or ARM v7E-M for Thumb mode.

### SXTB16

Syntax unsigned long \_\_SXTB16(unsigned long);

**Description** Inserts an SXTB16 instruction.

This intrinsic function requires an ARM v6 architecture or higher for ARM mode, and

ARM v7A, ARM v7R, or ARM v7E-M for Thumb mode.

### UADD8

Syntax unsigned long \_\_UADD8(unsigned long, unsigned long);

**Description** Inserts a UADD8 instruction.

This intrinsic function requires an ARM v6 architecture or higher for ARM mode, and

### \_\_UADD16

Syntax unsigned long \_\_UADD16(unsigned long, unsigned long);

**Description** Inserts a UADD16 instruction.

### \_\_UASX

Syntax unsigned long \_\_UASX(unsigned long, unsigned long);

Description Inserts a UASX instruction.

This intrinsic function requires an ARM v6 architecture or higher for ARM mode, and

ARM v7A, ARM v7R, or ARM v7E-M for Thumb mode.

### \_\_UHADD8

Syntax unsigned long \_\_UHADD8(unsigned long, unsigned long);

**Description** Inserts a UHADD8 instruction.

This intrinsic function requires an ARM v6 architecture or higher for ARM mode, and

ARM v7A, ARM v7R, or ARM v7E-M for Thumb mode.

#### UHADD16

Syntax unsigned long \_\_UHADD16(unsigned long, unsigned long);

**Description** Inserts a UHADD16 instruction.

This intrinsic function requires an ARM v6 architecture or higher for ARM mode, and

ARM v7A, ARM v7R, or ARM v7E-M for Thumb mode.

### UHASX

Syntax unsigned long \_\_UHASX(unsigned long, unsigned long);

**Description** Inserts a UHASX instruction.

This intrinsic function requires an ARM v6 architecture or higher for ARM mode, and

### UHSAX

Syntax unsigned long \_\_UHSAX(unsigned long, unsigned long);

**Description** Inserts a UHSAX instruction.

This intrinsic function requires an ARM v6 architecture or higher for ARM mode, and

ARM v7A, ARM v7R, or ARM v7E-M for Thumb mode.

### UHSUB8

Syntax unsigned long \_\_UHSUB8(unsigned long, unsigned long);

**Description** Inserts a UHSUB8 instruction.

This intrinsic function requires an ARM v6 architecture or higher for ARM mode, and

ARM v7A, ARM v7R, or ARM v7E-M for Thumb mode.

### \_\_UHSUB16

Syntax unsigned long \_\_UHSUB16(unsigned long, unsigned long);

**Description** Inserts a UHSUB16 instruction.

This intrinsic function requires an ARM v6 architecture or higher for ARM mode, and

ARM v7A, ARM v7R, or ARM v7E-M for Thumb mode.

### \_\_UMAAL

Syntax unsigned long long \_\_UMAAL(unsigned long, unsigned long,

unsigned long, unsigned long);

Description Inserts an UMAAL instruction.

This intrinsic function requires an ARM v6 architecture or higher for ARM mode, and

ARM v7A, ARM v7R, or ARM v7E-M for Thumb mode.

## \_\_UQADD8

Syntax unsigned long \_\_UQADD8(unsigned long, unsigned long);

**Description** Inserts a UQADD8 instruction.

This intrinsic function requires an ARM v6 architecture or higher for ARM mode, and ARM v7A, ARM v7R, or ARM v7E-M for Thumb mode.

## \_\_UQADD16

Syntax unsigned long \_\_UQADD16(unsigned long, unsigned long);

**Description** Inserts a UQADD16 instruction.

This intrinsic function requires an ARM v6 architecture or higher for ARM mode, and

ARM v7A, ARM v7R, or ARM v7E-M for Thumb mode.

## \_\_UQASX

Syntax unsigned long \_\_UQASX(unsigned long, unsigned long);

**Description** Inserts a UQASX instruction.

This intrinsic function requires an ARM v6 architecture or higher for ARM mode, and

ARM v7A, ARM v7R, or ARM v7E-M for Thumb mode.

## \_\_UQSAX

Syntax unsigned long \_\_UQSAX(unsigned long, unsigned long);

**Description** Inserts a UQSAX instruction.

This intrinsic function requires an ARM v6 architecture or higher for ARM mode, and

ARM v7A, ARM v7R, or ARM v7E-M for Thumb mode.

## \_\_UQSUB8

Syntax unsigned long \_\_UQSUB8(unsigned long, unsigned long);

Description Inserts a UQSUB8 instruction.

This intrinsic function requires an ARM v6 architecture or higher for ARM mode, and

ARM v7A, ARM v7R, or ARM v7E-M for Thumb mode.

## \_\_UQSUB16

Syntax unsigned long \_\_UQSUB16(unsigned long, unsigned long);

**Description** Inserts a UQSUB16 instruction.

This intrinsic function requires an ARM v6 architecture or higher for ARM mode, and

ARM v7A, ARM v7R, or ARM v7E-M for Thumb mode.

## USAD8

Syntax unsigned long \_\_USAD8(unsigned long, unsigned long);

**Description** Inserts a USAD8 instruction.

This intrinsic function requires an ARM v6 architecture or higher for ARM mode, and

ARM v7A, ARM v7R, or ARM v7E-M for Thumb mode.

## \_\_USADA8

Syntax unsigned long \_\_USADAS8(unsigned long, unsigned long);

**Description** Inserts a USADA8 instruction.

This intrinsic function requires an ARM v6 architecture or higher for ARM mode, and

ARM v7A, ARM v7R, or ARM v7E-M for Thumb mode.

## \_\_USAT

Syntax unsigned long \_\_USAT(unsigned long, unsigned long);

**Description** Inserts a USAT instruction.

The compiler will incorporate a shift instruction into the operand when possible. For example,  $\_\_USAT(x << 3,11)$  compiles to USAT Rd, #11, Rn, LSL #3, where the value of x has been placed in register Rn and the return value of  $\_\_USAT$  will be placed

in register Rd.

This intrinsic function requires an ARM v6 architecture or higher for ARM mode, and

ARM v7A, ARM v7R, or ARM v7M for Thumb mode.

## USAT16

Syntax unsigned long \_\_USAT16(unsigned long, unsigned long);

Description Inserts a USAT16 instruction.

This intrinsic function requires an ARM v6 architecture or higher for ARM mode, and

ARM v7A, ARM v7R, or ARM v7E-M for Thumb mode.

## **USAX**

Syntax unsigned long \_\_USAX(unsigned long, unsigned long);

Description Inserts a USAX instruction.

This intrinsic function requires an ARM v6 architecture or higher for ARM mode, and

ARM v7A, ARM v7R, or ARM v7E-M for Thumb mode.

## **USUB8**

Syntax unsigned long \_\_USUB8(unsigned long, unsigned long);

Description Inserts a USUB8 instruction.

This intrinsic function requires an ARM v6 architecture or higher for ARM mode, and

ARM v7A, ARM v7R, or ARM v7E-M for Thumb mode.

## USUB16

Syntax unsigned long \_\_USUB16(unsigned long, unsigned long);

Description Inserts a USUB16 instruction.

This intrinsic function requires an ARM v6 architecture or higher for ARM mode, and

ARM v7A, ARM v7R, or ARM v7E-M for Thumb mode.

## **UXTAB**

unsigned long \_\_UXTAB(unsigned long, unsigned long); Syntax

Description Inserts a UXTAB instruction. This intrinsic function requires an ARM v6 architecture or higher for ARM mode, and ARM v7A, ARM v7R, or ARM v7E-M for Thumb mode.

## \_\_UXTAB16

Syntax unsigned long \_\_UXTAB16(unsigned long, unsigned long);

**Description** Inserts a UXTAB16 instruction.

This intrinsic function requires an ARM v6 architecture or higher for ARM mode, and ARM v7A, ARM v7R, or ARM v7E-M for Thumb mode.

## \_\_UXTAH

Syntax unsigned long \_\_UXTAH(unsigned long, unsigned long);

Description Inserts a UXTAH instruction.

This intrinsic function requires an ARM v6 architecture or higher for ARM mode, and

ARM v7A, ARM v7R, or ARM v7E-M for Thumb mode.

## UXTB16

Syntax unsigned long \_\_UXTB16(unsigned long);

**Description** Inserts a UXTB16 instruction.

This intrinsic function requires an ARM v6 architecture or higher for ARM mode, and

ARM v7A, ARM v7R, or ARM v7E-M for Thumb mode.

## The preprocessor

This chapter gives a brief overview of the preprocessor, including reference information about the different preprocessor directives, symbols, and other related information.

## Overview of the preprocessor

The preprocessor of the IAR C/C++ Compiler for ARM adheres to Standard C. The compiler also makes these preprocessor-related features available to you:

• Predefined preprocessor symbols

These symbols allow you to inspect the compile-time environment, for example the time and date of compilation. For more information, see *Descriptions of predefined preprocessor symbols*, page 366.

- User-defined preprocessor symbols defined using a compiler option
   In addition to defining your own preprocessor symbols using the #define directive, you can also use the option -D, see -D, page 220.
- Preprocessor extensions

There are several preprocessor extensions, for example many pragma directives; for more information, see the chapter *Pragma directives* in this guide. For information about the corresponding \_Pragma operator and the other extensions related to the preprocessor, see *Descriptions of miscellaneous preprocessor extensions*, page 369.

Preprocessor output

Use the option --preprocess to direct preprocessor output to a named file, see --preprocess, page 242.

To specify a path for an include file, use forward slashes:

```
#include "mydirectory/myfile"
```

In source code, use forward slashes:

```
file = fopen("mydirectory/myfile","rt");
```

Note that backslashes can also be used. In this case, use one in include file paths and two in source code strings.

## **Descriptions of predefined preprocessor symbols**

This table describes the predefined preprocessor symbols:

Predefined symbol	Identifies
AAPCS	An integer that is set based on theaapcs option. The symbol is set to 1 if the AAPCS base standard is the selected calling convention (aapcs=std). The symbol is undefined for other calling conventions.
AAPCS_VFP	An integer that is set based on the $aapcs$ option. The symbol is set to 1 if the VFP variant of AAPCS is the selected calling convention ( $aapcs=vfp$ ). The symbol is undefined for other calling conventions.
ARM_ADVANCED_SIMD	An integer that is set based on the $cpu$ option. The symbol is set to $1$ if the selected processor architecture has the Advanced SIMD architecture extension. The symbol is undefined for other cores.
ARM_MEDIA	An integer that is set based on the $-\text{cpu}$ option. The symbol is set to 1 if the selected processor architecture has the ARMv6 SIMD extensions for multimedia. The symbol is undefined for other cores.
ARM_PROFILE_M	An integer that is set based on the $cpu$ option. The symbol is set to 1 if the selected processor architecture is a profile M core. The symbol is undefined for other cores.
ARMVFP	An integer that reflects thefpu option and is defined toARMVFPV2,ARMVFPV3, orARMVFPV4 These symbolic names can be used when testing theARMVFP symbol. If VFP code generation is disabled (default), the symbol will be undefined.
ARMVFP_D16	An integer that is set based on the $\mathrm{fpu}$ option. The symbol is set to 1 if the selected FPU is a VFPv3 or VFPv4 unit with only 16 D registers. Otherwise, the symbol is undefined.
ARMVFP_FP16	An integer that is set based on the $\mathrm{fpu}$ option. The symbol is set to 1 if the selected FPU only supports 16-bit floating-point numbers. Otherwise, the symbol is undefined.
ARMVFP_SP	An integer that is set based on the $fpu$ option. The symbol is set to 1 if the selected FPU only supports single-precision. Otherwise, the symbol is undefined.

Table 33: Predefined symbols

Predefined symbol	Identifies
BASE_FILEBUILD_NUMBER	A string that identifies the name of the base source file (that is, not the header file), being compiled. See alsoFILE, page 367, and _no_path_in_file_macros, page 236.  A unique integer that identifies the build number of the
	compiler currently in use.
CORE	An integer that identifies the processor architecture in use. The symbol reflects thecpu option and is defined toARM4M,ARM4TM, _ARM5, _ARM5E, _ARM6, _ARM6M, _ARM6SM, _ARM7M, _ARM7EM, _ARM7A, or _ARM7R These symbolic names can be used when testing theCORE symbol.
cplusplus	An integer which is defined when the compiler runs in any of the C++ modes, otherwise it is undefined. When defined, its value is $199711$ L. This symbol can be used with #ifdef to detect whether the compiler accepts C++ code. It is particularly useful when creating header files that are to be shared by C and C++ code.*
CPU_MODE	An integer that reflects the selected CPU mode and is defined to $1$ for Thumb and $2$ for ARM.
DATE	A string that identifies the date of compilation, which is returned in the form "Mmm dd yyyy", for example "Oct 30 2010". $^{*}$
DOUBLE	An integer that identifies the size of the data type double. The symbol is defined to 64.
embedded_cplusplus	An integer which is defined to $1$ when the compiler runs in Embedded C++ or Extended Embedded C++ mode, otherwise the symbol is undefined. This symbol can be used with $\#ifdef$ to detect whether the compiler accepts C++ code. It is particularly useful when creating header files that are to be shared by C and C++ code.*
FILE	A string that identifies the name of the file being compiled, which can be both the base source file and any included header file. See alsoBASE_FILE, page 367, andno_path_in_file_macros, page 236.*

Table 33: Predefined symbols (Continued)

Predefined symbol	Identifies
func	A predefined string identifier that is initialized with the name of the function in which the symbol is used. This is useful for assertions and other trace utilities. The symbol requires that language extensions are enabled, see -e, page 225. See alsoPRETTY_FUNCTION, page 368.*
FUNCTION	A predefined string identifier that is initialized with the name of the function in which the symbol is used. This is useful for assertions and other trace utilities. The symbol requires that language extensions are enabled, see -e, page 225. See alsoPRETTY_FUNCTION, page 368.
IAR_SYSTEMS_ICC	An integer that identifies the IAR compiler platform. The current value is 8. Note that the number could be higher in a future version of the product. This symbol can be tested with #ifdef to detect whether the code was compiled by a compiler from IAR Systems.
ICCARM	An integer that is set to $1$ when the code is compiled with the IAR C/C++ Compiler for ARM.
LINE	An integer that identifies the current source line number of the file being compiled, which can be both the base source file and any included header file.*
LITTLE_ENDIAN	An integer that reflects the $endian$ option and is defined to $1$ when the byte order is little-endian. The symbol is defined to $0$ when the byte order is big-endian.
PRETTY_FUNCTION	A string that identifies the function name, including parameter types and return type, of the function in which the symbol is used, for example "void func(char)". This symbol is useful for assertions and other trace utilities. The symbol requires that language extensions are enabled, see -e, page 225. See alsofunc, page 368.
ROPI	An integer that is defined when theropi compiler option is used; see <i>-ropi</i> , page 244.
RWPI	An integer that is defined when therwpi compiler option is used; see <i>-rwpi</i> , page 245.
STDC	An integer that is set to 1, which means the compiler adheres to Standard C. This symbol can be tested with $\#ifdef$ to detect whether the compiler in use adheres to Standard C.*

Table 33: Predefined symbols (Continued)

Predefined symbol	Identifies
STDC_VERSION	An integer that identifies the version of the C standard in use. The symbol expands to 199901L, unless thec89 compiler option is used in which case the symbol expands to 199409L. This symbol does not apply in EC++ mode.*
TIME	A string that identifies the time of compilation in the form "hh:mm:ss".*
VER	An integer that identifies the version number of the IAR compiler in use. For example, version 5.11.3 is returned as 5011003.

Table 33: Predefined symbols (Continued)

## Descriptions of miscellaneous preprocessor extensions

This section gives reference information about the preprocessor extensions that are available in addition to the predefined symbols, pragma directives, and Standard C directives.

### **NDEBUG**

### Description

This preprocessor symbol determines whether any assert macros you have written in your application shall be included or not in the built application.

If this symbol is not defined, all assert macros are evaluated. If the symbol is defined, all assert macros are excluded from the compilation. In other words, if the symbol is:

- **defined**, the assert code will *not* be included
- not defined, the assert code will be included

This means that if you write any assert code and build your application, you should define this symbol to exclude the assert code from the final application.

Note that the assert macro is defined in the assert.h standard include file.

See also

Assert, page 117.



In the IDE, the NDEBUG symbol is automatically defined if you build your application in the Release build configuration.

<sup>\*</sup> This symbol is required by Standard C.

## #warning message

Syntax #warning message

where message can be any string.

Description Use this preprocessor directive to produce messages. Typically, this is useful for

assertions and other trace utilities, similar to the way the Standard C #error directive is used. This directive is not recognized when the --strict compiler option is used.

# **Library functions**

This chapter gives an introduction to the C and C++ library functions. It also lists the header files used for accessing library definitions.

For detailed reference information about the library functions, see the online help system.

## Library overview

The compiler comes with the IAR DLIB Library, a complete library, compliant with Standard C and C++. This library also supports floating-point numbers in IEEE 754 format and it can be configured to include different levels of support for locale, file descriptors, multibyte characters, et cetera.

Note that different customization methods are normally needed for these two libraries. For more information, see the chapter *The DLIB runtime environment* and *The CLIB runtime environment*, respectively.

For detailed information about the library functions, see the online documentation supplied with the product. There is also keyword reference information for the DLIB library functions. To obtain reference information for a function, select the function name in the editor window and press F1.

For more information about library functions, see the chapter *Implementation-defined behavior* in this guide.

### **HEADER FILES**

Your application program gains access to library definitions through header files, which it incorporates using the #include directive. The definitions are divided into several different header files, each covering a particular functional area, letting you include just those that are required.

It is essential to include the appropriate header file before making any reference to its definitions. Failure to do so can cause the call to fail during execution, or generate error or warning messages at compile time or link time.

### **LIBRARY OBJECT FILES**

Most of the library definitions can be used without modification, that is, directly from the library object files that are supplied with the product. For information about how to set up a runtime library, see *Setting up the runtime environment*, page 90. The linker

will include only those routines that are required—directly or indirectly—by your application.

### **ALTERNATIVE MORE ACCURATE LIBRARY FUNCTIONS**

The default implementation of cos, sin, tan, and pow is designed to be fast and small. As an alternative, there are versions designed to provide better accuracy. They are named \_\_iar\_xxx\_accuratef for float variants of the functions and \_\_iar\_xxx\_accuratel for long double variants of the functions, and where xxx is cos, sin, etc.

To use any of these more accurate versions, use the --redirect linker option.

### REENTRANCY

A function that can be simultaneously invoked in the main application and in any number of interrupts is reentrant. A library function that uses statically allocated data is therefore not reentrant.

Most parts of the DLIB library are reentrant, but the following functions and parts are not reentrant because they need static data:

- Heap functions—malloc, free, realloc, calloc, and the C++ operators new and delete
- Locale functions—localeconv, setlocale
- Multibyte functions—mbrlen, mbrtowc, mbsrtowc, mbtowc, wcrtomb, wcsrtomb, wctomb
- Rand functions—rand, srand
- Time functions—asctime, localtime, gmtime, mktime
- The miscellaneous functions atexit, strerror, strtok
- Functions that use files or the heap in some way. This includes printf, sprintf, scanf, sscanf, getchar, and putchar.

Functions that can set errno are not reentrant, because an errno value resulting from one of these functions can be destroyed by a subsequent use of the function before it is read. This applies to math and string conversion functions, among others.

Remedies for this are:

- Do not use non-reentrant functions in interrupt service routines
- Guard calls to a non-reentrant function by a mutex, or a secure region, etc.

## THE LONGJMP FUNCTION



A longjmp is in effect a jump to a previously defined setjmp. Any variable length arrays or C++ objects residing on the stack during stack unwinding will not be destroyed. This can lead to resource leaks or incorrect application behavior.

## IAR DLIB Library

The IAR DLIB Library provides most of the important C and C++ library definitions that apply to embedded systems. These are of the following types:

- Adherence to a free-standing implementation of Standard C. The library supports
  most of the hosted functionality, but you must implement some of its base
  functionality. For additional information, see the chapter *Implementation-defined*behavior in this guide.
- Standard C library definitions, for user programs.
- C++ library definitions, for user programs.
- CSTARTUP, the module containing the start-up code, see the chapter The DLIB runtime environment in this guide.
- Runtime support libraries; for example low-level floating-point routines.
- Intrinsic functions, allowing low-level use of ARM features. See the chapter Intrinsic functions for more information.

In addition, the IAR DLIB Library includes some added C functionality, see *Added C functionality*, page 377.

### **C HEADER FILES**

This section lists the header files specific to the DLIB library C definitions. Header files may additionally contain target-specific definitions; these are documented in the chapter *Using C*.

This table lists the C header files:

Header file	Usage
assert.h	Enforcing assertions when functions execute
complex.h	Computing common complex mathematical functions
ctype.h	Classifying characters
errno.h	Testing error codes reported by library functions
fenv.h	Floating-point exception flags
float.h	Testing floating-point type properties

Table 34: Traditional Standard C header files—DLIB

Header file	Usage
inttypes.h	Defining formatters for all types defined in stdint.h
iso646.h	Using Amendment I—iso646.h standard header
limits.h	Testing integer type properties
locale.h	Adapting to different cultural conventions
math.h	Computing common mathematical functions
setjmp.h	Executing non-local goto statements
signal.h	Controlling various exceptional conditions
stdarg.h	Accessing a varying number of arguments
stdbool.h	Adds support for the bool data type in C.
stddef.h	Defining several useful types and macros
stdint.h	Providing integer characteristics
stdio.h	Performing input and output
stdlib.h	Performing a variety of operations
string.h	Manipulating several kinds of strings
tgmath.h	Type-generic mathematical functions
time.h	Converting between various time and date formats
uchar.h	Unicode functionality (IAR extension to Standard C)
wchar.h	Support for wide characters
wctype.h	Classifying wide characters

Table 34: Traditional Standard C header files—DLIB (Continued)

### C++ HEADER FILES

This section lists the C++ header files.

