
R-IN32M3, R-IN32M4, RZ/T, RZ/N Series

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Jul 26, 2018

HW-RTOS Accelerator Kernel Viewer Plug-in for C-SPY User's Guide

Introduction

This document explains the following.

- Overview of HW-RTOS Accelerator Kernel Viewer Plug-in for C-SPY
- How to Installation procedure
- How to use

Target Device

R-IN Family	R-IN32M3 Series
	R-IN32M4 Series
RZ Family	RZ/T1 Series
	RZ/N1 Series

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1. Introduction

1.1 Overview

The HW-RTOS accelerator Kernel Viewer Plug-in for C-SPY is a plug-in for displaying HW-RTOS kernel information of the R-IN Engine inside the C-SPY debugger of the IAR Embedded Workbench IDE.

1.2 Limitations

The plug-in is supported by the C-SPY debugger of IAR Embedded Workbench for Arm v8.3 for Renesas devices R-IN32M3, R-IN32M4, RZ/T1, and RZ/N1.

The plug-in acquires information from HW-RTOS only when reaching a break point. If a HW ISR happens during this time, there is a possibility that a HW ISR is lost. Best is therefore to turn off the plug-in if there is suspicion that a HW ISR is lost, and to not have breakpoints active during final testing. Explanation: This is caused by the plug-in's direct access to HW-RTOS register and memory, which may in rare circumstances compete with a HW ISR occurring in silicon. Observe that the HW-RTOS library also has indirect access to HW-RTOS via the normal system call (command) interface for which this conflict does not exist, however that interface cannot provide full kernel information.

For RZ/N1 GOAL software, the plug-in gets part of the kernel information from GOAL. If a task function name is "goal_tgtTaskWrapper", the plug-in assumes that the task is used for GOAL. Additionally, if task stack size is a default value defined by GOAL, "Stack Size" field in task status window shows 0.

If you encounter a problem with this plug-in's behavior, or if you have any comments or requests, please contact our support desk.

2. Folder structure

When IAR Embedded Workbench for Arm is installed, it becomes the following folder structure.