### C++ and Embedded C++

This table lists the header files that can be used in C++ as well as in Embedded C++:

Header file	Usage
complex	Defining a class that supports complex arithmetic
exception	Defining several functions that control exception handling; only usable in $C++$
fstream	Defining several I/O stream classes that manipulate external files
iomanip	Declaring several I/O stream manipulators that take an argument
ios	Defining the class that serves as the base for many I/O streams classes

Table 35: Embedded C++ header files

Header file	Usage
iosfwd	Declaring several I/O stream classes before they are necessarily defined
iostream	Declaring the I/O stream objects that manipulate the standard streams
istream	Defining the class that performs extractions
limits	Defining numerical values; only usable in C++
locale	Adapting to different cultural conventions; only usable in C++
new	Declaring several functions that allocate and free storage
ostream	Defining the class that performs insertions
sstream	Defining several I/O stream classes that manipulate string containers
stdexcept	Defining several classes useful for reporting exceptions; only usable in C++
streambuf	Defining classes that buffer I/O stream operations
string	Defining a class that implements a string container
strstream	Defining several I/O stream classes that manipulate in-memory character
	sequences
typeinfo	Defining type information support; only usable in C++

Table 35: Embedded C++ header files (Continued)

## C++ standard template library

The following table lists the standard template library (STL) header files that can be used in C++ as well as in Extended Embedded C++:

Header file	Description
algorithm	Defines several common operations on sequences
bitset	Defining a container with fixed-sized sequences of bits; only usable in $C\text{++}$
deque	A deque sequence container
functional	Defines several function objects
hash_map	A map associative container, based on a hash algorithm
hash_set	A set associative container, based on a hash algorithm
iterator	Defines common iterators, and operations on iterators
list	A doubly-linked list sequence container
map	A map associative container
memory	Defines facilities for managing memory
numeric	Performs generalized numeric operations on sequences
queue	A queue sequence container

Table 36: Standard template library header files

Header file	Description
set	A set associative container
slist	A singly-linked list sequence container
stack	A stack sequence container
utility	Defines several utility components
valarray	Defining varying length array container; only usable in C++
vector	A vector sequence container

Table 36: Standard template library header files (Continued)

## Using Standard C libraries in C++

The C++ library works in conjunction with some of the header files from the Standard C library, sometimes with small alterations. The header files come in two forms—new and traditional—for example, cassert and assert.h.

This table shows the new header files:

Header file	Usage
cassert	Enforcing assertions when functions execute
ccomplex	Computing common complex mathematical functions
cctype	Classifying characters
cerrno	Testing error codes reported by library functions
cfenv	Floating-point exception flags
cfloat	Testing floating-point type properties
cinttypes	Defining formatters for all types defined in stdint.h
ciso646	Using Amendment I—iso646.h standard header
climits	Testing integer type properties
clocale	Adapting to different cultural conventions
cmath	Computing common mathematical functions
csetjmp	Executing non-local goto statements
csignal	Controlling various exceptional conditions
cstdarg	Accessing a varying number of arguments
cstdbool	Adds support for the bool data type in C.
cstddef	Defining several useful types and macros
cstdint	Providing integer characteristics
cstdio	Performing input and output

Table 37: New Standard C header files—DLIB

Header file	Usage
cstdlib	Performing a variety of operations
cstring	Manipulating several kinds of strings
ctgmath	Type-generic mathematical functions
ctime	Converting between various time and date formats
cwchar	Support for wide characters
cwctype	Classifying wide characters

Table 37: New Standard C header files—DLIB (Continued)

### LIBRARY FUNCTIONS AS INTRINSIC FUNCTIONS

Certain C library functions will under some circumstances be handled as intrinsic functions and will generate inline code instead of an ordinary function call, for example memcpy, memset, and strcat.

### ADDED C FUNCTIONALITY

The IAR DLIB Library includes some added C functionality.

The following include files provide these features:

- fenv.h
- stdio.h
- stdlib.h
- string.h
- time.h

### fenv.h

In fenv.h, trap handling support for floating-point numbers is defined with the functions fegettrapenable and fegettrapdisable.

### stdio.h

These functions provide additional I/O functionality:

fdopen	Opens a file based on a low-level file descriptor.	
fileno	Gets the low-level file descriptor from the file descriptor ( $\mathtt{FILE}^*$ ).	
gets	Corresponds to fgets on stdin.	
aetw	Gets a wchar t character from stdin.	

putw	Puts a wchar_t character to stdout.  Corresponds to ungetc on stdout.	
ungetchar		
write_array	Corresponds to fwrite on stdout.	

### string.h

These are the additional functions defined in string.h:

strdup	Duplicates a string on the heap.	
strcasecmp	Compares strings case-insensitive.	
strncasecmp	Compares strings case-insensitive and bounded.	

strnlen Bounded string length.

### time.h

There are two interfaces for using time\_t and the associated functions time, ctime, difftime, qmtime, localtime, and mktime:

- The 32-bit interface supports years from 1900 up to 2035 and uses a 32-bit integer
  for time\_t. The type and function have names like \_\_time32\_t, \_\_time32, etc.
  This variant is mainly available for backwards compatibility.
- The 64-bit interface supports years from -9999 up to 9999 and uses a signed long long for time\_t. The type and function have names like \_\_time64\_t, \_\_time64, etc.

The interfaces are defined in the system header file time.h.

An application can use either interface, and even mix them by explicitly using the 32-or 64-bit variants. By default, the library and the header redirect time\_t, time etc. to the 32-bit variants. However, to explicitly redirect them to their 64-bit variants, define \_DLIB\_TIME\_USES\_64 in front of the inclusion of time.h or ctime.

See also, Time, page 116.

### SYMBOLS USED INTERNALLY BY THE LIBRARY

The following symbols are used by the library, which means that they are visible in library source files, etc:

```
__assignment_by_bitwise_copy_allowed
```

This symbol determines properties for class objects.

code.	data

These symbols are used as memory attributes internally by the compiler, and they might have to be used as arguments in certain templates.

```
__constrange()
```

Determines the allowed range for a parameter to an intrinsic function and that the parameter must be of type const.

```
__construction_by_bitwise_copy_allowed
```

This symbol determines properties for class objects.

```
__has_constructor, __has_destructor
```

These symbols determine properties for class objects and they function like the sizeof operator. The symbols are true when a class, base class, or member (recursively) has a user-defined constructor or destructor, respectively.

```
__memory_of
```

Determines the class memory. A class memory determines which memory a class object can reside in. This symbol can only occur in class definitions as a class memory.

**Note:** The symbols are reserved and should only be used by the library.

Use the compiler option --predef\_macros to determine the value for any predefined symbols.

# The linker configuration file

This chapter describes the purpose of the linker configuration file and describes its contents.

To read this chapter you must be familiar with the concept of sections, see *Modules and sections*, page 68.

## **Overview**

To link and locate an application in memory according to your requirements, ILINK needs information about how to handle sections and how to place them into the available memory regions. In other words, ILINK needs a *configuration*, passed to it by means of the *linker configuration file*.

This file consists of a sequence of directives and typically, provides facilities for:

- Defining available addressable memories
  giving the linker information about the maximum size of possible addresses and
  defining the available physical memory, as well as dealing with memories that can be
  addressed in different ways.
- Defining the regions of the available memories that are populated with ROM or RAM
  - giving the start and end address for each region.
- Section groups
   dealing with how to group sections into blocks and overlays depending on the section
   requirements.
- Defining how to handle initialization of the application giving information about which sections that are to be initialized, and how that initialization should be made.
- Memory allocation defining where—in what memory region—each set of sections should be placed.
- Using symbols, expressions, and numbers
   expressing addresses and sizes, etc, in the other configuration directives. The
   symbols can also be used in the application itself.

### • Structural configuration

meaning that you can include or exclude directives depending on a condition, and to split the configuration file into several different files.

Comments can be written either as C comments (/\*...\*/) or as C++ comments (//...).

## **Defining memories and regions**

ILINK needs information about the available memory spaces, or more specifically it needs information about:

• The maximum size of possible addressable memories

The define memory directive defines a *memory space* with a given size, which is the maximum possible amount of addressable memory, not necessarily physically available. See *Define memory directive*, page 382.

• Available physical memory

The define region directive defines a region in the available memories in which specific sections of application code and sections of application data can be placed. See *Define region directive*, page 383.

A region consists of one or several memory ranges. A range is a continuous sequence of bytes in a memory and several ranges can be expressed by using region expressions. See *Region expression*, page 385.

## **Define memory directive**

Syntax	define memory \[ \ name \] with size = size_expr \[ \] , unit-size \[ \];
	where unit-size is one of:
	unitbitsize = bitsize_expr unitbytesize = bytesize_expr
	and where expr is an expression, see Expressions, page 399.

**Parameters** 

size\_expr Specifies how many units the memory space contains;

always counted from address zero.

bitsize\_expr Specifies how many bits each unit contains.

bytesize\_expr Specifies how many bytes each unit contains. Each byte

contains 8 bits.

Description

The define memory directive defines a *memory space* with a given size, which is the maximum possible amount of addressable memory, not necessarily physically available. This sets the limits for the possible addresses to be used in the linker configuration file. For many microcontrollers, one memory space is sufficient. However, some microcontrollers require two or more. For example, a Harvard architecture usually requires two different memory spaces, one for code and one for data. If only one memory is defined, the memory name is optional. If no *unit-size* is given, the unit

contains 8 bits.

Example

```
/* Declare the memory space Mem of four Gigabytes */
define memory Mem with size = 4G;
```

## **Define region directive**

Syntax define region name = region-expr;

where region-expr is a region expression, see also Regions, page 383.

**Parameters** 

name

The name of the region.

Description

The define region directive defines a region in which specific sections of code and sections of data can be placed. A region consists of one or several memory ranges, where each memory range consists of a continuous sequence of bytes in a specific memory. Several ranges can be combined by using region expressions. Note that those ranges do

not need to be consecutive or even in the same memory.

Example

```
/* Define the 0x10000-byte code region ROM located at address 0x10000 in memory Mem */ define region ROM = Mem:[from 0x10000 size 0x10000];
```

## **Regions**

A *region* is s a set of non-overlapping memory ranges. A *region expression* is built up out of *region literals* and set operations (union, intersection, and difference) on regions.

## Region literal

```
Syntax [ memory-name: ][from expr { to expr | size expr }

[ repeat expr [ displacement expr ]]]
```

where expr is an expression, see Expressions, page 399.

### **Parameters**

memory-name

The name of the memory space in which the region literal will be

located. If there is only one memory, the name is optional.

from expr expr is the start address of the memory range (inclusive).

to expr is the end address of the memory range (inclusive).

size expr expr is the size of the memory range.

repeat expr expr defines several ranges in the same memory for the region

literal.

displacement expr is the displacement from the previous range start in the

repeat sequence. Default displacement is the same value as the

range size.

### Description

A region literal consists of one memory range. When you define a range, the memory it resides in, a start address, and a size must be specified. The range size can be stated explicitly by specifying a size, or implicitly by specifying the final address of the range. The final address is included in the range and a zero-sized range will only contain an address. A range can span over the address zero and such a range can even be expressed by unsigned values, because it is known where the memory wraps.

The repeat parameter will create a region literal that contains several ranges, one for each repeat. This is useful for *banked* or *far* regions.

### Example

```
/* The 5-byte size range spans over the address zero */
Mem:[from -2 to 2]

/* The 512-byte size range spans over zero, in a 64-Kbyte memory
*/
Mem:[from 0xFF00 to 0xFF]

/* Defining several ranges in the same memory, a repeating
    literal */
Mem:[from 0 size 0x100 repeat 3 displacement 0x1000]

/* Resulting in a region containing:
    Mem:[from 0 size 0x100]
    Mem:[from 0x1000 size 0x100]
    Mem:[from 0x2000 size 0x100]
*/
```

See also

Define region directive, page 383, and Region expression, page 385.

## Region expression

Syntax

```
region-operand
| region-expr | region-operand
| region-expr - region-operand
| region-expr & region-operand
```

where region-operand is one of:

```
( region-expr )
region-name
region-literal
empty-region
```

where region-name is a region, see Define region directive, page 383

where region-literal is a region literal, see Region literal, page 383

and where empty-region is an empty region, see Empty region, page 386.

### Description

Normally, a region consists of one memory range, which means a *region literal* is sufficient to express it. When a region contains several ranges, possibly in different memories, it is instead necessary to use a *region expression* to express it. Region expressions are actually set expressions on sets of memory ranges.

To create region expressions, three operators are available: union (|), intersection (&), and difference (-). These operators work as in *set theory*. For example, if you have the sets A and B, then the result of the operators would be:

- A | B: all elements in either set A or set B
- A & B: all elements in both set A and B
- A B: all elements in set A but not in B.

### Example

```
/* Resulting in a range starting at 1000 and ending at 2FFF, in
   memory Mem */
Mem:[from 0x1000 to 0x1FFF] | Mem:[from 0x1500 to 0x2FFF]

/* Resulting in a range starting at 1500 and ending at 1FFF, in
   memory Mem */
Mem:[from 0x1000 to 0x1FFF] & Mem:[from 0x1500 to 0x2FFF]

/* Resulting in a range starting at 1000 and ending at 14FF, in
   memory Mem */
Mem:[from 0x1000 to 0x1FFF] - Mem:[from 0x1500 to 0x2FFF]
```

```
/* Resulting in two ranges. The first starting at 1000 and ending
   at 1FFF, the second starting at 2501 and ending at 2FFF.
   Both located in memory Mem */
Mem:[from 0x1000 to 0x2FFF] - Mem:[from 0x2000 to 0x24FF]
```

## **Empty region**

Syntax [ ]

Description

The empty region does not contain any memory ranges. If the empty region is used in a placement directive that actually is used for placing one or more sections, ILINK will issue an error.

Example

```
define region Code = Mem:[from 0 size 0x10000];
if (Banked) {
  define region Bank = Mem:[from 0x8000 size 0x1000];
} else {
  define region Bank = [];
}
define region NonBanked = Code - Bank;
```

/\* Depending on the Banked symbol, the NonBanked region is either one range with 0x10000 bytes, or two ranges with 0x8000 and 0x7000 bytes, respectively. \*/

See also

Region expression, page 385.

## **Section handling**

Section handling describes how ILINK should handle the sections of the execution image, which means:

Placing sections in regions

The place at and place into directives place sets of sections with similar attributes into previously defined regions. See *Place at directive*, page 393 and *Place in directive*, page 394.

• Making sets of sections with special requirements

The block directive makes it possible to create empty sections with specific sizes and alignments, sequentially sorted sections of different types, etc.

The overlay directive makes it possible to create an area of memory that can contain several overlay images. See *Define block directive*, page 387, and *Define overlay directive*, page 388.

### • Initializing the application

The directives initialize and do not initialize control how the application should be started. With these directives, the application can initialize global symbols at startup, and copy pieces of code. The initializers can be stored in several ways, for example they can be compressed. See *Initialize directive*, page 390 and *Do not initialize directive*, page 392.

### • Keeping removed sections

The keep directive retains sections even though they are not referred to by the rest of the application, which means it is equivalent to the *root* concept in the assembler and compiler. See *Keep directive*, page 392.

### **Define block directive**

Syntax

```
define [movable] block name
  [ with param, param... ]
{
   extended-selectors
}
[except
  {
   section_selectors
}];
```

where param can be one of:

```
size = expr
maximum size = expr
alignment = expr
fixed order
static base [name]
static base
```

and where the rest of the directive selects sections to include in the block, see *Section selection*, page 394.

### **Parameters**

name	The name of the block to be defined.
size	Customizes the size of the block. By default, the size of a block is the sum of its parts dependent of its contents.
maximum size	Specifies an upper limit for the size of the block. An error is generated if the sections in the block do not fit.

alignment Specifies a minimum alignment for the block. If any section in the

block has a higher alignment than the minimum alignment, the

block will have that alignment.

fixed order Places sections in fixed order; if not specified, the order of the

sections will be arbitrary.

static base name Specifies that the static base with the specified name will be at the

start of the block when the application executes.

static base Specifies that the static base will be at the start of the block when

the application executes.

### Description

The block directive defines a named set of sections. By defining a block you can create empty blocks of bytes that can be used, for example as stacks or heaps. Another use for the directive is to group certain types of sections, consecutive or non-consecutive. A third example of use for the directive is to group sections into one memory area to access the start and end of that area from the application.

movable blocks are for use with read-only and read-write position independence. Making blocks movable enables the linker to validate the application's use of addresses. Movable blocks are located in exactly the same way as other blocks, but the linker will check that the appropriate relocations are used when referring to symbols in movable blocks.

```
Example /* Create a 0x1000-byte block for the heap */
```

define block HEAP with size = 0x1000, alignment = 8 { };

See also

Interaction between the tools and your application, page 168. See Define overlay directive, page 388 for an Accessing example.

## Define overlay directive

Syntax

```
define overlay name [ with param, param... ]
{
   extended-selectors;
}
[except
   {
   section_selectors
   }1:
```

For information about extended selectors and except clauses, see *Section selection*, page 394.

### **Parameters**

name	The name of the overlay.
size	Customizes the size of the overlay. By default, the size of a overlay is the sum of its parts dependent of its contents. $ \\$
maximum size	Specifies an upper limit for the size of the overlay. An error is generated if the sections in the overlay do not fit.
alignment	Specifies a minimum alignment for the overlay. If any section in the overlay has a higher alignment than the minimum alignment, the overlay will have that alignment.
fixed order	Places sections in fixed order; if not specified, the order of the sections will be arbitrary.

### Description

The overlay directive defines a named set of sections. In contrast to the block directive, the overlay directive can define the same name several times. Each definition will then be grouped in memory at the same place as all other definitions of the same name. This creates an *overlaid* memory area, which can be useful for an application that has several independent sub-applications.

Place each sub-application image in ROM and reserve a RAM overlay area that can hold all sub-applications. To execute a sub-application, first copy it from ROM to the RAM overlay. Note that ILINK does not help you with managing interdependent overlay definitions, apart from generating a diagnostic message for any reference from one overlay to another overlay.

The size of an overlay will be the same size as the largest definition of that overlay name and the alignment requirements will be the same as for the definition with the highest alignment requirements.

**Note:** Sections that were overlaid must be split into a RAM and a ROM part and you must take care of all the copying needed.

See also

Manual initialization, page 82.

### Initialize directive

Syntax

```
initialize { by copy | manually }
  [ with param, param... ]
{
   section-selectors
}
[except
{
   section_selectors
}];
where param is one of:
packing = { none | zeros | packbits | bwt | lzw | auto |
   smallest }
```

and where the rest of the directive selects sections to include in the block. See *Section selection*, page 394.

### **Parameters**

by copy

Splits the section into sections for initializers and initialized data, and handles the initialization at application startup automatically.

Splits the section into sections for initializers and initialized data.

The initialization at application startup is not handled automatically.

packing Specifies how to handle the initializers. Choose between:

none - Disables compression of the selected section contents.

none – Disables compression of the selected section contents

This is the default method for initialize manually.

zeros - Compresses sequential bytes with the value zero.
packbits - Compresses with the PackBits algorithm. This
method generates good results for data with many consecutive
bytes of the same value.

bwt - Compresses with the Burrows-Wheeler algorithm. This method improves the packbits method by transforming blocks of data before they are compressed.

1zw - Compresses with the Lempel-Ziv-Welch algorithm. This method uses a dictionary to store byte patterns in the data.
auto - Similar to smallest, but ILINK chooses between none and packbits. This is the default method for initialize by copy.

smallest - ILINK estimates the resulting size using each packing method (except for auto), and then chooses the packing method that produces the smallest estimated size. Note that the size of the decompressor is also included.

### Description

The initialize directive splits the initialization section into one section holding the initializers and another section holding the initialized data. You can choose whether the initialization at startup should be handled automatically (initialize by copy) or whether you should handle it yourself (initialize manually).

When you use the packing method auto (default for initialize by copy) or smallest, ILINK will automatically choose an appropriate packing algorithm for the initializers. To override this, specify a different packing method. The --log initialization option shows how ILINK decided which packing algorithm to use.

When initializers are compressed, a decompressor is automatically added to the image. The decompressors for bwt and lzw use significantly more execution time and RAM than zeros and packbits. Approximately 9 Kbytes of stack space is needed for bwt and 3.5 Kbytes for lzw.

When initializers are compressed, the exact size of the compressed initializers is unknown until the exact content of the uncompressed data is known. If this data contains other addresses, and some of these addresses are dependent on the size of the compressed initializers, the linker fails with error Lp017. To avoid this, place compressed initializers last, or in a memory region together with sections whose addresses do not need to be known.

Unless initialize manually is used, ILINK will arrange for initialization to occur during system startup by including an initialization table. Startup code calls an initialization routine that reads this table and performs the necessary initializations.

Zero-initialized sections are not affected by the initialize directive.

The initialize directive is normally used for initialized variables, but can be used for copying any sections, for example copying executable code from slow ROM to fast RAM, or for overlays. For another example, see *Define overlay directive*, page 388.

Sections that are needed for initialization are not affected by the initialize by copy directive. This includes the \_\_low\_level\_init function and anything it references.

Anything reachable from the program entry label is considered *needed for initialization* unless reached via a section fragment with a label starting with \_\_iar\_init\$\$done. The --log sections option, in addition to logging the marking of section fragments to be included in the application, also logs the process of determining which sections are needed for initialization.

### Example

```
/* Copy all read-write sections automatically from ROM to RAM at
   program start */
initialize by copy { rw };
place in RAM { rw };
place in ROM { ro };
```

See also

*Initialization at system startup*, page 73, and *Do not initialize directive*, page 392.

### Do not initialize directive

For information about extended selectors and except clauses, see *Section selection*, page 394.

Description

The do not initialize directive specifies the sections that should not be initialized by the system startup code. The directive can only be used on zeroinit sections.

The compiler keyword \_\_no\_init places variables into sections that must be handled by a do not initialize directive.

Example

```
/* Do not initialize read-write sections whose name ends with
   _noinit at program start */
do not initialize { rw section .*_noinit };
place in RAM { rw section .*_noinit };
```

See also

Initialization at system startup, page 73, and Initialize directive, page 390.

## **Keep directive**

**Syntax** 

```
keep
{
   section-selectors
}
[except
   {
   section-selectors
}];
```

For information about extended selectors and except clauses, see *Section selection*, page 394.

Description

The keep directive specifies that all selected sections should be kept in the executable image, even if there are no references to the sections.

Example

keep { section .keep\* } except {section .keep};

### Place at directive

Syntax

For information about extended selectors and except clauses, see *Section selection*, page 394.

### **Parameters**

memory: expr

A specific address in a specific memory. The address must be available in the supplied memory defined by the define memory directive. The memory specifier is optional if there is only one memory.

start of region\_expr A region expression. The start of the region is used.
end of region\_expr A region expression. The end of the region is used.

### Description

The place at directive places sections and blocks either at a specific address or, at the beginning or the end of a region. The same address cannot be used for two different place at directives. It is also not possible to use an empty region in a place at directive. If placed in a region, the sections and blocks will be placed before any other sections or blocks placed in the same region with a place in directive.

The sections and blocks will be placed in the region in an arbitrary order. To specify a specific order, use the block directive.

The name, if specified, is used in the map file and in some log messages.

Example /\* Place the read-only section .startup at the beginning of the code\_region \*/

"START": place at start of ROM { readonly section .startup };

See also *Place in directive*, page 394.

### Place in directive

**Syntax** 

```
[ "name": ]
place in region-expr
{
   extended-selectors
}
[except{
   section-selectors
}];
```

where region-expr is a region expression, see also Regions, page 383.

and where the rest of the directive selects sections to include in the block. See *Section selection*, page 394.

Description

The place in directive places sections and blocks in a specific region. The sections and blocks will be placed in the region in an arbitrary order.

To specify a specific order, use the block directive. The region can have several ranges.

The name, if specified, is used in the map file and in some log messages.

Example

/\* Place the read-only sections in the code\_region \*/
"ROM": place in ROM { readonly };

See also

Place at directive, page 393.

## Section selection

The purpose of *section selection* is to specify—by means of *section selectors* and *except clauses*—the sections that an ILINK directive should be applied to. All sections that match one or more of the section selectors will be selected, and none of the sections selectors in the except clause, if any. Each section selector can match sections on section attributes, section name, and object or library name.

Some directives provide functionality that requires more detailed selection capabilities, for example directives that can be applied on both sections and blocks. In this case, the *extended-selectors* are used.

### **Section-selectors**

{ [ section-selector ][, section-selector...] } Syntax where section-selector is: [ section-attribute ] [ section-type ] [ section sectionname ] [object {module | filename}] where section-attribute is: [ ro [ code | data ] | rw [ code | data ] | zi ] and where ro, rw, and zi also can be readonly, readwrite, and zeroinit, respectively. And section-type is: [ preinit\_array | init\_array ] **Parameters** ro or readonly Read-only sections. rw or readwrite Read/write sections. zi or zeroinit Zero-initialized sections. These sections have no content and should possibly be initialized with zeros during system startup. code Sections that contain code. data Sections that contain data. preinit array Sections of the ELF section type SHT PREINIT ARRAY. Sections of the ELF section type SHT\_INIT\_ARRAY. init\_array sectionname The section name. Two wildcards are allowed: ? matches any single character \* matches zero or more characters. module A name in the form objectname(libraryname). Sections from object modules where both the object name and the library name match their respective patterns are selected. An empty library name pattern selects only sections from object files. filename The name of an object file, a library, or an object in a library. Two wildcards are allowed: ? matches any single character \* matches zero or more characters.

Description

A section selector selects all sections that match the section attribute, section type, section name, and the name of the *object*, where *object* is an object file, a library, or an

object in a library. Up to three of the four conditions can be omitted. If the section attribute is omitted, any section will be selected, without restrictions on the section attribute. If the section type is omitted, sections of any type will be selected.

If the section name part or the object name part is omitted, sections will be selected without restrictions on the section name or object name, respectively.

It is also possible to use only  $\{\ \}$  without any section selectors, which can be useful when defining blocks.

Note that a section selector with narrower scope has higher priority than a more generic section selector.

If more than one section selector matches for the same purpose, one of them must be more specific. A section selector is more specific than another one if:

- It specifies a section type and the other one does not
- It specifies a section name or object name with no wildcards and the other one does not
- There could be sections that match the other selector that also match this one, and the reverse is not true.

Selector I	Selector 2	More specific
section "foo*"	section "f*"	Selector 1
section "*x"	section "f*"	Neither
ro code section "f*"	ro section "f*"	Selector 1
init_array	ro section "xx"	Selector 1
section ".intvec"	ro section ".int*"	Selector 1
section ".intvec"	object "foo.o"	Neither

Table 38: Examples of section selector specifications

### Example

```
{ rw } /* Selects all read-write sections */
{ section .mydata* } /* Selects only .mydata* sections */
/* Selects .mydata* sections available in the object special.o */
{ section .mydata* object special.o }
```

Assuming a section in an object named foo.o in a library named lib.a, any of these selectors will select that section:

```
object foo.o(lib.a)
object f*(lib*)
object foo.o
object lib.a
```

See also

*Initialize directive*, page 390, *Do not initialize directive*, page 392, and *Keep directive*, page 392.

#### **Extended-selectors**

```
{ [ extended-selector ][, extended-selector...] }
Syntax
                         where extended-selector is:
                           [ first | last ] { section-selector |
                                                 block name [ inline-block-def ] |
                                                 overlay name }
                         where inline-block-def is:
                           [ block-params ] extended-selectors
Parameters
                         first
                                                 Places the selected name first in the region, block, or overlay.
                         last
                                                 Places the selected name last in the region, block, or overlay.
                         block
                                                 The name of the block.
                                                 The name of the overlay.
                         overlay
Description
                         In addition to what the section-selector does, extended-selector provides
                         functionality for placing blocks or overlays first or last in a set of sections, a block, or
                         an overlay. It is also possible to create an inline definition of a block. This means that
                         you can get more precise control over section placement.
Example
                         define block First { section .first }; /* Define a block holding
                                                                            the section .first */
                         define block Table { first block First }; /* Define a block where
                                                                                the block First is
                                                                                placed first */
                         or, equivalently using an inline definition of the block First:
                         define block Table { first block First { section .first }};
See also
                         Define block directive, page 387, Define overlay directive, page 388, and Place at
```

directive, page 393.

# Using symbols, expressions, and numbers

In the linker configuration file, you can also:

• Define and export symbols

The define symbol directive defines a symbol with a specified value that can be used in expressions in the configuration file. The symbol can also be exported to be used by the application or the debugger. See *Define symbol directive*, page 398, and *Export directive*, page 399.

• Use expressions and numbers

In the linker configuration file, expressions and numbers are used for specifying addresses, sizes, etc. See *Expressions*, page 399.

# **Define symbol directive**

Syntax define [ exported ] symbol name = expr;

**Parameters** 

exported Exports the symbol to be usable by the executable image.

name The name of the symbol.

expr The symbol value.

Description

The define symbol directive defines a symbol with a specified value. The symbol can then be used in expressions in the configuration file. The symbols defined in this way work exactly like the symbols defined with the option --config\_def outside of the configuration file.

The define exported symbol variant of this directive is a shortcut for using the directive define symbol in combination with the export symbol directive. On the command line this would require both a --config\_def option and a --define\_symbol option to achieve the same effect.

#### Note:

- A symbol cannot be redefined
- Symbols that are either prefixed by \_x, where x is a capital letter, or that contain \_\_ (double underscore) are reserved for toolset vendors.

Example /\* Define the symbol my\_symbol with the value 4 \*/
define symbol my\_symbol = 4;

See also Export directive, page 399 and Interaction between ILINK and the application, page 85.

# **Export directive**

Syntax export symbol name;

**Parameters** 

name

The name of the symbol.

Description The export directive defines a symbol to be exported, so that it can be used both from

the executable image and from a global label. The application, or the debugger, can then

refer to it for setup purposes etc.

Example /\* Define the symbol my\_symbol to be exported \*/

export symbol my\_symbol;

# **Expressions**

Syntax

An expression is built up of the following constituents:

expression binop expression

unop expression

expression ? expression : expression

(expression) number

symbol

func-operator

where binop is one of these binary operators:

+, -, \*, /, %, <<, >>, <, >, ==, !=, &, ^, |, &&, | |

where unop is one of this unary operators:

+, -, !, ~

where number is a number, see Numbers, page 400

where symbol is a defined symbol, see Define symbol directive, page 398 and

--config\_def, page 255

and where func-operator is one of these function-like operators:

minimum (expr, expr) Returns the smallest of the two parameters.

maximum (expr, expr) Returns the largest of the two parameters.

isempty (r) Returns True if the region is empty, otherwise False.

```
is defined symbol (expr-symbol Returns True if the expression symbol is defined, otherwise False.

start (r) Returns the lowest address in the region.

end (r) Returns the highest address in the region.

size (r) Returns the size of the complete region.
```

where expr is an expression, and r is a region expression, see *Region expression*, page 385.

## Description

In the linker configuration file, an expression is a 65-bit value with the range -2^64 to 2^64. The expression syntax closely follows C syntax with some minor exceptions. There are no assignments, casts, pre- or post-operations, and no address operations (\*, &, [], ->, and .). Some operations that extract a value from a region expression, etc, use a syntax resembling that of a function call. A boolean expression returns 0 (False) or 1 (True).

## **Numbers**

Syntax nr [nr-suffix]

where nr is either a decimal number or a hexadecimal number  $(0 \times ...)$ .

and where nr-suffix is one of:

Description

A number can be expressed either by normal C means or by suffixing it with a set of useful suffixes, which provides a compact way of specifying numbers.

Example

1024 is the same as  $0 \times 400$ , which is the same as 1K.

# Structural configuration

The structural directives provide means for creating structure within the configuration, such as:

Conditional inclusion

An if directive includes or excludes other directives depending on a condition, which makes it possible to have directives for several different memory configurations in the same file. See *If directive*, page 401.

Dividing the linker configuration file into several different files
 The include directive makes it possible to divide the configuration file into several logically distinct files. See *Include directive*, page 402.

### If directive

Syntax

```
if (expr) {
    directives
[ } else if (expr) {
    directives ]
[ } else {
    directives ]
}
```

where expr is an expression, see Expressions, page 399.

**Parameters** 

directives

Any ILINK directive.

Description

An if directive includes or excludes other directives depending on a condition, which makes it possible to have directives for several different memory configurations, for example both a banked and non-banked memory configuration, in the same file.

The directives inside an if part, else if part, or an else part are syntax checked and processed regardless of whether the conditional expression was true or false, but only the directives in the part where the conditional expression was true, or the else part if none of the conditions were true, will have any effect outside the if directive. The if directives can be nested.

Example

See *Empty region*, page 386.

# Include directive

Syntax include filename;

**Parameters** 

filename A string literal where both / and \ can be used as the directory

delimiter.

Description The include directive makes it possible to divide the configuration file into several

logically distinct parts, each in a separate file. For instance, there might be parts that you

need to change often and parts that you seldom edit.

# **Section reference**

The compiler places code and data into sections. Based on a configuration specified in the linker configuration file, ILINK places sections in memory.

This chapter lists all predefined ELF sections and blocks that are available for the IAR build tools for ARM, and gives detailed reference information about each section.

For more information about sections, see the chapter *Modules and sections*, page 68.

# **Summary of sections**

This table lists the ELF sections and blocks that are used by the IAR build tools:

Section	Description
.bss	Holds zero-initialized static and global variables.
CSTACK	Holds the stack used by C or C++ programs.
.cstart	Holds the startup code.
.data	Holds static and global initialized variables.
.data_init	Holds initial values for . data sections when the linker directive initialize by copy is used.
DLIB_PERTHREAD	Holds variables that contain static states for DLIB modules.
.exc.text	Holds exception-related code.
HEAP	Holds the heap used for dynamically allocated data.
.iar.dynexit	Holds the atexit table.
.init_array	Holds a table of dynamic initialization functions.
.intvec	Holds the reset vector table
IRQ_STACK	Holds the stack for interrupt requests, IRQ, and exceptions.
.noinit	Holdsno_init static and global variables.
.preinit_array	Holds a table of dynamic initialization functions.
.prepreinit_array	Holds a table of dynamic initialization functions.
.rodata	Holds constant data.

Table 39: Section summary

Section	Description
.text	Holds the program code.
.textrw	Holdsramfunc declared program code.
.textrw_init	Holds initializers for the .textrw declared section.

Table 39: Section summary (Continued)

In addition to the ELF sections used for your application, the tools use a number of other ELF sections for a variety of purposes:

- Sections starting with .debug generally contain debug information in the DWARF format
- Sections starting with .iar.debug contain supplemental debug information in an IAR format
- The section .comment contains the tools and command lines used for building the file
- Sections starting with .rel or .rela contain ELF relocation information
- The section .symtab contains the symbol table for a file
- The section .strtab contains the names of the symbol in the symbol table
- The section . shstrtab contains the names of the sections.

# **Descriptions of sections and blocks**

This section gives reference information about each section, where the:

- Description describes what type of content the section is holding and, where required, how the section is treated by the linker
- Memory placement describes memory placement restrictions.

For information about how to allocate sections in memory by modifying the linker configuration file, see the *Placing code and data—the linker configuration file*, page 71.

#### .bss

Description Holds zero-initialized static and global variables.

Memory placement This section can be placed anywhere in memory.

## **CSTACK**

Description Block that holds the internal data stack.

Memory placement This block can be placed anywhere in memory.

See also Setting up the stack, page 81.

#### .cstart

Description Holds the startup code.

Memory placement This section can be placed anywhere in memory.

# .data

Description Holds static and global initialized variables. In object files, this includes the initial

values. When the linker directive initialize by copy is used, a corresponding .data\_init section is created for each .data section, holding the possibly

compressed initial values.

Memory placement This section can be placed anywhere in memory.

# .data init

Description Holds the possibly compressed initial values for .data sections. This section is created

by the linker if the initialize by copy linker directive is used.

Memory placement This section can be placed anywhere in memory.

# DLIB PERTHREAD

Description Holds variables that contain static states for DLIB modules.

Memory placement This section is automatically placed correctly; you must not change its placement.

See also *Multithread support in the DLIB library*, page 118.

#### .exc.text

Description Holds code that is only executed when your application handles an exception.

Memory placement In the same memory as .text.

See also *Exception handling*, page 156.

## **HEAP**

Description Holds the heap used for dynamically allocated data, in other words data allocated by

malloc and free, and in C++, new and delete.

Memory placement This section can be placed anywhere in memory.

See also Setting up the heap, page 82.

# .iar.dynexit

Description Holds the table of calls to be made at exit.

Memory placement This section can be placed anywhere in memory.

See also Setting up the atexit limit, page 82.

# .init\_array

Description Holds pointers to routines to call for initializing one or more C++ objects with static

storage duration.

Memory placement This section can be placed anywhere in memory.

#### .intvec

Description Holds the reset vector and exception vectors which contain branch instructions to

cstartup, interrupt service routines etc.

Memory placement Must be placed at address range 0x00 to 0x3F.

# IRQ\_STACK

Description Holds the stack which is used when servicing IRQ exceptions. Other stacks may be

added as needed for servicing other exception types: FIQ, SVC, ABT, and UND. The cstartup.s file must be modified to initialize the exception stack pointers used.

Note: This section is not used when compiling for Cortex-M.

Memory placement This section can be placed anywhere in memory.

See also *Exception stacks*, page 166.

# .noinit

Description Holds static and global \_\_no\_init variables.

Memory placement This section can be placed anywhere in memory.

# .preinit\_array

Description Like .init\_array, but is used by the library to make some C++ initializations happen

before the others.

Memory placement This section can be placed anywhere in memory.

See also .init\_array, page 406.

# .prepreinit\_array

Description Like .init\_array, but is used when C static initialization is rewritten as dynamic

initialization. Performed before all C++ dynamic initialization.

Memory placement This section can be placed anywhere in memory.

See also .init\_array, page 406.

# .rodata

Description Holds constant data. This can include constant variables, string and aggregate literals,

etc.

Memory placement This section can be placed anywhere in memory.

#### .text

Description Holds program code, except the code for system initialization.

Memory placement This section can be placed anywhere in memory.

#### .textrw

Description Holds \_\_ramfunc declared program code.

Memory placement This section can be placed anywhere in memory.

See also \_\_ramfunc, page 299.

# .textrw\_init

Description Holds initializers for the .textrw declared sections.

Memory placement This section can be placed anywhere in memory.

See also \_\_ramfunc, page 299.

# IAR utilities

This chapter describes the IAR command line utilities that are available:

- The IAR Archive Tool—iarchive—creates and manipulates a library (an archive) of several ELF object files
- The IAR ELF Tool—ielftool—performs various transformations on an ELF executable image (such as fill, checksum, format conversions, etc)
- The IAR ELF Dumper for ARM—ielfdumparm—creates a text representation of the contents of an ELF relocatable or executable image
- The IAR ELF Object Tool—iobjmanip—is used for performing low-level manipulation of ELF object files
- The IAR Absolute Symbol Exporter—isymexport—exports absolute symbols from a ROM image file, so that they can be used when you link an add-on application.

Descriptions of options gives detailed reference information about each command line option available for the different utilities.

# The IAR Archive Tool—iarchive

The IAR Archive Tool, iarchive, can create a library (an archive) file from several ELF object files. You can also use iarchaive to manipulate ELF libraries.

A library file contains several relocatable ELF object modules, each of which can be independently used by a linker. In contrast with object modules specified directly to the linker, each module in a library is only included if it is needed.

For information about how to build a library in the IDE, see the *IDE Project Management and Building Guide for ARM*®.

#### INVOCATION SYNTAX

The invocation syntax for the archive builder is:

iarchive parameters

#### **Parameters**

The parameters are:

Parameter	Description
command	Command line options that define an operation to be performed.
	Such an option must be specified before the name of the library file.
libraryfile	The library file to be operated on.
objectfile1 objectfileN	The object file(s) that the specified command operates on.
options	Command line options that define actions to be performed. These options can be placed anywhere on the command line.

Table 40: iarchive parameters

# **Examples**

This example creates a library file called mylibrary.a from the source object files module1.o, module.2.o, and module3.o:

iarchive mylibrary.a module1.o module2.o module3.o.

This example lists the contents of mylibrary.a:

iarchive --toc mylibrary.a

This example replaces module3.0 in the library with the content in the module3.0 file and appends module4.0 to mylibrary.a:

iarchive --replace mylibrary.a module3.o module4.o

#### **SUMMARY OF IARCHIVE COMMANDS**

This table summarizes the iarchive commands:

Command line option	Description
create	Creates a library that contains the listed object files.
delete, -d	Deletes the listed object files from the library.
extract, -x	Extracts the listed object files from the library.
replace, -r	Replaces or appends the listed object files to the library.
symbols	Lists all symbols defined by files in the library.
toc, -t	Lists all files in the library.

Table 41: iarchive commands summary

For more information, see Descriptions of options, page 423.

## **SUMMARY OF IARCHIVE OPTIONS**

This table summarizes the iarchive options:

Command line option	Description
-f	Extends the command line.
output, -o	Specifies the library file.
silent	Sets silent operation.
verbose, -V	Reports all performed operations.

Table 42: iarchive options summary

For more information, see Descriptions of options, page 423.

#### **DIAGNOSTIC MESSAGES**

This section lists the messages produced by iarchive:

# La001: could not open file filename

iarchive failed to open an object file.

### La002: illegal path pathname

The path pathname is not a valid path.

#### La006: too many parameters to cmd command

A list of object modules was specified as parameters to a command that only accepts a single library file.

#### La007: too few parameters to cmd command

A command that takes a list of object modules was issued without the expected modules.

#### La008: lib is not a library file

The library file did not pass a basic syntax check. Most likely the file is not the intended library file.

# La009: lib has no symbol table

The library file does not contain the expected symbol information. The reason might be that the file is not the intended library file, or that it does not contain any ELF object modules.

# La010: no library parameter given

The tool could not identify which library file to operate on. The reason might be that a library file has not been specified.