C:/Program Files

└─IAR Systems

└─Embedded Workbench 8.1

└─arm

└─doc

| └─HWRTOSplugin.ENU.pdf

| └─HWRTOSplugin.JPN.pdf

└─plugins

└─rtos

└─HWRTOSplugin

└─HWRTOSplugin.dll

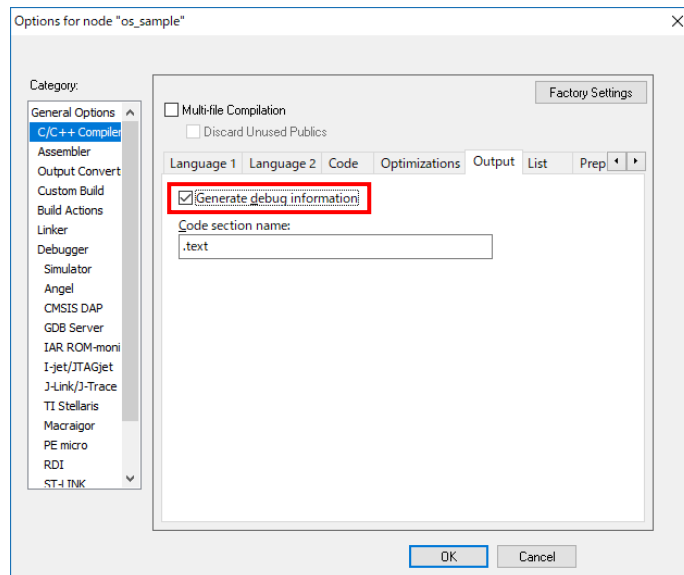
└─HWRTOSplugin.ewplugin

3. Settings for using plug-ins

3.1 Create debug information

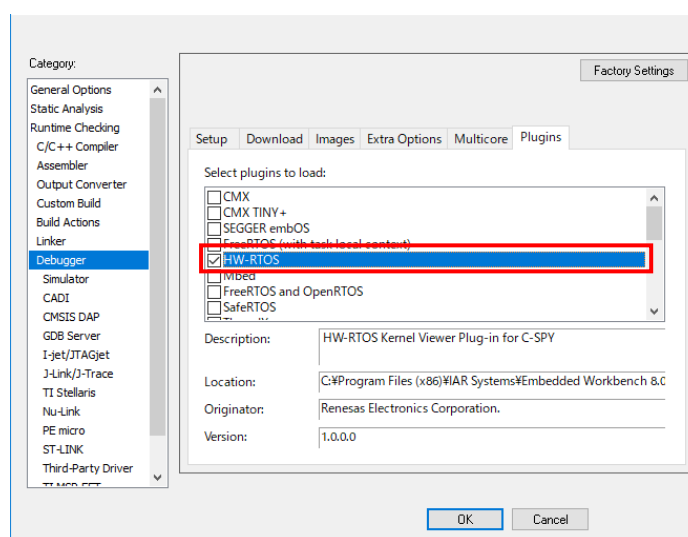
Start IAR Embedded Workbench for Arm.

To enable the plug-in to reference necessary debug information, select [Project]->[Option]->[C/C++Compiler]->[Output]->[Generate debug information].



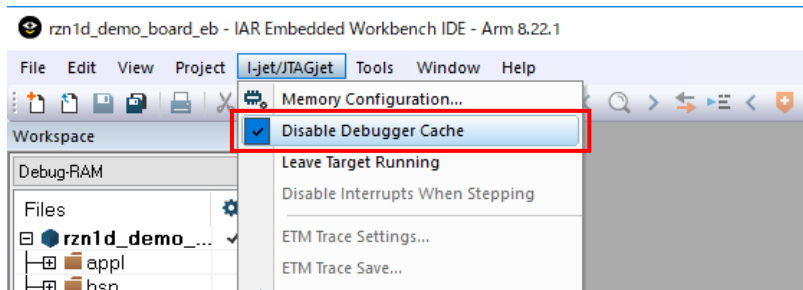
3.2 Enable plug-in

Enable HW-RTOS accelerator Kernel Viewer Plug-in for C-SPY by selecting [Project]->[Option]->[Debug]->[Plugins]->[HW-RTOS].



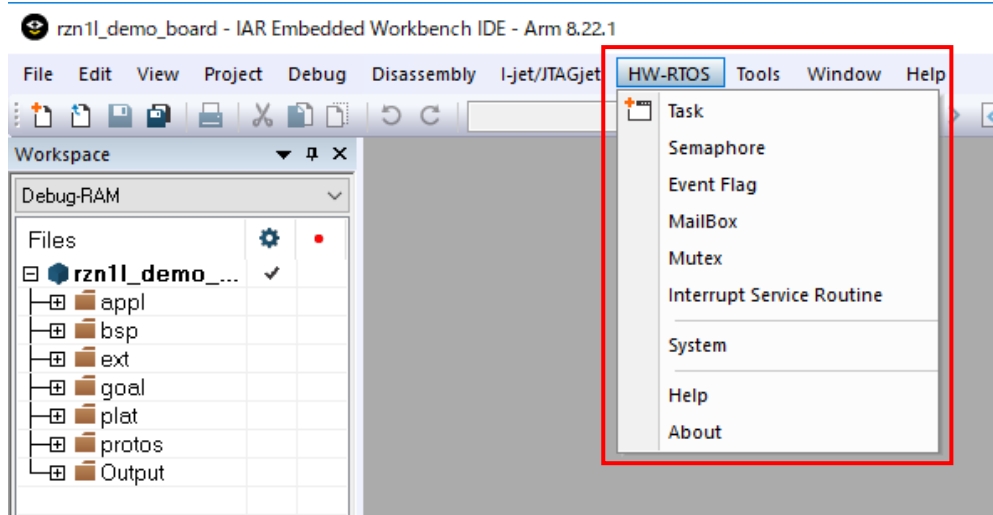
3.3 Preparation to use plug-in

If debugger cache is enabled, the plug-in may fail to access memory data needed for HW-RTOS. Therefore, debugger cache should be disabled by checking [I-jet/JTAGjet]->[Disable Debugger Cache].



4. How to use Plug-in

After activating the plug-in, start the C-SPY debugger by selecting [Project]->[Download and Debug].
If the plug-in successfully loads, the "HW-RTOS" menu will be displayed in the menu bar.