#### La011: file file already exists

The file could not be created because a file with the same name already exists.

## La013: file confusions, lib given as both library and object

The library file was also mentioned in the list of object modules.

# La014: module module not present in archive lib

The specified object module could not be found in the archive.

#### La015: internal error

The invocation triggered an unexpected error in iarchive.

# Ms003: could not open file filename for writing

iarchive failed to open the archive file for writing. Make sure that it is not write protected.

# Ms004: problem writing to file filename

An error occurred while writing to file filename. A possible reason for this is that the volume is full.

#### Ms005: problem closing file filename

An error occurred while closing the file filename.

# The IAR ELF Tool—ielftool

The IAR ELF Tool, ielftool, can generate a checksum on specific ranges of memories. This checksum can be compared with a checksum calculated on your application.

The source code for ielftool and a Microsoft VisualStudio 2005 template project are available in the arm\src\elfutils directory. If you have specific requirements for how the checksum should be generated or requirements for format conversion, you can modify the source code accordingly.

#### **INVOCATION SYNTAX**

The invocation syntax for the IAR ELF Tool is:

```
ielftool [options] inputfile outputfile [options]
```

The ielftool tool will first process all the fill options, then it will process all the checksum options (from left to right).

#### **Parameters**

The parameters are:

Parameter	Description
inputfile	An absolute ELF executable image produced by the ILINK linker.
options	Any of the available command line options, see Summary of ielftool options, page 413.
outputfile	An absolute ELF executable image.

Table 43: ielftool parameters

For information about specifying a filename or a directory, see *Rules for specifying a filename or directory as parameters*, page 210.

# **Example**

This example fills a memory range with 0xFF and then calculates a checksum on the same range:

#### **SUMMARY OF IELFTOOL OPTIONS**

This table summarizes the ielftool command line options:

Command line option	Description
bin	Sets the format of the output file to binary.
checksum	Generates a checksum.
fill	Specifies fill requirements.
ihex	Sets the format of the output file to linear Intel hex.
self_reloc	Not for general use.
silent	Sets silent operation.
simple	Sets the format of the output file to Simple code.
srec	Sets the format of the output file to Motorola S-records.

Table 44: ielftool options summary

Command line option	Description
srec-len	Restricts the number of data bytes in each S-record.
srec-s3only	Restricts the S-record output to contain only a subset of records.
strip	Removes debug information.
verbose, -V	Prints all performed operations.

Table 44: ielftool options summary (Continued)

For more information, see Descriptions of options, page 423.

# The IAR ELF Dumper for ARM—ielfdumparm

The IAR ELF Dumper for ARM, ielfdumparm, can be used for creating a text representation of the contents of a relocatable or absolute ELF file.

ielfdumparm can be used in one of three ways:

- To produce a listing of the general properties of the input file and the ELF segments and ELF sections it contains. This is the default behavior when no command line options are used.
- To also include a textual representation of the contents of each ELF section in the input file. To specify this behavior, use the command line option --all.
- To produce a textual representation of selected ELF sections from the input file. To specify this behavior, use the command line option --section.

#### **INVOCATION SYNTAX**

The invocation syntax for ielfdumparm is:

ielfdumparm input\_file [output\_file]

**Note:** ielfdumparm is a command line tool which is not primarily intended to be used in the IDE.

#### **Parameters**

The parameters are:

Parameter	Description
input_file	An ELF relocatable or executable file to use as input.
output_file	A file or directory where the output is emitted. If absent and nooutput option is specified, output is directed to the console.

Table 45: ielfdumparm parameters

For information about specifying a filename or a directory, see *Rules for specifying a filename or directory as parameters*, page 210.

#### SUMMARY OF IELFDUMPARM OPTIONS

This table summarizes the ielfdumparm command line options:

Command line option	Description
all	Generates output for all input sections regardless of their names or numbers.
code	Dumps all sections that contain executable code.
-f	Extends the command line.
output, -o	Specifies an output file.
no_strtab	Suppresses dumping of string table sections.
raw	Uses the generic hexadecimal/ASCII output format for the contents of any selected section, instead of any dedicated output format for that section.
section, -s	Generates output for selected input sections.

Table 46: ielfdumparm options summary

For more information, see Descriptions of options, page 423.

# The IAR ELF Object Tool—iobjmanip

Use the IAR ELF Object Tool, iobjmanip, to perform low-level manipulation of ELF object files.

## **INVOCATION SYNTAX**

The invocation syntax for the IAR ELF Object Tool is:

iobjmanip options inputfile outputfile

#### **Parameters**

The parameters are:

Parameter	Description
options	Command line options that define actions to be performed. These
	options can be placed anywhere on the command line. At least one of
	the options must be specified.
inputfile	A relocatable ELF object file.

Table 47: iobjmanip parameters

Parameter	Description
outputfile	A relocatable ELF object file with all the requested operations applied.

Table 47: iobjmanip parameters (Continued)

For information about specifying a filename or a directory, see *Rules for specifying a filename or directory as parameters*, page 210.

## **Examples**

This example renames the section .example in input.o to .example2 and stores the result in output.o:

iobjmanip --rename\_section .example=.example2 input.o output.o

# **SUMMARY OF IOBJMANIP OPTIONS**

This table summarizes the iobjmanip options:

Command line option	Description
-f	Extends the command line.
remove_section	Removes a section.
rename_section	Renames a section.
rename_symbol	Renames a symbol.
strip	Removes debug information.

Table 48: iobjmanip options summary

For more information, see *Descriptions of options*, page 423.

#### **DIAGNOSTIC MESSAGES**

This section lists the messages produced by iobjmanip:

#### Lm001: No operation given

None of the command line parameters specified an operation to perform.

# Lm002: Expected nr parameters but got nr

Too few or too many parameters. Check invocation syntax for iobjmanip and for the used command line options.

#### Lm003: Invalid section/symbol renaming pattern pattern

The pattern does not define a valid renaming operation.

# Lm004: Could not open file filename

iobjmanip failed to open the input file.

#### Lm005: ELF format error msg

The input file is not a valid ELF object file.

## Lm006: Unsupported section type nr

The object file contains a section that iobjmanip cannot handle. This section will be ignored when generating the output file.

# Lm007: Unknown section type nr

iobjmanip encountered an unrecognized section. iobjmanip will try to copy the content as is.

# Lm008: Symbol symbol has unsupported format

iobjmanip encountered a symbol that cannot be handled. iobjmanip will ignore this symbol when generating the output file.

# Lm009: Group type nr not supported

iobjmanip only supports groups of type GRP\_COMDAT. If any other group type is encountered, the result is undefined.

## Lm010: Unsupported ELF feature in file: msg

The input file uses a feature that iobjmanip does not support.

### Lm011: Unsupported ELF file type

The input file is not a relocatable object file.

# Lm012: Ambiguous rename for section/symbol name (alt1 and alt2)

An ambiguity was detected while renaming a section or symbol. One of the alternatives will be used.

# Lm013: Section name removed due to transitive dependency on name

A section was removed as it depends on an explicitly removed section.

#### Lm014: File has no section with index nr

A section index, used as a parameter to --remove\_section or --rename\_section, did not refer to a section in the input file.

# Ms003: could not open file filename for writing

iobjmanip failed to open the output file for writing. Make sure that it is not write protected.

# Ms004: problem writing to file filename

An error occurred while writing to file filename. A possible reason for this is that the volume is full.

# Ms005: problem closing file filename

An error occurred while closing the file filename.

# The IAR Absolute Symbol Exporter—isymexport

The IAR Absolute Symbol Exporter, isymexport, can export absolute symbols from a ROM image file, so that they can be used when you link an add-on application.

#### INVOCATION SYNTAX

The invocation syntax for the IAR Absolute Symbol Exporter is:

isymexport [options] inputfile outputfile [options]

#### **Parameters**

The parameters are:

Parameter	Description
inputfile	A ROM image in the form of an executable ELF file (output from linking).
options	Any of the available command line options, see Summary of isymexport options, page 419.
outputfile	A relocatable ELF file that can be used as input to linking, and which contains all or a selection of the absolute symbols in the input file. The output file contains only the symbols, not the actual code or data sections. A steering file can be used to control which symbols that are included, and also to rename some of the symbols if that is desired.

Table 49: ielftool parameters

For information about specifying a filename or a directory, see *Rules for specifying a filename or directory as parameters*, page 210.

#### SUMMARY OF ISYMEXPORT OPTIONS

This table summarizes the isymexport command line options:

Command line option	Description
edit	Specifies a steering file.
-f	Extends the command line.
ram_reserve_ranges	Generates symbols to reserve the areas in RAM that the image uses.
reserve_ranges	Generates symbols to reserve the areas in ROM and RAM that the image uses.

Table 50: isymexport options summary

For more information, see Descriptions of options, page 423.

#### STEERING FILES

A steering file can be used for controlling which symbols that are included, and also to rename some of the symbols if that is desired. In the file, you can use show and hide directives to select which public symbols from the input file that are to be included in the output file. rename directives can be used for changing the names of symbols in the input file.

### **Syntax**

The following syntax rules apply:

- Each directive is specified on a separate line.
- C comments (/\*...\*/) and C++ comments (//...) can be used.
- Patterns can contain wildcard characters that match more than one possible character in a symbol name.
- The \* character matches any sequence of zero or more characters in a symbol name.
- The ? character matches any single character in a symbol name.

#### **Example**

```
rename xxx_* as YYY_* /*Change symbol prefix from xxx_ to YYY_ */
show YYY_* /* Export all symbols from YYY package */
hide *_internal /* But do not export internal symbols */
show zzz? /* Export zzza, but not zzzaaa */
hide zzzx /* But do not export zzzx */
```

# **Show directive**

Syntax show pattern

**Parameters** 

pattern A pattern to match against a symbol name.

**Description** A symbol with a name that matches the pattern will be included in the output file unless

this is overridden by a later hide directive.

Example /\* Include all public symbols ending in \_pub. \*/

show \*\_pub

# Hide directive

Syntax hide pattern

**Parameters** 

pattern A pattern to match against a symbol name.

Description A symbol with a name that matches the pattern will not be included in the output file

unless this is overridden by a later show directive.

Example /\* Do not include public symbols ending in \_sys. \*/

hide \*\_sys

### Rename directive

Syntax rename pattern1 pattern2

**Parameters** 

pattern1 A pattern used for finding symbols to be renamed. The pattern can

contain no more than one \* or ? wildcard character.

pattern2 A pattern used for the new name for a symbol. If the pattern contains a

wildcard character, it must be of the same kind as in pattern1.

Description Use this directive to rename symbols from the output file to the input file. No exported

symbol is allowed to match more than one rename pattern.

rename directives can be placed anywhere in the steering file, but they are executed before any show and hide directives. Thus, if a symbol will be renamed, all show and hide directives in the steering file must refer to the new name.

If the name of a symbol matches a pattern1 pattern that contains no wildcard characters, the symbol will be renamed pattern2 in the output file.

If the name of a symbol matches a pattern1 pattern that contains a wildcard character, the symbol will be renamed pattern2 in the output file, with part of the name matching the wildcard character preserved.

Example

```
/* xxx_start will be renamed Y_start_X in the output file,
    xxx_stop will be renamed Y_stop_X in the output file. */
rename xxx_* Y_*_X
```

#### **DIAGNOSTIC MESSAGES**

This section lists the messages produced by isymexport:

#### Es001: could not open file filename

isymexport failed to open the specified file.

# Es002: illegal path pathname

The path pathname is not a valid path.

### Es003: format error: message

A problem occurred while reading the input file.

#### Es004: no input file

No input file was specified.

#### Es005: no output file

An input file, but no output file was specified.

### Es006: too many input files

More than two files were specified.

# Es007: input file is not an ELF executable

The input file is not an ELF executable file.

#### Es008: unknown directive: directive

The specified directive in the steering file is not recognized.

## Es009: unexpected end of file

The steering file ended when more input was required.

#### Es010: unexpected end of line

A line in the steering file ended before the directive was complete.

## Es011: unexpected text after end of directive

There is more text on the same line after the end of a steering file directive.

### Es012: expected text

The specified text was not present in the steering file, but must be present for the directive to be correct.

# Es013: pattern can contain at most one \* or ?

Each pattern in the current directive can contain at most one \* or one ? wildcard character.

# Es014: rename patterns have different wildcards

Both patterns in the current directive must contain exactly the same kind of wildcard. That is, both must either contain:

- No wildcards
- Exactly one \*
- Exactly one ?

This error occurs if the patterns are not the same in this regard.

# Es014: ambiguous pattern match: symbol matches more than one rename pattern

A symbol in the input file matches more than one rename pattern.

# **Descriptions of options**

This section gives detailed reference information about each command line option available for the different utilities.

#### --all

Syntax --all

Tool ielfdumparm

Description Use this option to include the contents of all ELF sections in the output, in addition to

the general properties of the input file. Sections are output in index order, except that each relocation section is output immediately after the section it holds relocations for.

By default, no section contents are included in the output.



This option is not available in the IDE.

#### --bin

Syntax --bin

Tool ielftool

**Description** Sets the format of the output file to binary.



To set related options, choose:

#### Project>Options>Output converter

#### --checksum

Syntax --checksum

 $\{symbol\,[+offset]\,\big|\,address\}: size, algorithm\,[:[1\,\big|\,2]\,[m]\,[r]\,[i\,\big|\,p]\,]$ 

[,start];range[;range...]

**Parameters** 

Symbol The name of the symbol where the checksum value should be stored.

Note that it must exist in the symbol table in the input ELF file.

offset An offset to the symbol.

address	The absolute address where the checksum value should be stored.
size	The number of bytes in the checksum: $1,2,\mathrm{or}4;\mathrm{must}$ not be larger than the size of the checksum symbol.
algorithm	The checksum algorithm used, one of:  • sum, a byte-wise calculated arithmetic sum. The result is truncated to 8 bits.  • sum8wide, a byte-wise calculated arithmetic sum. The result is truncated to the size of the symbol.  • sum32, a word-wise (32 bits) calculated arithmetic sum  • crc16, CRC16 (generating polynomial 0x11021); used by default  • crc32, CRC32 (generating polynomial 0x104C11DB7)  • crc=n, CRC with a generating polynomial of n.
1   2	If specified, can be one of:  • 1 - Specifies one's complement.  • 2 - Specifies two's complement.
m	Reverses the order of the bits within each byte when calculating the checksum.
r	Reverses the byte order of the input data within each word of size $size$ .
i p	Use either $i$ or $p$ , if the $start$ value is bigger than 0. If specified, can be one of:  • $i$ – Initializes the checksum value with the start value.  • $p$ – Prefixes the input data with a word of size $size$ that contains the $start$ value.
start	By default, the initial value of the checksum is 0. If necessary, use $start$ to supply a different initial value. If not 0, then either $i$ or $p$ must be specified.
range	The address range on which the checksum should be calculated. Hexadecimal and decimal notation is allowed (for example, $0x8002-0x8FFF$ ).
ielftool	

Tool

ielftool

Description

Use this option to calculate a checksum with the specified algorithm for the specified ranges. The checksum will then replace the original value in <code>symbol</code>. A new absolute symbol will be generated; with the <code>symbol</code> name suffixed with <code>\_value</code> containing the calculated checksum. This symbol can be used for accessing the checksum value later when needed, for example during debugging.

If the --checksum option is used more than once on the command line, the options are evaluated from left to right. If a checksum is calculated for a *symbol* that is specified in a later evaluated --checksum option, an error is issued.

Example This example shows how to use the crc16 algorithm with the start value 0 over the

address range 0x8000-0x8FFF:

ielftool --checksum=\_\_checksum:2,crc16;0x8000-0x8FFF

sourceFile.out destinationFile.out

The input data i read from sourceFile.out, and the resulting checksum value of size 2 bytes will be stored at the symbol \_\_checksum. The modified ELF file is saved as

destinationFile.out leaving sourceFile.out untouched.

See also Checksum calculation, page 169

X

To set related options, choose:

Project>Options>Linker>Checksum

--code

Syntax --code

Tool ielfdump

Description Use this option to dump all sections that contain executable code (sections with the ELF

section attribute SHF\_EXECINSTR).

This option is not available in the IDE.

--create

Syntax --create libraryfile objectfile1 ... objectfileN

**Parameters** 

11braryfile The library file that the command operates on. For information about

specifying a filename, see Rules for specifying a filename or directory as

parameters, page 210.

objectfile1 ... The object file(s) to build the library from.

objectfileN

Tool iarchive

Description

Use this command to build a new library from a set of object files (modules). The object files are added to the library in the exact order that they are specified on the command

line.

If no command is specified on the command line, --create is used by default.



This option is not available in the IDE.

# --delete, -d

Syntax --delete libraryfile objectfile1 ... objectfileN -d libraryfile objectfile1 ... objectfileN

**Parameters** 

library file The library file that the command operates on. For information about

specifying a filename, see Rules for specifying a filename or directory as

parameters, page 210.

objectfile1 ... The object file(s) that the command operates on.

objectfileN

Tool iarchive

Description Use this command to remove object files (modules) from an existing library. All object

files that are specified on the command line will be removed from the library.



This option is not available in the IDE.

# --edit

Syntax --edit steering\_file

Tool isymexport

Description Use this option to specify a steering file to control which symbols that are included in

the isymexport output file, and also to rename some of the symbols if that is desired.

See also Steering files, page 419.

X

This option is not available in the IDE.

#### --extract, -x

Syntax --extract libraryfile [objectfile1 ... objectfileN]

-x libraryfile [objectfile1 ... objectfileN]

**Parameters** 

11braryfile The library file that the command operates on. For information about

specifying a filename, see Rules for specifying a filename or directory as

parameters, page 210.

objectfile1 ... The object file(s) that the command operates on.

objectfileN

Tool iarchive

Description Use this command to extract object files (modules) from an existing library. If a list of

object files is specified, only these files are extracted. If a list of object files is not

specified, all object files in the library are extracted.

X

This option is not available in the IDE.

-f

Syntax -f filename

Parameters For information about specifying a filename, see Rules for specifying a filename or

directory as parameters, page 210.

Tool iarchive, ielfdumparm, iobjmanip, and isymexport.

Description Use this option to make the tool read command line options from the named file, with

the default filename extension xcl.

In the command file, you format the items exactly as if they were on the command line itself, except that you can use multiple lines, because the newline character acts just as

a space or tab character.

Both C and C++ style comments are allowed in the file. Double quotes behave in the

same way as in the Microsoft Windows command line environment.

X

This option is not available in the IDE.

# --fill

Syntax --fill pattern; range[; range...]

**Parameters** 

range Specifies the address range for the fill. Hexadecimal and decimal

notation is allowed (for example, 0x8002-0x8FFF). Note that each

address must be 4-byte aligned.

pattern A hexadecimal string with the 0x prefix (for example, 0xEF)

interpreted as a sequence of bytes, where each pair of digits

corresponds to one byte (for example 0x123456, for the sequence of bytes 0x12, 0x34, and 0x56). This sequence is repeated over the fill area. If the length of the fill pattern is greater than 1 byte, it is repeated

as if it started at address 0.

Applicability ielftool

Description

Use this option to fill all gaps in one or more ranges with a pattern, which can be either an expression or a hexadecimal string. The contents will be calculated as if the fill

then the real contents will overwrite that pattern.

If the --fill option is used more than once on the command line, the fill ranges cannot

pattern was repeatedly filled from the start address until the end address is passed, and

overlap each other.

X

To set related options, choose:

Project>Options>Linker>Checksum

--ihex

Syntax --ihex

Tool ielftool

**Description** Sets the format of the output file to linear Intel hex.

X

To set related options, choose:

Project>Options>Linker>Output converter

## --no\_strtab

Syntax --no\_strtab

Tool ielfdumparm

Description Use this option to suppress dumping of string table sections (sections of type

SHT\_STRTAB).



This option is not available in the IDE.

# --output, -o

Syntax -o {filename | directory}

--output {filename | directory}

Parameters For information about specifying a filename or a directory, see *Rules for specifying a* 

filename or directory as parameters, page 210.

Tool iarchive and ielfdumparm.

**Description** iarchive

By default, iarchive assumes that the first argument after the iarchive command is the name of the destination library. Use this option to explicitly specify a different

filename for the library.

ielfdumparm

By default, output from the dumper is directed to the console. Use this option to direct the output to a file instead. The default name of the output file is the name of the input

file with an added id filename extension

You can also specify the output file by specifying a file or directory following the name

of the input file.



This option is not available in the IDE.

# --ram\_reserve\_ranges

Syntax --ram\_reserve\_ranges[=symbol\_prefix]

**Parameters** 

symbol\_prefix The prefix of symbols created by this option.

Tool isymexport

Description Use this option to generate symbols for the areas in RAM that the image uses. One

symbol will be generated for each such area. The name of each symbol is based on the name of the area and is prefixed by the optional parameter <code>symbol\_prefix</code>.

Generating symbols that cover an area in this way prevents the linker from placing other content at the affected addresses. This can be useful when linking against an existing

If --ram\_reserve\_ranges is used together with --reserve\_ranges, the RAM areas will get their prefix from the --ram\_reserve\_ranges option and the non-RAM areas will get their prefix from the --reserve\_ranges option.

See also --reserve\_ranges, page 432.

image.



This option is not available in the IDE.

--raw

Syntax --raw

Tool ielfdumparm

**Description** By default, many ELF sections will be dumped using a text format specific to a

particular kind of section. Use this option to dump each selected ELF section using the

generic text format.

The generic text format dumps each byte in the section in hexadecimal format, and

where appropriate, as ASCII text.



This option is not available in the IDE.

### --remove section

Syntax --remove\_section { section | number }

**Parameters** 

section The section—or sections, if there are more than one section with the

same name—to be removed.

number The number of the section to be removed. Section numbers can be

obtained from an object dump created using ielfdumparm.

Tool iobjmanip

Description Use this option to make iobjmanip omit the specified section when generating the

output file.

X

This option is not available in the IDE.

# --rename section

Syntax --rename\_section {oldname|oldnumber}=newname

**Parameters** 

oldname The section—or sections, if there are more than one section with the

same name—to be renamed.

oldnumber The number of the section to be renamed. Section numbers can be

obtained from an object dump created using ielfdumparm.

newname The new name of the section.

Tool iobjmanip

Description Use this option to make iobjmanip rename the specified section when generating the

output file.

X

This option is not available in the IDE.

# --rename\_symbol

Syntax --rename\_symbol oldname =newname

**Parameters** 

oldname The symbol to be renamed.

newname The new name of the symbol.

Tool iobjmanip

Description Use this option to make iobjmanip rename the specified symbol when generating the

output file.

X

This option is not available in the IDE.

# --replace, -r

Syntax --replace libraryfile objectfile1 ... objectfileN

-r libraryfile objectfile1 ... objectfileN

**Parameters** 

11braryfile The library file that the command operates on. For information about

specifying a filename, see Rules for specifying a filename or directory as

parameters, page 210.

objectfile1 ... The object file(s) that the command operates on.

objectfileN

Tool iarchive

Description Use this command to replace or add object files (modules) to an existing library. The

object files specified on the command line either replace existing object files in the

library (if they have the same name) or are appended to the library.



This option is not available in the IDE.

# --reserve\_ranges

Syntax --reserve\_ranges[=symbol\_prefix]

**Parameters** 

 $symbol\_prefix$  The prefix of symbols created by this option.

Tool isymexport

Description Use this option to generate symbols for the areas in ROM and RAM that the image uses.

One symbol will be generated for each such area. The name of each symbol is based on the name of the area and is prefixed by the optional parameter <code>symbol\_prefix</code>.

Generating symbols that cover an area in this way prevents the linker from placing other content at the affected addresses. This can be useful when linking against an existing

image.

 $If --reserve\_ranges is used together with --ram\_reserve\_ranges, the RAM areas will get their prefix from the --ram\_reserve\_ranges option and the non-RAM$ 

areas will get their prefix from the --reserve\_ranges option.

See also --ram\_reserve\_ranges, page 429.



This option is not available in the IDE.

#### --section, -s

**Parameters** 

section\_number The number of the section to be dumped.section\_name The name of the section to be dumped.

Tool ielfdumparm

Description Use this option to dump the contents of a section with the specified number, or any

section with the specified name. If a relocation section is associated with a selected

section, its contents are output as well.

If you use this option, the general properties of the input file will not be included in the

output.

You can specify multiple section numbers or names by separating them with commas,

or by using this option more than once.

By default, no section contents are included in the output.

Example -s 3,17 /\* Sections #3 and #17

-s .debug\_frame,42  $\,$  /\* Any sections named .debug\_frame and

also section #42 \*/



This option is not available in the IDE.

#### --self reloc

Syntax --self\_reloc

Tool ielftool

**Description** This option is intentionally not documented as it is not intended for general use.

This option is not available in the IDE.

#### --silent

Syntax --silent

-S (iarchive only)

Tool iarchive and ielftool.

Description Causes the tool to operate without sending any messages to the standard output stream.

By default, ielftool sends various messages via the standard output stream. You can use this option to prevent this. ielftool sends error and warning messages to the error

output stream, so they are displayed regardless of this setting.



This option is not available in the IDE.

#### --simple

Syntax --simple

Tool ielftool

Description Sets the format of the output file to Simple code.

X

To set related options, choose:

Project>Options>Output converter

#### --srec

Syntax --srec

Tool ielftool

Description Sets the format of the output file to Motorola S-records.

X

To set related options, choose:

Project>Options>Output converter

#### --srec-len

Syntax --srec-len=length

**Parameters** 

1ength The number of data bytes in each S-record.

Tool ielftool

Description Restricts the number of data bytes in each S-record. This option can be used in

combination with the --srec option.

X

This option is not available in the IDE.

#### --srec-s3only

Syntax --srec-s3only

Tool ielftool

Description Restricts the S-record output to contain only a subset of records, that is S0, S3 and S7

records. This option can be used in combination with the --srec option.

X

This option is not available in the IDE.

#### --strip

Syntax --strip

Tool iobjmanip and ielftool.

Description Use this option to remove all sections containing debug information before the output

file is written.

Note that ielftool needs an unstripped input ELF image. If you use the --strip option in the linker, remove it and use the --strip option in ielftool instead.

X

To set related options, choose:

Project>Options>Linker>Output>Include debug information in output

#### --symbols

Syntax --symbols libraryfile

**Parameters** 

1ibraryfile The library file that the command operates on. For information about

specifying a filename, see Rules for specifying a filename or directory as

parameters, page 210.

Tool iarchive

Description Use this command to list all external symbols that are defined by any object file

(module) in the specified library, together with the name of the object file (module) that

defines it.

In silent mode (--silent), this command performs symbol table-related syntax checks

on the library file and displays only errors and warnings.



This option is not available in the IDE.

#### --toc, -t

Syntax --toc libraryfile

-t libraryfile

**Parameters** 

11braryfile The library file that the command operates on. For information about

specifying a filename, see Rules for specifying a filename or directory as

parameters, page 210.

Tool iarchive

Description Use this command to list the names of all object files (modules) in a specified library.

In silent mode (--silent), this command performs basic syntax checks on the library

file, and displays only errors and warnings.



This option is not available in the IDE.

#### --verbose, -V

Syntax --verbose

-V (iarchive only)

Tool iarchive and ielftool.

Description Use this option to make the tool report which operations it performs, in addition to

giving diagnostic messages.



This option is not available in the IDE because this setting is always enabled.

Descriptions of options

# Implementation-defined behavior

This chapter describes how IAR Systems handles the implementation-defined areas of the C language.

Note: The IAR Systems implementation adheres to a freestanding implementation of Standard C. This means that parts of a standard library can be excluded in the implementation.

#### Descriptions of implementation-defined behavior

This section follows the same order as the C standard. Each item includes references to the ISO chapter and section (in parenthesis) that explains the implementation-defined behavior.

#### J.3.1 Translation

#### **Diagnostics (3.10, 5.1.1.3)**

Diagnostics are produced in the form:

filename, linenumber level[tag]: message

where filename is the name of the source file in which the error was encountered, linenumber is the line number at which the compiler detected the error, level is the level of seriousness of the message (remark, warning, error, or fatal error), tag is a unique tag that identifies the message, and message is an explanatory message, possibly several lines.

#### White-space characters (5.1.1.2)

At translation phase three, each non-empty sequence of white-space characters is retained.

#### J.3.2 Environment

#### The character set (5.1.1.2)

The source character set is the same as the physical source file multibyte character set. By default, the standard ASCII character set is used. However, if you use the --enable\_multibytes compiler option, the host character set is used instead.

#### Main (5.1.2.1)

The function called at program startup is called main. No prototype is declared for main, and the only definition supported for main is:

```
int main(void)
```

To change this behavior, see *Customizing system initialization*, page 106.

#### The effect of program termination (5.1.2.1)

Terminating the application returns the execution to the startup code (just after the call to main).

#### Alternative ways to define main (5.1.2.2.1)

There is no alternative ways to define the main function.

#### The argv argument to main (5.1.2.2.1)

The argy argument is not supported.

#### Streams as interactive devices (5.1.2.3)

The streams stdin, stdout, and stderr are treated as interactive devices.

#### Signals, their semantics, and the default handling (7.14)

In the DLIB library, the set of supported signals is the same as in Standard C. A raised signal will do nothing, unless the signal function is customized to fit the application.

#### Signal values for computational exceptions (7.14.1.1)

In the DLIB library, there are no implementation-defined values that correspond to a computational exception.

#### Signals at system startup (7.14.1.1)

In the DLIB library, there are no implementation-defined signals that are executed at system startup.

#### Environment names (7.20.4.5)

In the DLIB library, there are no implementation-defined environment names that are used by the getenv function.

#### The system function (7.20.4.6)

The system function is not supported.

#### J.3.3 Identifiers

#### Multibyte characters in identifiers (6.4.2)

Additional multibyte characters may not appear in identifiers.

#### Significant characters in identifiers (5.2.4.1, 6.1.2)

The number of significant initial characters in an identifier with or without external linkage is guaranteed to be no less than 200.

#### J.3.4 Characters

#### Number of bits in a byte (3.6)

A byte contains 8 bits.

#### Execution character set member values (5.2.1)

The values of the members of the execution character set are the values of the ASCII character set, which can be augmented by the values of the extra characters in the host character set.

#### Alphabetic escape sequences (5.2.2)

The standard alphabetic escape sequences have the values a-7, b-8, f-12, n-10, r-13, t-9, and v-11.

#### Characters outside of the basic executive character set (6.2.5)

A character outside of the basic executive character set that is stored in a char is not transformed.

#### Plain char (6.2.5, 6.3.1.1)

A plain char is treated as an unsigned char.

#### Source and execution character sets (6.4.4.4, 5.1.1.2)

The source character set is the set of legal characters that can appear in source files. By default, the source character set is the standard ASCII character set. However, if you use the command line option --enable\_multibytes, the source character set will be the host computer's default character set.

The execution character set is the set of legal characters that can appear in the execution environment. By default, the execution character set is the standard ASCII character set.

However, if you use the command line option --enable\_multibytes, the execution character set will be the host computer's default character set. The IAR DLIB Library needs a multibyte character scanner to support a multibyte execution character set. See *Locale*, page 112.

#### Integer character constants with more than one character (6.4.4.4)

An integer character constant that contains more than one character will be treated as an integer constant. The value will be calculated by treating the leftmost character as the most significant character, and the rightmost character as the least significant character, in an integer constant. A diagnostic message will be issued if the value cannot be represented in an integer constant.

#### Wide character constants with more than one character (6.4.4.4)

A wide character constant that contains more than one multibyte character generates a diagnostic message.

#### Locale used for wide character constants (6.4.4.4)

By default, the C locale is used. If the --enable\_multibytes compiler option is used, the default host locale is used instead.

#### Locale used for wide string literals (6.4.5)

By default, the C locale is used. If the --enable\_multibytes compiler option is used, the default host locale is used instead.

#### Source characters as executive characters (6.4.5)

All source characters can be represented as executive characters.

#### J.3.5 Integers

#### Extended integer types (6.2.5)

There are no extended integer types.

#### Range of integer values (6.2.6.2)

The representation of integer values are in the two's complement form. The most significant bit holds the sign; 1 for negative, 0 for positive and zero.

For information about the ranges for the different integer types, see *Basic data types*, page 276.

#### The rank of extended integer types (6.3.1.1)

There are no extended integer types.

#### Signals when converting to a signed integer type (6.3.1.3)

No signal is raised when an integer is converted to a signed integer type.

#### Signed bitwise operations (6.5)

Bitwise operations on signed integers work the same way as bitwise operations on unsigned integers; in other words, the sign-bit will be treated as any other bit.

#### J.3.6 Floating point

#### Accuracy of floating-point operations (5.2.4.2.2)

The accuracy of floating-point operations is unknown.

#### Rounding behaviors (5.2.4.2.2)

There are no non-standard values of FLT ROUNDS.

#### Evaluation methods (5.2.4.2.2)

There are no non-standard values of FLT\_EVAL\_METHOD.

#### Converting integer values to floating-point values (6.3.1.4)

When an integral value is converted to a floating-point value that cannot exactly represent the source value, the round-to-nearest rounding mode is used (FLT\_ROUNDS is defined to 1).

#### Converting floating-point values to floating-point values (6.3.1.5)

When a floating-point value is converted to a floating-point value that cannot exactly represent the source value, the round-to-nearest rounding mode is used (FLT\_ROUNDS is defined to 1).

#### Denoting the value of floating-point constants (6.4.4.2)

The round-to-nearest rounding mode is used (FLT\_ROUNDS is defined to 1).

#### Contraction of floating-point values (6.5)

Floating-point values are contracted. However, there is no loss in precision and because signaling is not supported, this does not matter.

#### Default state of FENV\_ACCESS (7.6.1)

The default state of the pragma directive FENV\_ACCESS is OFF.

#### Additional floating-point mechanisms (7.6, 7.12)

There are no additional floating-point exceptions, rounding-modes, environments, and classifications.

#### Default state of FP\_CONTRACT (7.12.2)

The default state of the pragma directive FP\_CONTRACT is OFF.

#### J.3.7 Arrays and pointers

#### Conversion from/to pointers (6.3.2.3)

For information about casting of data pointers and function pointers, see *Casting*, page 284.

#### ptrdiff\_t (6.5.6)

For information about ptrdiff\_t, see *ptrdiff\_t*, page 285.

#### J.3.8 Hints

#### Honoring the register keyword (6.7.1)

User requests for register variables are not honored.

#### Inlining functions (6.7.4)

User requests for inlining functions increases the chance, but does not make it certain, that the function will actually be inlined into another function. See the pragma directive *inline*, page 311.

#### J.3.9 Structures, unions, enumerations, and bitfields

#### Sign of 'plain' bitfields (6.7.2, 6.7.2.1)

For information about how a 'plain' int bitfield is treated, see *Bitfields*, page 278.

#### Possible types for bitfields (6.7.2.1)

All integer types can be used as bitfields in the compiler's extended mode, see -e, page 225.

#### Bitfields straddling a storage-unit boundary (6.7.2.1)

A bitfield is always placed in one—and one only—storage unit, which means that the bitfield cannot straddle a storage-unit boundary.

#### Allocation order of bitfields within a unit (6.7.2.1)

For information about how bitfields are allocated within a storage unit, see *Bitfields*, page 278.

#### Alignment of non-bitfield structure members (6.7.2.1)

The alignment of non-bitfield members of structures is the same as for the member types, see *Alignment*, page 275.

#### Integer type used for representing enumeration types (6.7.2.2)

The chosen integer type for a specific enumeration type depends on the enumeration constants defined for the enumeration type. The chosen integer type is the smallest possible.

#### J.3.10 Qualifiers

#### Access to volatile objects (6.7.3)

Any reference to an object with volatile qualified type is an access, see *Declaring objects volatile*, page 287.

#### J.3.11 Preprocessing directives

#### Mapping of header names (6.4.7)

Sequences in header names are mapped to source file names verbatim. A backslash '\' is not treated as an escape sequence. See *Overview of the preprocessor*, page 365.

#### Character constants in constant expressions (6.10.1)

A character constant in a constant expression that controls conditional inclusion matches the value of the same character constant in the execution character set.

#### The value of a single-character constant (6.10.1)

A single-character constant may only have a negative value if a plain character (char) is treated as a signed character, see --char\_is\_signed, page 217.

#### Including bracketed filenames (6.10.2)

For information about the search algorithm used for file specifications in angle brackets <>, see *Include file search procedure*, page 203.

#### Including quoted filenames (6.10.2)

For information about the search algorithm used for file specifications enclosed in quotes, see *Include file search procedure*, page 203.

#### Preprocessing tokens in #include directives (6.10.2)

Preprocessing tokens in an #include directive are combined in the same way as outside an #include directive.

#### Nesting limits for #include directives (6.10.2)

There is no explicit nesting limit for #include processing.

#### Universal character names (6.10.3.2)

Universal character names (UCN) are not supported.

#### Recognized pragma directives (6.10.6)

In addition to the pragma directives described in the chapter *Pragma directives*, the following directives are recognized and will have an indeterminate effect. If a pragma directive is listed both in the *Pragma directives* chapter and here, the information provided in the *Pragma directives* chapter overrides the information here.

alignment

```
baseaddr
basic_template_matching
building_runtime
can_instantiate
codeseg
constseg
cspy_support
dataseg
define_type_info
do_not_instantiate
early_dynamic_initialization
function
hdrstop
important_typedef
instantiate
keep_definition
library_requirement_override
library_provides
library_requirement_override
memory
module_name
no_pch
once
public_equ
system_include
vector
warnings
```

#### **Default \_\_DATE\_\_ and \_\_TIME\_\_ (6.10.8)**

The definitions for  $\__{\tt TIME}\_$  and  $\__{\tt DATE}\_$  are always available.

#### J.3.12 Library functions

#### Additional library facilities (5.1.2.1)

Most of the standard library facilities are supported. Some of them—the ones that need an operating system—requiere a low-level implementation in the application. For more information, see *The DLIB runtime environment*, page 89.

#### Diagnostic printed by the assert function (7.2.1.1)

The assert () function prints:

filename: linenr expression -- assertion failed

when the parameter evaluates to zero.

#### Representation of the floating-point status flags (7.6.2.2)

For information about the floating-point status flags, see *fenv.h*, page 377.

#### Feraiseexcept raising floating-point exception (7.6.2.3)

For information about the feraiseexcept function raising floating-point exceptions, see Floating-point environment, page 282.

#### Strings passed to the setlocale function (7.11.1.1)

For information about strings passed to the setlocale function, see *Locale*, page 112.

#### Types defined for float t and double t (7.12)

The FLT\_EVAL\_METHOD macro can only have the value 0.

#### Domain errors (7.12.1)

No function generates other domain errors than what the standard requires.

#### Return values on domain errors (7.12.1)

Mathematic functions return a floating-point NaN (not a number) for domain errors.

#### Underflow errors (7.12.1)

Mathematic functions set errno to the macro ERANGE (a macro in errno.h) and return zero for underflow errors.

#### fmod return value (7.12.10.1)

The fmod function returns a floating-point NaN when the second argument is zero.

#### The magnitude of remquo (7.12.10.3)

The magnitude is congruent modulo INT\_MAX.

#### signal() (7.14.1.1)

The signal part of the library is not supported.

**Note:** Low-level interface functions exist in the library, but will not perform anything. Use the template source code to implement application-specific signal handling. See *Signal and raise*, page 116.

#### NULL macro (7.17)

The NULL macro is defined to 0.

#### Terminating newline character (7.19.2)

stdout stream functions recognize either newline or end of file (EOF) as the terminating character for a line.

#### Space characters before a newline character (7.19.2)

Space characters written to a stream immediately before a newline character are preserved.

#### Null characters appended to data written to binary streams (7.19.2)

No null characters are appended to data written to binary streams.

#### File position in append mode (7.19.3)

The file position is initially placed at the beginning of the file when it is opened in append-mode.

#### Truncation of files (7.19.3)

Whether a write operation on a text stream causes the associated file to be truncated beyond that point, depends on the application-specific implementation of the low-level file routines. See *File input and output*, page 112.

#### File buffering (7.19.3)

An open file can be either block-buffered, line-buffered, or unbuffered.

#### A zero-length file (7.19.3)

Whether a zero-length file exists depends on the application-specific implementation of the low-level file routines.

#### Legal file names (7.19.3)

The legality of a filename depends on the application-specific implementation of the low-level file routines.

#### Number of times a file can be opened (7.19.3)

Whether a file can be opened more than once depends on the application-specific implementation of the low-level file routines.

#### Multibyte characters in a file (7.19.3)

The encoding of multibyte characters in a file depends on the application-specific implementation of the low-level file routines.

#### remove() (7.19.4.1)

The effect of a remove operation on an open file depends on the application-specific implementation of the low-level file routines. See *File input and output*, page 112.

#### rename() (7.19.4.2)

The effect of renaming a file to an already existing filename depends on the application-specific implementation of the low-level file routines. See *File input and output*, page 112.

#### Removal of open temporary files (7.19.4.3)

Whether an open temporary file is removed depends on the application-specific implementation of the low-level file routines.

#### Mode changing (7.19.5.4)

freopen closes the named stream, then reopens it in the new mode. The streams stdin, stdout, and stderr can be reopened in any new mode.

#### Style for printing infinity or NaN (7.19.6.1, 7.24.2.1)

The style used for printing infinity or NaN for a floating-point constant is inf and nan (INF and NAN for the F conversion specifier), respectively. The n-char-sequence is not used for nan.

#### %p in printf() (7.19.6.1, 7.24.2.1)

The argument to a %p conversion specifier, print pointer, to printf() is treated as having the type void \*. The value will be printed as a hexadecimal number, similar to using the %x conversion specifier.

#### Reading ranges in scanf (7.19.6.2, 7.24.2.1)

A - (dash) character is always treated as a range symbol.

#### %p in scanf (7.19.6.2, 7.24.2.2)

The %p conversion specifier, scan pointer, to scanf() reads a hexadecimal number and converts it into a value with the type void \*.

#### File position errors (7.19.9.1, 7.19.9.3, 7.19.9.4)

On file position errors, the functions fgetpos, ftell, and fsetpos store EFPOS in errno.

#### An n-char-sequence after nan (7.20.1.3, 7.24.4.1.1)

An n-char-sequence after a NaN is read and ignored.

#### errno value at underflow (7.20.1.3, 7.24.4.1.1)

errno is set to ERANGE if an underflow is encountered.

#### Zero-sized heap objects (7.20.3)

A request for a zero-sized heap object will return a valid pointer and not a null pointer.

#### Behavior of abort and exit (7.20.4.1, 7.20.4.4)

A call to abort () or \_Exit() will not flush stream buffers, not close open streams, and not remove temporary files.

#### Termination status (7.20.4.1, 7.20.4.3, 7.20.4.4)

The termination status will be propagated to \_\_exit() as a parameter. exit() and \_Exit() use the input parameter, whereas abort uses EXIT\_FAILURE.

#### The system function return value (7.20.4.6)

The system function is not supported.

#### The time zone (7.23.1)

The local time zone and daylight savings time must be defined by the application. For more information, see *Time*, page 116.

#### Range and precision of time (7.23)

The implementation uses signed long for representing clock\_t and time\_t, based at the start of the year 1970. This gives a range of approximately plus or minus 69 years in seconds. However, the application must supply the actual implementation for the functions time and clock. See *Time*, page 116.

#### clock() (7.23.2.1)

The application must supply an implementation of the clock function. See *Time*, page 116.

#### %Z replacement string (7.23.3.5, 7.24.5.1)

By default, ":" is used as a replacement for %z. Your application should implement the time zone handling. See *Time*, page 116.

#### Math functions rounding mode (F.9)

The functions in math.h honor the rounding direction mode in FLT-ROUNDS.

#### J.3.13 Architecture

## Values and expressions assigned to some macros (5.2.4.2, 7.18.2, 7.18.3)

There are always 8 bits in a byte.

MB\_LEN\_MAX is at the most 6 bytes depending on the library configuration that is used.

For information about sizes, ranges, etc for all basic types, see *Data representation*, page 275.

The limit macros for the exact-width, minimum-width, and fastest minimum-width integer types defined in stdint.h have the same ranges as char, short, int, long, and long long.

The floating-point constant FLT\_ROUNDS has the value 1 (to nearest) and the floating-point constant FLT\_EVAL\_METHOD has the value 0 (treat as is).

#### The number, order, and encoding of bytes (6.2.6.1)

See Data representation, page 275.

#### The value of the result of the size of operator (6.5.3.4)

See Data representation, page 275.

#### J.4 Locale

#### Members of the source and execution character set (5.2.1)

By default, the compiler accepts all one-byte characters in the host's default character set. If the compiler option --enable\_multibytes is used, the host multibyte characters are accepted in comments and string literals as well.

#### The meaning of the additional character set (5.2.1.2)

Any multibyte characters in the extended source character set is translated verbatim into the extended execution character set. It is up to your application with the support of the library configuration to handle the characters correctly.

#### Shift states for encoding multibyte characters (5.2.1.2)

Using the compiler option --enable\_multibytes enables the use of the host's default multibyte characters as extended source characters.

#### Direction of successive printing characters (5.2.2)

The application defines the characteristics of a display device.

#### The decimal point character (7.1.1)

The default decimal-point character is a '.'. You can redefine it by defining the library configuration symbol \_LOCALE\_DECIMAL\_POINT.

#### Printing characters (7.4, 7.25.2)

The set of printing characters is determined by the chosen locale.

#### Control characters (7.4, 7.25.2)

The set of control characters is determined by the chosen locale.

## Characters tested for (7.4.1.2, 7.4.1.3, 7.4.1.7, 7.4.1.9, 7.4.1.10, 7.4.1.11, 7.25.2.1.2, 7.25.5.1.3, 7.25.2.1.7, 7.25.2.1.9, 7.25.2.1.10, 7.25.2.1.11)

The sets of characters tested are determined by the chosen locale.

#### The native environment (7.1.1.1)

The native environment is the same as the "C" locale.

### Subject sequences for numeric conversion functions (7.20.1, 7.24.4.1)

There are no additional subject sequences that can be accepted by the numeric conversion functions.

#### The collation of the execution character set (7.21.4.3, 7.24.4.4.2)

The collation of the execution character set is determined by the chosen locale.

#### Message returned by strerror (7.21.6.2)

The messages returned by the strerror function depending on the argument is:

Argument	Message
EZERO	no error
EDOM	domain error
ERANGE	range error
EFPOS	file positioning error
EILSEQ	multi-byte encoding error
<0    >99	unknown error
all others	error nnn

Table 51: Message returned by strerror()—IAR DLIB library

Λ	architecture
<b>A</b>	more information about
AAPCS (predefined symbol)	of ARM
aapcs (compiler option)	argv (argument), implementation-defined behavior 440
AAPCS_VFP (predefined symbol)	ARM
ABI, AEABI and IA64	and Thumb code, overview
abort	CPU mode
implementation-defined behavior	memory layout53
system termination (DLIB)	supported devices
Abort_Handler (exception function) 60	_arm (extended keyword)
_absolute (extended keyword)	arm (compiler option)
absolute location	ARMVFP (predefined symbol)
data, placing at (@)	ARMVFPV2 (predefined symbol)
language support for	ARMVFPV3 (predefined symbol)
placing data in registers (@)	ARMVFPV4 (predefined symbol)
#pragma location	ARMVFP_D6 (predefined symbol)
-aeabi (compiler option)	ARMVFP_FP16 (predefined symbol)366
_AEABI_PORTABILITY_LEVEL (preprocessor	ARMVFP_SP (predefined symbol)
symbol)	ARM_ADVANCED_SIMD (predefined symbol) 366
_AEABI_PORTABLE (preprocessor symbol)	ARM_MEDIA (predefined symbol)
algorithm (STL header file)	ARM_PROFILE_M (predefined symbol)366
alignment	ARM4M (predefined symbol)
forcing stricter (#pragma data_alignment)308	ARM4TM (predefined symbol)
in structures (#pragma pack)	ARM5 (predefined symbol)
in structures, causing problems	ARM5E (predefined symbol)
of an object (ALIGNOF)	ARM6 (predefined symbol)
of data types	ARM6M (predefined symbol)
restrictions for inline assembler	ARM6SM (predefined symbol)
alignment (pragma directive)	ARM7A (predefined symbol)
ALIGNOF (operator)	ARM7EM (predefined symbol)
align_sp_on_irq (compiler option)216	ARM7M (predefined symbol)
all (ielfdump option)	ARM7R (predefined symbol)
anonymous structures	arrays
anonymous symbols, creating	designated initializers in
application	implementation-defined behavior444
building, overview of	incomplete at end of structs
execution, overview of	non-lvalue
startup and termination (DLIB)	of incomplete types
(= ===),	single-value initialization

asm,asm (language extension)	baseaddr (pragma directive)
assembler code	BASE_FILE (predefined symbol)
calling from C	basic type names, using in preprocessor expressions
calling from C++	(migration_preprocessor_extensions)232
inserting inline	basic_heap (linker option)
assembler directives	basic_template_matching (pragma directive)
for call frame information	batch files
using in inline assembler code	error return codes
assembler instructions	none for building library from command line101
for software interrupts	BE8 (linker option)
inserting inline	BE32 (linker option)
assembler labels, making public (public_equ) 243	big_endian (extended keyword)
assembler language interface	big-endian (byte order)
calling convention. See assembler code	bin (ielftool option)
assembler list file, generating	binary streams
assembler output file	bit negation
assembler, inline	bitfields
asserts	data representation of
implementation-defined behavior of	hints
including in application	implementation-defined behavior445
assert.h (DLIB header file)	non-standard types in
assignment_by_bitwise_copy_allowed, symbol used	bitfields (pragma directive)307
in library	bits in a byte, implementation-defined behavior 441
atexit117	bitset (library header file)
reserving space for calls82	bold style, in this guide
atexit limit, setting up	bool (data type)276
attributes	adding support for in DLIB
object293	.bss (ELF section)
type	building_runtime (pragma directive)447
auto variables	BUILD_NUMBER (predefined symbol)367
at function entrance	Burrows-Wheeler algorithm, for packing initializers 390
programming hints for efficient code	BusFault_Handler (exception function)
using in inline assembler code	bwt, packing algorithm for initializers
auto, packing algorithm for initializers	byte order
	identifying
В	specifying (endian)
backtrace information See call frame information	

	signed and unsigned	277
	character set, implementation-defined behavior	440
C and C++ linkage	characters, implementation-defined behavior of	441
C/C++ calling convention. <i>See</i> calling convention	character-based I/O	
C header files	in DLIB	108
C language, overview	char_is_signed (compiler option)	217
call frame information	char_is_unsigned (compiler option)	218
in assembler list file	checksum	
in assembler list file (-lA)	calculation of	169
call stack	display format in C-SPY for symbol	173
callee-save registers, stored on stack	checksum (ielftool option)	423
calling convention	cinttypes (DLIB header file)	
C++, requiring C linkage	ciso646 (library header file)	
in compiler	class memory (extended EC++)	
calloc (library function)	climits (DLIB header file)	
See also heap	clocale (DLIB header file)	376
can_instantiate (pragma directive)	clock (library function)	
cassert (library header file)	implementation-defined behavior	452
cast operators	clock.c	116
in Extended EC++	close (DLIB library function)	112
missing from Embedded C++	clustering (compiler transformation)	191
casting	disabling (no_clustering)	233
of pointers and integers	CLZ (intrinsic function)	330
pointers to integers, language extension	cmain (system initialization code)	103
ccomplex (library header file)	cmath (DLIB header file)	376
cctype (DLIB header file)	CMSIS integration	176
cerrno (DLIB header file)	code	
cexit (system termination code)	ARM and Thumb, overview	57
cfenv (library header file)	interruption of execution	59
CFI (assembler directive)	code (ielfdump option)	425
cfiCommon.i (CFI header example file)	code motion (compiler transformation)	190
CFI_COMMON_ARM (CFI macro)	disabling (no_code_motion)	233
CFI_COMMON_Thumb (CFI macro)	codeseg (pragma directive)	447
CFI_NAME_BLOCK (CFI macro)	code, symbol used in library	379
cfloat (DLIB header file)	command line options	
char (data type)	part of compiler invocation syntax	201
changing default representation (char_is_signed) 217	part of linker invocation syntax	201
changing representation (-char_is_signed) 218	passing	202
implementation-defined behavior441	See also compiler options	
imprementation defined condition	See also linker options	

typographic convention	complex.h (library header file)	73
command prompt icon, in this guide27	compound literals	13
commands, iarchive.	computer style, typographic convention	26
.comment (ELF section)	config (linker option)	55
comments	config_def (linker option)	55
after preprocessor directives	configuration	
C++ style, using in C code	basic project settings	18
common block (call frame information)	low_level_init	
common subexpr elimination (compiler transformation) . 189	configuration file for linker. See linker configuration file	
disabling (no_cse)	configuration symbols	
compilation date	for file input and output	12
exact time of (TIME)	for locale	
identifying (DATE)	for printf and scanf	
compiler	in library configuration files	
environment variables	in linker configuration files	
invocation syntax	specifying for linker	
output from	consistency, module	
compiler listing, generating (-1)	const	
compiler object file	declaring objects	39
including debug information in (debug, -r)	non-top level	
output from compiler	constrange(), symbol used in library	
compiler optimization levels	construction_by_bitwise_copy_allowed, symbol used	
compiler options	in library	79
passing to compiler	constseg (pragma directive)	17
reading from file (-f)	const_cast (cast operator)	
specifying parameters	contents, of this guide	
summary	control characters,	
syntax	implementation-defined behavior	53
for creating skeleton code	conventions, used in this guide	26
instruction scheduling	copyright notice	. 2
warnings_affect_exit_code	CORE (predefined symbol)36	57
compiler platform, identifying	core	
compiler transformations	identifying36	57
compiler version number	selecting4	18
compiling	Cortex	
from the command line	special considerations for interrupt functions6	54
syntax	support for	18
complex numbers, supported in Embedded C++ 154	cos (library function)	72
complex (library header file)	cplusplus (predefined symbol)	57
£ . ( )	cpp_init_routine (linker option)	

CPU         specifying on command line for compiler         218           specifying on command line for linker         256          cpu (compiler option)         218          cpu (linker option)         256           CPU modes         48           _CPU_MODE (predefined symbol)         367          cpu_mode (compiler option)         219          create (iarchive option)         425           csetjmp (DLIB header file)         376           csignal (DLIB header file)         376           cspy_support (pragma directive)         447           CSTACK (ELF block)         405	header files.       374         language extensions       161         special function types.       65         static member variables       185         support for       33        c++ (compiler option)       219         C++ header files       374         C++ etrminology       26         C++-style comments       143        c89 (compiler option)       217
See also stack         CSTACK (section), example         165           .cstart (ELF section)         405	-D (compiler option)
cstartup (system startup code) customizing system initialization	data       alignment of
cstdbool (DLIB header file)	at absolute location
cstring (DLIB header file)	storage
ctime (DLIB header file)	data pointers       284         data types       276         floating point       282
C_INCLUDE (environment variable)	in C++
including debugging support	dataseg (pragma directive)
C++ See also Embedded C++ and Extended Embedded C++ absolute location	

debug information, including in object file	suppressing in compiler	
debug (ELF section)	suppressing in linker	258
DebugMon_Handler (exception function)	diagnostics	411
decimal point, implementation-defined behavior	iarchive	
declarations	implementation-defined behavior	
empty	iobjmanip	
in for loops	isymexport	
Kernighan & Ritchie	diagnostics_tables (compiler option)	
of functions	diagnostics_tables (linker option)	
declarations and statements, mixing	diag_default (pragma directive)	
define block (linker directive)	diag_error (compiler option)	
define overlay (linker directive)	diag_error (linker option)	
define symbol (linker directive)	no_fragments (compiler option)	
define_symbol (linker option)	no_fragments (linker option)	
define_type_info (pragma directive)447	diag_error (pragma directive)	
delete (iarchive option)	diag_remark (compiler option)	222
delete (keyword)55	diag_remark (linker option)	258
denormalized numbers. See subnormal numbers	diag_remark (pragma directive)	309
dependencies (compiler option)	diag_suppress (compiler option)	222
dependencies (linker option)	diag_suppress (linker option)	258
deque (STL header file)	diag_suppress (pragma directive)	309
destructors and interrupts, using	diag_warning (compiler option)	223
device description files, preconfigured for C-SPY34	diag_warning (linker option)	
diagnostic messages	diag_warning (pragma directive)	
classifying as compilation errors	directives	
classifying as compilation remarks	pragma	35, 305
classifying as compiler warnings	to the linker	
classifying as errors	directory, specifying as parameter	
classifying as linker warnings	disable_fiq (intrinsic function)	
classifying as linking errors	disable_interrupt (intrinsic function)	
classifying as linking remarks	disable_irq (intrinsic function)	
disabling compiler warnings	discard_unused_publics (compiler option)	
disabling linker warnings	disclaimer	
disabling wrapping of in compiler	DLIB	
disabling wrapping of in linker	configurations	,
	configuring	
enabling compiler remarks	documentation	
enabling linker remarks		
listing all used by compiler	including debug support	
listing all used by linker	reference information. See the online help system.	5/1

runtime environment	enable_hardware_workaround (compiler option)226
dlib_config (compiler option)	enable_interrupt (intrinsic function)
DLib_Defaults.h (library configuration file) 102, 107	enable_irq (intrinsic function)
DLIB_FILE_DESCRIPTOR (configuration symbol) 112	enable_multibytes (compiler option)
DMB (intrinsic function)	endian (compiler option)
do not initialize (linker directive)	entry (linker option)
document conventions	entry label, program
documentation, overview of guides	enumerations, implementation-defined behavior
domain errors, implementation-defined behavior	enums
DOUBLE (predefined symbol)	data representation
double (data type)	forward declarations of148
identifying size of (DOUBLE)367	enum_is_int (compiler option)
do_not_instantiate (pragma directive)447	environment
DSB (intrinsic function)	implementation-defined behavior
dynamic initialization	runtime (DLIB)
for C++	environment names, implementation-defined behavior441
dynamic memory	environment variables
dynamic RTTI data, including in the image265	C_INCLUDE
	ILINKARM_CMD_LINE
	QCCARM
E	environment (native)
-e (compiler option)	implementation-defined behavior
early_initialization (pragma directive)	EQU (assembler directive)
ec++ (compiler option)	ERANGE
edit (isymexport option)	errno value at underflow.
	implementation-defined behavior
edition, of this guide	errno.h (library header file)373
eec++ (compiler option)	error messages
ELF utilities	classifying
Embedded C++	classifying for compiler
differences from C++	classifying for linker
enabling	range
function linkage	error return codes
language extensions	error (pragma directive)
overview	
Embedded C++ Technical Committee	error_limit (compiler option)
embedded systems, IAR special support for	error_limit (linker option)
embedded_cplusplus (predefined symbol) 367	escape sequences, implementation-defined behavior 441
empty region (in linker configuration file)	exception flags, for floating-point values
enable_fiq (intrinsic function)331	exception handling, missing from Embedded C++ 153
	exception stacks

exception (library header file)	fatal error messages
exceptions, code for in section	fdopen, in stdio.h
exception_tables (linker option)260	fegettrapdisable377
.exc.text (ELF section)	fegettrapenable
_Exit (library function)	FENV_ACCESS, implementation-defined behavior 444
exit (library function)	fenv.h (library header file)
implementation-defined behavior	additional C functionality377
_exit (library function)	fgetpos (library function), implementation-defined
exit (library function)	behavior
export keyword, missing from Extended EC++ 160	FILE (predefined symbol)
export (linker directive)	file buffering, implementation-defined behavior449
export_builtin_config (linker option)	file dependencies, tracking
expressions (in linker configuration file)399	file paths, specifying for #include files
extended command line file	file position, implementation-defined behavior449
for compiler	file (zero-length), implementation-defined behavior 449
for linker	filename
passing options	extension for device description files
Extended Embedded C++	extension for header files
enabling	of object executable image
extended keywords	search procedure for
enabling (-e)	specifying as parameter
overview	filenames (legal), implementation-defined behavior 450
summary	fileno, in stdio.h
•	files, implementation-defined behavior
syntax object attributes293	handling of temporary
type attributes on data objects	multibyte characters in
type attributes on data pointers	opening
type attributes on functions	fill (ielftool option)
extended-selectors (in linker configuration file)	fiq (extended keyword)
extern "C" linkage	FIQ_Handler (exception function)
<u> </u>	float (data type)
extract (iarchive option)	floating-point constants
extra_init (linker option)	hexadecimal notation
_	hints
F	
	floating-point environment, accessing or not
-f (compiler option)	floating-point expressions
-f (iobjmanip option)	contracting or not
-f (linker option)	using in preprocessor extensions
fast interrupts61	floating-point format
	hints

implementation-defined behavior
special cases
32-bits
64-bits
floating-point status flags
floating-point unit
float.h (library header file)
FLT_EVAL_METHOD, implementation-defined
behavior
FLT_ROUNDS, implementation-defined
behavior
for loops, declarations in
force_exceptions (linker option)261
force_output (linker option)
formats
floating-point values
standard IEEE (floating point)
fpu (compiler option)
FP_CONTRACT, implementation-defined behavior 444
fragmentation, of heap memory55
free (library function). See also heap55
fsetpos (library function), implementation-defined
behavior
fstream (library header file)
ftell (library function), implementation-defined behavior . 451
Full DLIB (library configuration)
func (predefined symbol)
FUNCTION (predefined symbol) 150, 368
function calls
calling convention
stack image after
function declarations, Kernighan & Ritchie
function execution, in RAM
function inlining (compiler transformation)
disabling (no_inline)
function pointers
function prototypes
enforcing
function (pragma directive)
functional (STL header file)

functions
C++ and special function types
declaring
inlining
interrupt59
intrinsic
parameters
placing in memory
recursive
avoiding
storing data on stack
reentrancy (DLIB)
related extensions
return values from
special function types
G
getenv (library function), configuring support for 115
getw, in stdio.h
getzone (library function), configuring support for 116
getzone.c
get_BASEPRI (intrinsic function)
get_CONTROL (intrinsic function)
get_CPSR (intrinsic function)
get_FAULTMASK (intrinsic function)
get_interrupt_state (intrinsic function)
get_IPSR (intrinsic function)
get_LR (intrinsic function)
get_MSP (intrinsic function)
get_PRIMASK (intrinsic function)
get_PSP (intrinsic function)
get_PSR (intrinsic function)
get_SB (intrinsic function)
get_SP (intrinsic function)
GRP_COMDAT, group type
guard_calls (compiler option)
guidelines, reading

ш	iarbuild.exe (utility)
П	iarchive
Harbison, Samuel P	commands summary
HardFault_Handler (exception function)	options summary
hardware support in compiler	iar_cos_accuratef (library function)
hash_map (STL header file)	iar_cos_accuratel (library function)
hash_set (STL header file)	iar_pow_accuratef (library function)372
_has_constructor, symbol used in library	iar_pow_accuratel (library function)372
has_destructor, symbol used in library	iar_program_start (label)
hdrstop (pragma directive)	iar_ReportAssert (library function)11
header files	iar_sin_accuratef (library function)372
C	iar_sin_accuratel (library function)372
C++	IAR_SYSTEMS_ICC (predefined symbol) 368
library	iar_tan_accuratef (library function)
special function registers	iar_tan_accuratel (library function)372
DLib_Defaults.h	iar.debug (ELF section)
including stdbool.h for bool	.iar.dynexit (ELF section)
including stddef.h for wchar_t	IA64 ABI
header names, implementation-defined behavior	ICCARM (predefined symbol)
header_context (compiler option)	icons, in this guide
	IDE
heap dynamic memory	building a library from
•	overview of build tools
storing data	identifiers, implementation-defined behavior
heap size	IEEE format, floating-point values
and standard I/O	ielfdump
HEAP (section)	options summary
heap (zero-sized), implementation-defined behavior 451	ielftool
• •	options summary
hide (isymexport directive)	if (linker directive)
hints	ihex (ielftool option)
for good code generation	ILINK options. See linker options
implementation-defined behavior	ILINKARM_CMD_LINE (environment variable) 203
using efficient data types	ILINK. See linker
-	image_input (linker option)
	implementation-defined behavior
- 	important_typedef (pragma directive)
-I (compiler option)	include files
IAR Command Line Build Utility101	including before source files
IAR Systems Technical Support	merading octore source mes

specifying	interrupt functions	59
include (linker directive)	fast interrupts	
include_alias (pragma directive)	in ARM Cortex	
infinity	nested interrupts	
infinity (style for printing), implementation-defined	operations	
behavior	software interrupts	
inheritance, in Embedded C++	interrupt state, restoring	
initialization	interrupt vector table	
changing default82	.intvec section	
C++ dynamic	interrupts	
dynamic	processor state	54
manual	using with EC++ destructors	
packing algorithm for	interwork (extended keyword)	
single-value		
initialize (linker directive)	interwork (compiler option)	
	interworking code	
initializers, static	intptr_t (integer type)	
.init_array (section)	intrinsic (extended keyword)	
inline (linker option)	intrinsic functions	
inline assembler	for Neon	
avoiding	overview	
See also assembler language interface	summary	
inline functions	intrinsics.h (header file)	
in compiler190	inttypes.h (library header file)	374
inline (pragma directive)311	.intvec (section)	406
inlining functions, implementation-defined behavior 445	invocation syntax	201
installation directory	iobjmanip	415
instantiate (pragma directive)	options summary	416
instruction scheduling (compiler option)	iomanip (library header file)	374
int (data type) signed and unsigned277	ios (library header file)	374
integer types	iosfwd (library header file)	375
casting	iostream (library header file)	375
implementation-defined behavior	irq (extended keyword)	
intptr_t285	IRQ_Handler (exception function)	
ptrdiff_t	IRQ_STACK (section)	
size_t	ISB (intrinsic function)	
uintptr_t	iso646.h (library header file)	
integral promotion	istream (library header file)	
Intel hex	isymexport	
Intel IA64 ABI	options summary	
internal error 208	options summary	

italic style, in this guide	LDC2L_noidx (intrinsic function)
iterator (STL header file)	LDC2_noidx (intrinsic function)
	LDREX (intrinsic function)
	legacy (compiler option)
J	Lempel-Ziv-Welch algorithm, for packing initializers 390
Josuttis, Nicolai M	libraries, using a prebuilt91
	library configuration files
<b>I</b> /	DLIB
K	DLib_Defaults.h
keep (linker option)	modifying
keep (linker directive)	specifying224
• '	library documentation
keep_definition (pragma directive)	library features, missing from Embedded C++ 154
Kernighan & Ritchie function declarations	library files, linker search path to (search)
disallowing	library functions
Kernighan, Brian W	summary, DLIB
keywords	library header files
extended, overview of	library modules
_	introduction
L	overriding
	library object files
-l (compiler option)	library options, setting
for creating skeleton code	library project template
labels	using
assembler, making public243	library_default_requirements (pragma directive)
iar_program_start103	library_provides (pragma directive)
Labrosse, Jean J	library_requirement_override (pragma directive)
Lajoie, Josée	lightbulb icon, in this guide
language extensions	limits (library header file)
Embedded C++	limits.h (library header file)
enabling using pragma312	LINE (predefined symbol)
enabling (-e)	linkage, C and C++
language overview	linker
language (pragma directive)	
LDC (intrinsic function)	output from
LDCL (intrinsic function)	linker configuration file
LDCL_noidx (intrinsic function)	for placing code and data
LDC_noidx (intrinsic function)	in depth
LDC2 (intrinsic function)	overview of
I DC2L (intrinsic function) 335	selecting77

linker object executable image
specifying filename of (-o)
linker options
reading from file (-f)
summary
typographic convention
linking
from the command line
introduction
process for
Lippman, Stanley B
list (STL header file)
listing, generating
literals, compound143
literature, recommended
LITTLE_ENDIAN (predefined symbol)368
little_endian (extended keyword)297
little-endian (byte order)
local variables, See auto variables
locale
adding support for in library
changing at runtime
implementation-defined behavior
library header file
removing support for
support for
locale.h (library header file)
located data, declaring extern
location (pragma directive)
lock_regs (compiler option)
log (linker option)
log_file (linker option)
long double (data type)
long float (data type), synonym for double
longjmp, restrictions for using
loop unrolling (compiler transformation)
disabling
loop-invariant expressions
low_level_init
customizing

low_level_init.c	103
low_level_init.s	
low-level processor operations	
accessing	125
lseek (library function)	
lzw, packing algorithm for initializers	390
M	
-map (linker option)	265
macros	
embedded in #pragma optimize	315
ERANGE (in errno.h)	448
inclusion of assert	369
NULL, implementation-defined behavior	449
substituted in #pragma directives	145
variadic	143
macro_positions_in_diagnostics (compiler optio	n)232
main (function), implementation-defined behavior	440
malloc (library function)	
See also heap	55
$mangled\_names\_in\_messages \ (linker \ option) \ \ . \ .$	264
Mann, Bernhard	25
map file, producing	
map (STL header file)	375
math functions rounding mode,	
implementation-defined behavior	
math.h (library header file)	
MB_LEN_MAX, implementation-defined behavior	
MCR (intrinsic function)	
memattr_HEAP (ELF section)	
$MemManage\_Handler \ (exception \ function) \ . \ . \ . \ .$	64
memory	
allocating in C++	
dynamic	
heap	
non-initialized	
RAM, saving	
releasing in C++	55

stack54
saving
used by global or static variables
memory layout, ARM53
memory management, type-safe
memory map, output from linker
memory (pragma directive)447
memory (STL header file)375
memory_of, symbol used in library379
message (pragma directive)
messages
disabling
forcing
Meyers, Scott
mfc (compiler option)
migration_preprocessor_extensions (compiler option) 232
migration, from earlier IAR compilers
MISRA C, documentation
misrac (compiler option)
misrac_verbose (compiler option)
misrac_verbose (linker option)
misrac1998 (compiler option)
misrac1998 (linker option)
misrac2004 (compiler option)
misrac2004 (linker option)
mode changing, implementation-defined behavior 450
module consistency
rtmodel317
modules, introduction
module_name (pragma directive)
Motorola S-records
MRC (intrinsic function)
multibyte character support226
multibyte characters, implementation-defined
behavior
multiple inheritance
in Extended EC++
missing from Embedded C++
missing from STL
multi-file compilation

mutable attribute, in Extended EC++	54, 161
N	
names block (call frame information)	139
namespace support	
in Extended EC++	54, 161
missing from Embedded C++	154
naming conventions	27
NaN	
implementation of	283
implementation-defined behavior	450
native environment	
implementation-defined behavior	453
NDEBUG (preprocessor symbol)	369
Neon intrinsic functions	329
nested (extended keyword)	297
nested interrupts	61
new (keyword)	55
new (library header file)	375
NMI_Handler (exception function)	64
.noinit (ELF section)	407
non-initialized variables, hints for	196
non-scalar parameters, avoiding	193
NOP (assembler instruction)	337
noreturn (extended keyword)	298
Normal DLIB (library configuration)	107
Not a number (NaN)	283
no_clustering (compiler option)	233
no_code_motion (compiler option)	233
no_const_align (compiler option)	233
no_cse (compiler option)	
no_dynamic_rtti_elimination (linker option)	
no_exceptions (compiler option)	234
no_exceptions (linker option)	
no_init (extended keyword)	
no_inline (compiler option)	
no_library_search (linker option)	
no_locals (linker option)	267

no_loop_align (compiler option)	object files, linker search path to (search)	271
no_mem_idioms (compiler option)	object_attribute (pragma directive)	
no_operation (intrinsic function)	once (pragma directive)	447
no_path_in_file_macros (compiler option) 236	only_stdout (compiler option)	241
no_pch (pragma directive)	only_stdout (linker option)	
no_range_reservations (linker option)	open (library function)	
no_remove (linker option)	operators	
no_rtti (compiler option)	See also @ (operator)	
no_rw_dynamic_init (compiler option)	for cast	
no_scheduling (compiler option)	in Extended EC++	154
no_static_destruction (compiler option)237	missing from Embedded C++	
no_strtab (ielfdump option)	for region expressions	
no_system_include (compiler option)	for section control	
no_tbaa (compiler option)	in inline assembler	
no_typedefs_in_diagnostics (compiler option)238	precision for 32-bit float	
no_unaligned_access (compiler option)	precision for 64-bit float	
no_unroll (compiler option)	sizeof, implementation-defined behavior	
no_veneer (linker option)	variants for cast	
no_vfe (compiler option)	_Pragma (preprocessor)	
no_warnings (compiler option)	ALIGNOF, for alignment control	
no_warnings (linker option)	?, language extensions for	
no_wrap_diagnostics (compiler option)	optimization	
no_wrap_diagnostics (linker option)	clustering, disabling	233
NULL	code motion, disabling	
implementation-defined behavior	common sub-expression elimination, disabling.	
pointer constant, relaxation to Standard C	configuration	
numbers (in linker configuration file)	disabling	
numeric conversion functions,	function inlining, disabling (no_inline)	
implementation-defined behavior	hints	
numeric (STL header file)	loop unrolling, disabling	
,	scheduling, disabling	
lack	specifying (-O).	
O	techniques	
-O (compiler option)	type-based alias analysis, disabling (tbaa)	
-o (compiler option)	using inline assembler code	
-o (iarchive option)	using pragma directive	
-o (ielfdump option)	optimization levels	
-o (linker option)	optimize (pragma directive)	
object attributes	option parameters	
00ject attitoates	opaca parameters	207

options, compiler. See compiler options	PKHBT (intrinsic function)
options, iarchive. See iarchive options	PKHTB (intrinsic function)
options, ielfdump. See ielfdump options	place at (linker directive)
options, ielftool. See ielftool options	place in (linker directive)
options, iobjmanip. See iobjmanip options	placement
options, isymexport. See isymexport options	code and data
options, linker. See linker options	in named sections
Oram, Andy	of code and data, introduction to
ostream (library header file)	place_holder (linker option)
output	plain char, implementation-defined behavior
from preprocessor	pointer types
specifying for linker	mixing
-output (compiler option)	pointers
-output (iarchive option)	casting
-output (ielfdump option)	data
-output (linker option)	function
overhead, reducing	implementation-defined behavior
,	polymorphic RTTI data, including in the image 265
D	polymorphism, in Embedded C++
	porting, code containing pragma directives306
pack (pragma directive)	pow (library function)
packbits, packing algorithm for initializers390	alternative implementation of
_packed (extended keyword)298	powXp (library function)
packed structure types	pragma directives
packing, algorithms for initializers	summary
parameters	for absolute located data
function	list of all recognized
hidden	pack
non-scalar, avoiding	_Pragma (preprocessor operator)
register	predefined symbols
rules for specifying a file or directory	overview
specifying	summary
stack	predef_macro (compiler option)241
typographic convention	Prefetch_Handler (exception function)
part number, of this guide	preinclude (compiler option)
_pcrel (extended keyword)	.preinit_array (section)
PendSV_Handler (exception function)	.prepreinit_array (section)
permanent registers	preprocess (compiler option)
-pi_veneer (linker option)	

preprocessor	public_equ (pragma directive)
operator (_Pragma)	putenv (library function), absent from DLIB115
output242	putw, in stdio.h
overview of	
preprocessor directives	
comments at the end of149	Q
implementation-defined behavior446	QADD (intrinsic function)
#pragma305	QADD8 (intrinsic function)
preprocessor extensions	QADD16 (intrinsic function)
compatibility	QASX (intrinsic function)
VA_ARGS	QCCARM (environment variable)
#warning message	QCFlag (intrinsic function)
preprocessor symbols	QDADD (intrinsic function)
defining	_QDOUBLE (intrinsic function)340
preserved registers	QDSUB (intrinsic function)
PRETTY_FUNCTION (predefined symbol) 368	QFlag (intrinsic function)
primitives, for special functions	_QSAX (intrinsic function)340
print formatter, selecting96	QSUB (intrinsic function)341
printf (library function)95	_QSUB8 (intrinsic function)
choosing formatter95	_QSUB16 (intrinsic function)
configuration symbols	qualifiers
implementation-defined behavior	const and volatile
printf_args (pragma directive)316	implementation-defined behavior
printing characters, implementation-defined behavior 453	queue (STL header file)
processor configuration	1
processor operations	D
accessing	R
low-level	-r (compiler option)
program entry label	-r (iarchive option)
program termination, implementation-defined behavior 440	raise (library function), configuring support for
programming hints	raise.c
projects	RAM
basic settings for	example of declaring region
setting up for a library	execution
prototypes, enforcing	initializers copied from ROM
ptrdiff_t (integer type)285	running code from
PUBLIC (assembler directive)	saving memory
publication date, of this guide2	ramfunc (extended keyword)
public_equ (compiler option)	ram_reserve_ranges (isymexport option)

range errors86	remarks (linker option)	271
raw (ielfdump option)	remove (library function)	112
read (library function)112	implementation-defined behavior	450
customizing	remove_section (iobjmanip option)	430
read formatter, selecting	remquo, magnitude of	448
reading guidelines	rename (isymexport directive)	420
reading, recommended	rename (library function)	112
realloc (library function)55	implementation-defined behavior	450
See also heap	rename_section (iobjmanip option)	431
recursive functions	rename_symbol (iobjmanip option)	431
avoiding	replace (iarchive option)	432
storing data on stack54	required (pragma directive)	
redirect (linker option)	require_prototypes (compiler option)	
reentrancy (DLIB)	reserve_ranges (isymexport option)	
reference information, typographic convention26	reset_QC_flag (intrinsic function)	
region	reset_Q_flag (intrinsic function)	
region expression (in linker configuration file)	return values, from functions	
region literal (in linker configuration file)383	REV (intrinsic function)	342
register keyword, implementation-defined behavior 444	REVSH (intrinsic function)	
register parameters	Ritchie, Dennis M	
registered trademarks	.rodata (ELF section)	408
registers	ROM to RAM, copying	
assigning to parameters	root (extended keyword)	
callee-save, stored on stack	ROPI (predefined symbol)	
in assembler-level routines	ropi (compiler option)	
preserved	routines, time-critical	
scratch	rtmodel (assembler directive)	
reinterpret_cast (cast operator)	rtmodel (pragma directive)	317
.rel (ELF section)	RTTI data (dynamic), including in the image	
rela (ELF section)	rtti support, missing from STL	
relaxed_fp (compiler option)	runtime environment	
relay, see veneers	DLIB	. 89
relocation errors, resolving	setting options for	
remark (diagnostic message)	setting up (DLIB)	
classifying for compiler	runtime libraries (DLIB)	
classifying for linker	introduction	371
enabling in compiler	customizing system startup code	
enabling in linker	customizing without rebuilding	
remarks (compiler option)	filename syntax	

overriding modules in	segment (pragma directive)318
setting up from command line	SEL (intrinsic function)
setting up from IDE50	semihosting (linker option)
using a prebuilt91	semihosting, overview98
runtime model attributes	separate_cluster_for_initialized_variables
runtime model definitions	(compiler option)246
runtime type information, missing from Embedded C++ . 154	set (STL header file)
rwpi (compiler option)	setjmp.h (library header file)374
	setlocale (library function)
C	settings, basic for project configuration
S	set_BASEPRI (intrinsic function)343
-S (iarchive option)	set_CONTROL (intrinsic function)
-s (ielfdump option)	set_CPSR (intrinsic function)
SADD8 (intrinsic function)	set_FAULTMASK (intrinsic function)
SADD16 (intrinsic function)	set_interrupt_state (intrinsic function)
SASX (intrinsic function)	set_LR (intrinsic function)
sbrel (extended keyword)	set_MSP (intrinsic function)344
scanf (library function)	set_PRIMASK (intrinsic function)
choosing formatter (DLIB)96	set_PSP (intrinsic function)
configuration symbols	set_SB (intrinsic function)
implementation-defined behavior	set_SP (intrinsic function)
scanf_args (pragma directive)	severity level, of diagnostic messages
scheduling (compiler transformation)191	specifying
disabling	SFR
scratch registers	accessing special function registers
search (linker option)	declaring extern special function registers 184
search path to library files (search)	SHADD8 (intrinsic function)
search path to object files (search)	SHADD16 (intrinsic function)
section (ielfdump option)	shared object
sections	SHASX (intrinsic function)
summary	short (data type)
allocation of	show (isymexport directive)
declaring (#pragma section)318	SHSAX (intrinsic function)
introduction	.shstrtab (ELF section)
specifying (section)245	SHSUB8 (intrinsic function)346
section_begin (extended operator)	SHSUB16 (intrinsic function)346
section_end (extended operator)	signal (library function)
section_size (extended operator)147	configuring support for116
section-selectors (in linker configuration file)395	implementation-defined behavior449

signals, implementation-defined behavior440	SMLAWT (intrinsic function)	350
at system startup440	SMLSD (intrinsic function)	350
signal.c	SMLSDX (intrinsic function)	350
signal.h (library header file)	SMLSLD (intrinsic function)	350
signed char (data type)	SMLSLDX (intrinsic function)	351
specifying	SMMLA (intrinsic function)	351
signed int (data type)	SMMLAR (intrinsic function)	351
signed long long (data type)	SMMLS (intrinsic function)	
signed long (data type)	SMMLSR (intrinsic function)	352
signed short (data type)277	SMMUL (intrinsic function)	352
silent (compiler option)	SMMULR (intrinsic function)	352
silent (iarchive option)	SMUAD (intrinsic function)	
silent (ielftool option)	SMUADX (intrinsic function)	
silent (linker option)272	SMUL (intrinsic function)	
silent operation	SMULBB (intrinsic function)	
specifying in compiler	SMULBT (intrinsic function)	
specifying in linker	SMULTB (intrinsic function)	
simple (ielftool option)	SMULTT (intrinsic function)	
sin (library function)	SMULWB (intrinsic function)	354
64-bits (floating-point format)	SMULWT (intrinsic function)	
sizeof, using in preprocessor extensions	SMUSD (intrinsic function)	
size_t (integer type)	SMUSDX (intrinsic function)	
skeleton code, creating for assembler language interface . 129	software interrupts	
skeleton.s (assembler source output)	source files, list all referred	
slist (STL header file)	space characters, implementation-defined behavior	449
smallest, packing algorithm for initializers	special function registers (SFR)	195
SMLABB (intrinsic function)	special function types	59
SMLABT (intrinsic function)	overview	
SMLAD (intrinsic function)	sprintf (library function)	95
SMLADX (intrinsic function)	choosing formatter	
SMLALBB (intrinsic function)	srec (ielftool option)	434
SMLALBT (intrinsic function)	srec-len (ielftool option)	
SMLALD (intrinsic function)	srec-s3only (ielftool option)	435
SMLALDX (intrinsic function)	SSAT (intrinsic function)	355
SMLALTB (intrinsic function)	SSAT16 (intrinsic function)	355
SMLALTT (intrinsic function)	SSAX (intrinsic function)	
SMLATB (intrinsic function)	sscanf (library function), choosing formatter (DLIB) .	
SMLATT (intrinsic function)	sstream (library header file)	
SMLAWB (intrinsic function)	SSUB8 (intrinsic function)	

SSUB16 (intrinsic function)	STC2L (intrinsic function)
stack	STC2L_noidx (intrinsic function)
advantages and problems using	STC2_noidx (intrinsic function)
cleaning after function return	std namespace, missing from EC++
contents of	and Extended EC++
exception	stdarg.h (library header file)
internal data	stdbool.h (library header file)
layout	_STDC (predefined symbol)
saving space	STDC CX_LIMITED_RANGE (pragma directive) 319
size	STDC FENV_ACCESS (pragma directive)
stack parameters	STDC FP_CONTRACT (pragma directive)
	_STDC_VERSION (predefined symbol)
stack pointer	stddef.h (library header file)
stack (STL header file)	stdern (nordly header life)
stackless (extended keyword)	stderrent (library header file)
Standard C	stdin
library compliance with	stdint.h (library header file)
specifying strict usage	stdint.ii (library header file)
standard error	stdio.h (horary header me)
redirecting in compiler	· · · · · · · · · · · · · · · · · · ·
redirecting in linker	stdlib.h (library header file)
standard input	stdout
standard output	implementation-defined behavior
specifying in compiler	Steele, Guy L
specifying in linker	steering file, input to isymexport
standard template library (STL)	STL
in Extended EC++	strcasecmp, in string.h
missing from Embedded C++	strdup, in string.h
startup system. See system startup	streambuf (library header file)
static clustering (compiler transformation)	streams
static variables	implementation-defined behavior
taking the address of	supported in Embedded C++
static_assert()	strerror (library function), implementation-defined
static_cast (cast operator)	behavior
status flags for floating-point	STREX (intrinsic function)
STC (intrinsic function)	strict (compiler option)
STCL (intrinsic function)	string (library header file)
STCL_noidx (intrinsic function)	strings, supported in Embedded C++
STC_noidx (intrinsic function)	string.h (library header file)
STC2 (intrinsic function)	string.h, additional C functionality
	strip (ielftool option)

strip (iobjmanip option)	symbols (iarchive option)
strip (linker option)	.symtab (ELF section)
strncasecmp, in string.h	syntax
strnlen, in string.h	command line options
Stroustrup, Bjarne25	extended keywords
strstream (library header file)	invoking compiler and linker
strtab (ielfdump option)	system function, implementation-defined behavior 441, 451
.strtab (ELF section)	system startup
structure types	customizing
alignment	DLIB
layout of	initialization phase
packed	system termination
structures	C-SPY interface to
aligning	DLIB
anonymous146, 181	system (library function), configuring support for 115
implementation-defined behavior	system_include (pragma directive)
packing and unpacking181	system_include_dir (compiler option)
subnormal numbers	SysTick_Handler (exception function)
support, technical	•
Sutter, Herb	T
SVC #immed, for software interrupts	
SVC_Handler (exception function)64	-t (iarchive option)
swi (extended keyword)	tan (library function)
SWI_Handler (exception function)	_task (extended keyword)
swi_number (pragma directive)	technical support, IAR Systems
SWO, directing stdout/stderr via97	template support
SWP (intrinsic function)	in Extended EC++
SWPB (intrinsic function)	missing from Embedded C++
SXTAB (intrinsic function)	Terminal I/O window
SXTAB16 (intrinsic function)	making available (DLIB)
SXTAH (intrinsic function)	not supported when
SXTB16 (intrinsic function)	terminal I/O, debugger runtime interface for
symbol names, using in preprocessor extensions 232	terminal output, speeding up
symbols	termination of system. See system termination
anonymous, creating	termination of system. See system termination termination status, implementation-defined behavior 451
directing from one to another	terminology
including in output	text (ELF section)
overview of predefined	tgmath.h (library header file)
preprocessor, defining	32-bits (floating-point format)
rr25501, dollars	52-ons (noaning-point format)

this (pointer)	UASX (intrinsic function)	359
thumb (extended keyword)	uchar.h (library header file)	374
thumb (compiler option)	UHADD8 (intrinsic function)	359
Thumb, CPU mode	UHADD16 (intrinsic function)	359
TIME (predefined symbol)	UHASX (intrinsic function)	359
time zone (library function), implementation-defined	UHSAX (intrinsic function)	360
behavior	UHSUB8 (intrinsic function)	360
time-critical routines	UHSUB16 (intrinsic function)	
time.c	uintptr_t (integer type)	285
time.h (library header file)	UMAAL (intrinsic function)	
time.h, additional C functionality	Undefined_Handler (exception function)	
time32 (library function), configuring support for 116	underflow errors, implementation-defined behavior	
time64 (library function), configuring support for 116	ungetchar, in stdio.h	
tips, programming	unions	
toc (iarchive option)	anonymous14	6. 181
tools icon, in this guide27	implementation-defined behavior	
trademarks2	universal character names, implementation-defined	
transformations, compiler	behavior	446
translation, implementation-defined behavior	unsigned char (data type)	
type attributes	changing to signed char	
specifying	unsigned int (data type)	
type qualifiers	unsigned long long (data type)	
const and volatile	unsigned long (data type)	
implementation-defined behavior	unsigned short (data type)	
typedefs	UQADD8 (intrinsic function)	
excluding from diagnostics	UQADD16 (intrinsic function)	
repeated	UQASX (intrinsic function)	
using in preprocessor extensions	UQSAX (intrinsic function)	
typeinfo (library header file)	UQSUB8 (intrinsic function)	
type_attribute (pragma directive)	UQSUB16 (intrinsic function)	
type-based alias analysis (compiler transformation) 190	USADA8 (intrinsic function)	
disabling	USAD8 (intrinsic function)	
type-safe memory management	UsageFault_Handler (exception function)	
typographic conventions	USAT (intrinsic function)	
eypograpme conventions.	USAT16 (intrinsic function)	
1 1	USAX (intrinsic function)	
U	use_c++_inline (compiler option)	
UADD8 (intrinsic function)	use_unix_directory_separators (compiler option)	
UADD16 (intrinsic function)	USUB8 (intrinsic function)	
	USUB16 (intrinsic function)	

utilities (ELF)       409         utility (STL header file)       376         _UXTAB (intrinsic function)       363         _UXTAB16 (intrinsic function)       364         _UXTAH (intrinsic function)       364         _UXTB16 (intrinsic function)       364	volatile and const, declaring objects
V	#warning message (preprocessor extension)
-V (iarchive option)	warnings
valaway (library header file)	classifying in compiler223
variables	classifying in linker
auto	disabling in compiler
defined inside a function	disabling in linker269
global, placement in memory53	exit code in compiler
hints for choosing	exit code in linker
local. See auto variables	warnings icon, in this guide27
non-initialized	warnings (pragma directive)
placing at absolute addresses	warnings_affect_exit_code (compiler option) 205, 249
placing in named sections	warnings_affect_exit_code (linker option)273
static	warnings_are_errors (compiler option)
placement in memory	warnings_are_errors (linker option)
taking the address of	wchar_t (data type), adding support for in C278
variadic macros147	wchar.h (library header file)
vector floating-point unit	wctype.h (library header file)
vector (pragma directive)	weak (extended keyword)302
vector (STL header file)	weak (pragma directive)
vector_table, array holding vector table64	web sites, recommended
veneers	white-space characters, implementation-defined behavior 439
VER (predefined symbol)	write (library function)
verbose (iarchive option)	customizing
verbose (ielftool option)	write_array, in stdio.h
version number	write_buffered (DLIB library function)
of compiler	<b>3.7</b>
of this guide	X
vfe (compiler option)	
VFP	-x (iarchive option)
vla (compiler option)	xreportassert.c117
void, pointers to	

7	assignment_by_bitwise_copy_allowed, symbol used
	in library
zeros, packing algorithm for initializers	BASE_FILE (predefined symbol)
	big_endian (extended keyword)
Symbols	BUILD_NUMBER (predefined symbol)
Syllibols	close (library function)
_AEABI_PORTABILITY_LEVEL (preprocessor	CLZ (intrinsic function)
symbol)	code, symbol used in library
_AEABI_PORTABLE (preprocessor symbol) 176	constrange(), symbol used in library
_Exit (library function)	construction_by_bitwise_copy_allowed, symbol used
_exit (library function)	in library
AAPCS_VFP (predefined symbol)	CORE (predefined symbol)
AAPCS (predefined symbol)	cplusplus (predefined symbol)
_absolute (extended keyword)	CPU_MODE (predefined symbol)
ALIGNOF (operator)	data, symbol used in library
arm (extended keyword)	DATE (predefined symbol)
ARMVFPV2 (predefined symbol)	disable_fiq (intrinsic function)
ARMVFPV3 (predefined symbol)	disable_interrupt (intrinsic function)330
ARMVFPV4 (predefined symbol)	disable_irq (intrinsic function)
ARMVFP_D6 (predefined symbol)	DLIB_FILE_DESCRIPTOR (configuration symbol) 112
ARMVFP_FP16 (predefined symbol)366	DLIB_PERTHREAD (ELF section)
ARMVFP_SP (predefined symbol)	DMB (intrinsic function)
ARMVFP (predefined symbol)	DOUBLE (predefined symbol)
ARM_ADVANCED_SIMD (predefined symbol) 366	DSB (intrinsic function)
ARM_MEDIA (predefined symbol)	embedded_cplusplus (predefined symbol)
ARM_PROFILE_M (predefined symbol)366	enable_fiq (intrinsic function)
ARM4M (predefined symbol)	enable_interrupt (intrinsic function)
ARM4TM (predefined symbol)	enable_irq (intrinsic function)
ARM5E (predefined symbol)	exit (library function)
ARM5 (predefined symbol)	FILE (predefined symbol)367
ARM6M (predefined symbol)	fiq (extended keyword)
ARM6SM (predefined symbol)	FUNCTION (predefined symbol)
ARM6 (predefined symbol)	func (predefined symbol)
ARM7A (predefined symbol)	gets, in stdio.h
ARM7EM (predefined symbol)	get_BASEPRI (intrinsic function)
ARM7M (predefined symbol)	get_CONTROL (intrinsic function)
ARM7R (predefined symbol)	get_CPSR (intrinsic function)332
_asm (language extension)	get_FAULTMASK (intrinsic function)
	get_interrupt_state (intrinsic function)
	get IPSR (intrinsic function)

get_LR (intrinsic function)	no_init (extended keyword)
get_MSP (intrinsic function)334	no_operation (intrinsic function)
get_PRIMASK (intrinsic function)334	open (library function)
get_PSP (intrinsic function)	packed (extended keyword)
get_PSR (intrinsic function)	pcrel (extended keyword)
get_SB (intrinsic function)	PKHBT (intrinsic function)
get_SP (intrinsic function)	PKHTB (intrinsic function)
_has_constructor, symbol used in library	PRETTY_FUNCTION (predefined symbol) 368
has_destructor, symbol used in library	printf_args (pragma directive)
iar_maximum_atexit_calls	QADD (intrinsic function)
iar_program_start (label)	_QADD8 (intrinsic function)
iar_ReportAssert (library function)117	_QADD16 (intrinsic function)
IAR_SYSTEMS_ICC (predefined symbol) 368	QASX (intrinsic function)
ICCARM (predefined symbol)	QCFlag (intrinsic function)
interwork (extended keyword)	_QDADD (intrinsic function)
intrinsic (extended keyword)294, 296	QDOUBLE (intrinsic function)
irq (extended keyword)297	QDSUB (intrinsic function)
ISB (intrinsic function)	QFlag (intrinsic function)
LDC (intrinsic function)	QSAX (intrinsic function)
LDCL (intrinsic function)	QSUB (intrinsic function)
LDCL_noidx (intrinsic function)	QSUB8 (intrinsic function)
LDC_noidx (intrinsic function)	QSUB16 (intrinsic function)
LDC2 (intrinsic function)	ramfunc (extended keyword)
LDC2L (intrinsic function)	executing in RAM
LDC2L_noidx (intrinsic function)	read (library function)
LDC2_noidx (intrinsic function)	customizing
LDREX (intrinsic function)	reset_QC_flag (intrinsic function)
LINE (predefined symbol)	reset_Q_flag (intrinsic function)
little_endian (extended keyword)	REV (intrinsic function)
LITTLE_ENDIAN (predefined symbol)368	REVSH (intrinsic function)
low_level_init	_root (extended keyword)
initialization phase	ROPI (predefined symbol)
_low_level_init, customizing	SADD8 (intrinsic function)
lseek (library function)	SADD16 (intrinsic function)
MCR (intrinsic function)	SASX (intrinsic function)
memory_of, symbol used in library	sbrel (extended keyword)
MRC (intrinsic function)	scanf_args (pragma directive)
nested (extended keyword)	section_begin (extended operator)
noreturn (extended keyword) 208	section and (extended operator) 147

section size (extended energter) 147	SMMLS (intrinsic function)	251
section_size (extended operator)	SMMLS (intrinsic function)	
SEL (intrinsic function)	SMMUL (intrinsic function)	
set_CONTROL (intrinsic function)	SMMULR (intrinsic function)	
set_CPSR (intrinsic function)	SMUAD (intrinsic function)	
set_FAULTMASK (intrinsic function)	SMUADX (intrinsic function)	
set_interrupt_state (intrinsic function)	SMUL (intrinsic function)	
set_LR (intrinsic function)	SMULBB (intrinsic function)	
set_MSP (intrinsic function)	SMULBT (intrinsic function)	
set_PRIMASK (intrinsic function)	SMULTB (intrinsic function)	
set_PSP (intrinsic function)	SMULTT (intrinsic function)	
set_ISI (intrinsic function)	SMULWB (intrinsic function)	
set_SB (intrinsic function)	SMULWT (intrinsic function)	
SHADD8 (intrinsic function)	SMUSD (intrinsic function)	
SHADD8 (intrinsic function)	SMUSDX (intrinsic function)	
SHADD10 (intrinsic function)	SMCSDA (intrinsic function)	
SHASA (intrinsic function)	SSAT (fittilistic function)	
	SSAX (intrinsic function)	
SHSUB8 (intrinsic function)	SSAX (intrinsic function)	
SHSUB16 (intrinsic function)		
SMLABB (intrinsic function)	SSUB16 (intrinsic function)	
SMLABT (intrinsic function)	stackless (extended keyword)	
SMLAD (intrinsic function)	STC (intrinsic function)	
SMLADX (intrinsic function)	STCL (intrinsic function)	
SMLALBB (intrinsic function)	STCL_noidx (intrinsic function)	
SMLALBT (intrinsic function)	STC_noidx (intrinsic function)	
SMLALD (intrinsic function)	STC2 (intrinsic function)	
SMLALDX (intrinsic function)	STC2L (intrinsic function)	
SMLALTB (intrinsic function)	STC2L_noidx (intrinsic function)	
SMLALTT (intrinsic function)	STC2_noidx (intrinsic function)	
SMLATB (intrinsic function)	STDC_VERSION (predefined symbol)	
SMLATT (intrinsic function)	STDC (predefined symbol)	
SMLAWB (intrinsic function)	STREX (intrinsic function)	
SMLAWT (intrinsic function)	swi (extended keyword)	
SMLSD (intrinsic function)	SWP (intrinsic function)	
SMLSDX (intrinsic function)	SWPB (intrinsic function)	
SMLSLD (intrinsic function)	SXTAB (intrinsic function)	
SMLSLDX (intrinsic function)	SXTAB16 (intrinsic function)	
SMMLA (intrinsic function)	SXTAH (intrinsic function)	358
SMMI AR (intrinsic function) 351	SYTR16 (intrinsic function)	358

_task (extended keyword)	-e (compiler option)	225
thumb (extended keyword)	-f (compiler option)	227
TIME (predefined symbol)	-f (iobjmanip option)	427
UADD8 (intrinsic function)	-f (linker option)	261
UADD16 (intrinsic function)	-I (compiler option)	229
UASX (intrinsic function)	-l (compiler option)	
UHADD8 (intrinsic function)	for creating skeleton code	130
UHADD16 (intrinsic function)	-O (compiler option)	240
UHASX (intrinsic function)	-o (compiler option)	241
UHSAX (intrinsic function)	-o (iarchive option)	429
UHSUB16 (intrinsic function)	-o (ielfdump option)	429
UMAAL (intrinsic function)	-o (linker option)	269
ungetchar, in stdio.h	-r (compiler option)	220
UQADD8 (intrinsic function)	-r (iarchive option)	432
UQADD16 (intrinsic function)	-S (iarchive option)	
UQASX (intrinsic function)	-s (ielfdump option)	433
UQSAX (intrinsic function)	-t (iarchive option)	436
UQSUB8 (intrinsic function)	-V (iarchive option)	436
UQSUB16 (intrinsic function)	-x (iarchive option)	427
USADA8 (intrinsic function)	aapcs (compiler option)	216
USAD8 (intrinsic function)	aeabi (compiler option)	216
USAT (intrinsic function)	align_sp_on_irq (compiler option)	216
USAT16 (intrinsic function)	all (ielfdump option)	423
USAX (intrinsic function)	arm (compiler option)	217
USUB8 (intrinsic function)	basic_heap (linker option)	253
_USUB16 (intrinsic function)	BE32 (linker option)	254
UXTAB (intrinsic function)	BE8 (linker option)	254
UXTAB16 (intrinsic function)	bin (ielftool option)	423
UXTAH (intrinsic function)	char_is_signed (compiler option)	217
UXTB16 (intrinsic function)	char_is_unsigned (compiler option)	218
VA_ARGS (preprocessor extension)143	checksum (ielftool option)	423
VER (predefined symbol)	code (ielfdump option)	425
weak (extended keyword)	config (linker option)	255
write (library function)	config_def (linker option)	255
customizing	cpp_init_routine (linker option)	255
write_array, in stdio.h	cpu (compiler option)	218
write_buffered (DLIB library function)	cpu (linker option)	256
-D (compiler option)	cpu_mode (compiler option)	219
-d (jarchive option) 426	create (jarchive option).	425

c++ (compiler option)	ihex (ielftool option)	428
c89 (compiler option)	image_input (linker option)	262
debug (compiler option)220	inline (linker option)	
define_symbol (linker option)	interwork (compiler option)	229
delete (iarchive option)	keep (linker option)	263
dependencies (compiler option)	legacy (compiler option)	
dependencies (linker option)	lock_regs (compiler option)	231
diagnostics_tables (compiler option)	log (linker option)	
diagnostics_tables (linker option)	log_file (linker option)	
diag_error (compiler option)	macro_positions_in_diagnostics (compiler option)	232
diag_error (linker option)257	mangled_names_in_messages (linker option)	264
diag_remark (compiler option)	map (linker option)	
diag_remark (linker option)	mfc (compiler option)	
diag_suppress (compiler option)	migration_preprocessor_extensions (compiler option)	
diag_suppress (linker option)	misrac (compiler option)	
diag_warning (compiler option)223	misrac_verbose (compiler option)	
diag_warning (linker option)	misrac_verbose (linker option)	
discard_unused_publics (compiler option)223	misrac1998 (compiler option)	
dlib_config (compiler option)	misrac1998 (linker option)	
ec++ (compiler option)	misrac2004 (compiler option)	
edit (isymexport option)	misrac2004 (linker option)	
eec++ (compiler option)	no_clustering (compiler option)	
enable_hardware_workaround (compiler option)226	no_code_motion (compiler option)	
enable_multibytes (compiler option)	no_const_align (compiler option)	
endian (compiler option)	no_cse (compiler option)	
entry (linker option)	no_dynamic_rtti_elimination (linker option)	
enum_is_int (compiler option)	no_exceptions (compiler option)	
error_limit (compiler option)	no_exceptions (linker option)	
error_limit (linker option)	no_fragments (compiler option)	
exception_tables (linker option)260	no_fragments (linker option)	
export_builtin_config (linker option)	no_inline (compiler option)	
extract (iarchive option)	no_library_search (linker option)	
extra_init (linker option)	no_locals (linker option)	
fill (ielftool option)	no_loop_align (compiler option)	
force_exceptions (linker option)	no_mem_idioms (compiler option)	
force_output (linker option)	no_path_in_file_macros (compiler option)	
fpu (compiler option)	no_range_reservations (linker option)	
guard_calls (compiler option)	no_remove (linker option)	
header context (compiler option)	-no rtti (compiler option)	

no_rw_dynamic_init (compiler option)	search (linker option)
no_scheduling (compiler option)	section (compiler option)
no_static_destruction (compiler option)	section (ielfdump option)
no_strtab (ielfdump option)	semihosting (linker option)272
no_system_include (compiler option)	separate_cluster_for_initialized_variables
no_typedefs_in_diagnostics (compiler option) 238	(compiler option)
no_unaligned_access (compiler option)	silent (compiler option)
no_unroll (compiler option)	silent (iarchive option)
no_veneer (linker option)	silent (ielftool option)
no_vfe (compiler option)	silent (linker option)272
no_warnings (compiler option)	simple (ielftool option)
no_warnings (linker option)	srec (ielftool option)
no_wrap_diagnostics (compiler option)	srec-len (ielftool option)
no_wrap_diagnostics (linker option)	srec-s3only (ielftool option)
only_stdout (compiler option)	strict (compiler option)
only_stdout (linker option)	strip (ielftool option)
output (compiler option)	strip (iobjmanip option)
output (iarchive option)	strip (linker option)
output (ielfdump option)	strtab (ielfdump option)
output (linker option)	symbols (iarchive option)
pi_veneer (linker option)	system_include_dir (compiler option)
place_holder (linker option)	thumb (compiler option)
predef_macro (compiler option)241	toc (iarchive option)
preinclude (compiler option)	use_c++_inline (compiler option)
preprocess (compiler option)	use_unix_directory_separators (compiler option) 248
ram_reserve_ranges (isymexport option)	verbose (iarchive option)
raw (ielfdump] option)	verbose (ielftool option)
redirect (linker option)	vfe (compiler option)
relaxed_fp (compiler option)	vla (compiler option)
remarks (compiler option)	warnings_affect_exit_code (compiler option) 205, 249
remarks (linker option)	warnings_affect_exit_code (linker option)
remove_section (iobjmanip option)	warnings_are_errors (compiler option)
rename_section (iobjmanip option)	warnings_are_errors (linker option)
rename_symbol (iobjmanip option)	.bss (ELF section)
replace (iarchive option)	.comment (ELF section)
require_prototypes (compiler option)244	.cstart (ELF section)
reserve_ranges (isymexport option)	.data (ELF section)
ropi (compiler option)	.data_init (ELF section)
rwpi (compiler option)	.debug (ELF section)
	.exc.text (ELF section)

.iar.debug (ELF section)	. 404
.iar.dynexit (ELF section)	. 406
.init_array (section)	. 406
.intvec (section)	. 406
.noinit (ELF section)	. 407
.preinit_array (section)	. 407
.prepreinit_array (section)	. 407
.rel (ELF section)	. 404
rela (ELF section)	. 404
.rodata (ELF section)	. 408
.shstrtab (ELF section)	. 404
.strtab (ELF section)	. 404
.symtab (ELF section)	. 404
.text (ELF section)	. 408
.textrw (ELF section)	. 408
.textrw_init (ELF section)	. 408
@ (operator)	
placing at absolute address	. 183
placing in sections	. 185
#include files, specifying	, 229
#warning message (preprocessor extension)	. 370
%Z replacement string,	
implementation-defined behavior	. 452
Numerics	
Mullierics	
32-bits (floating-point format)	. 282
64-bits (floating-point format)	