4.1 Menu Item list

Object status

Display status monitor of each object

- Task
- Semaphore
- Event Flag
- MailBox
- Mutex
- Interrupt Service Routine

System information

- System Displays system information (system time)

Other

- Help Refer user's guide (opens this document)
- About Information about plug-in version

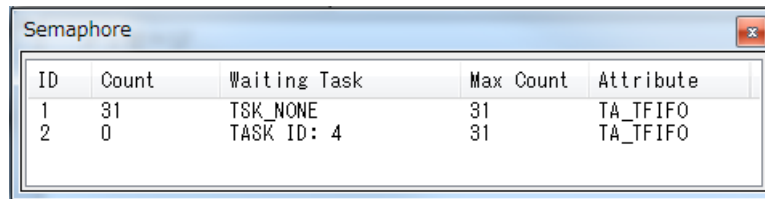
4.2 Task / Status of task

* ID	Task Address	Task Name	Pri	Status	Waiting Cause	LeftTime	Stack Used	Stack Size	Stack Pointer	Stack Base
1	0x04004700	init_task	1	DORMANT				1024 Byte		0x2000C500
3	0x04000218	Task1	5	RUNNING			72 Byte	1024 Byte	0x2000C1B8	0x2000C1C0
4	0x04000552	Task2	1	WAITING	SLEEP	TMO_FEVR		1024 Byte		0x2000B8C0
5	0x04000A10	Task3	4	WAITING	MTX ID: 43	TMO_FEVR		1024 Byte		0x2000B9C0
6	0x04000E5C	Task4	2	DORMANT				1024 Byte		0x2000B5C0
7	0x040010B2	Task5	4	DORMANT				1024 Byte		0x2000B1C0
63	0x0400472C	idle_task	15	READY				256 Byte		0x2000ADC0

Display task status

Column name	Description
*	Currently running task
ID	Task ID number
Task Address	Task ID start address
Task Name	Task function name
Pri	Task priority
Status	Task status WAITING: Waiting state, RUNNING: Execution state, READY: Executable state, DORMANT: Dormant state
Waiting Cause	Wait cause for task in wait state SLEEP: Waiting to wake up, DELAY: Pending time, <object type> ID: <object ID> = Wait object <object type>Display list: SEM: semaphore, FLG: event flag, MBX: mailbox, MTX: mutex Wait cause for task in running state INTERRUPT: Interrupt processing in progress
Left Time	Time left until task wait state times out. TMO_FEVR: Permanent wait
Stack Used	Stack usage size of currently executing task. Sizes other than the execution task are hidden.
Stack Size	Task stack area size
Stack Pointer	Current trade stack pointer Sizes other than the execution task are hidden.
Stack Base	Task base stack pointer

4.3 Semaphore / Status of Semaphore

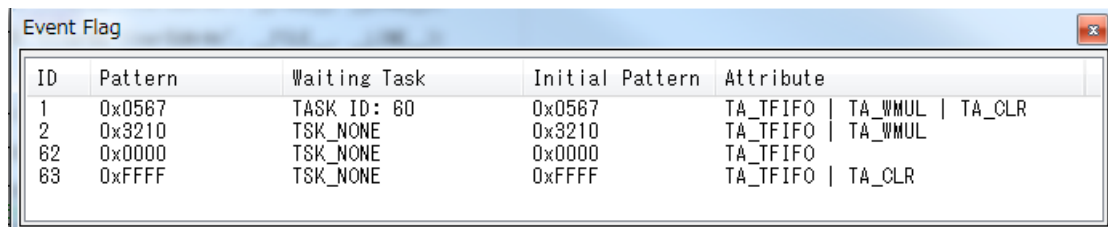


ID	Count	Waiting Task	Max Count	Attribute
1	31	TSK_NONE	31	TA_TFIFO
2	0	TASK ID: 4	31	TA_TFIFO

Display the semaphore status

Column name	Description
ID	Semaphore ID number
Count	Number of resources of current semaphore
Waiting Task	ID number of the task at the head of the semaphore's queue
Max Count	Maximum number of resources of current semaphore
Attribute	Attributes of semaphores (TA_TFIFO TA_TPRI)

4.4 Event Flag / Status of event flag



ID	Pattern	Waiting Task	Initial Pattern	Attribute
1	0x0567	TASK ID: 60	0x0567	TA_TFIFO TA_WMUL TA_CLR
2	0x3210	TSK_NONE	0x3210	TA_TFIFO TA_WMUL
82	0x0000	TSK_NONE	0x0000	TA_TFIFO
83	0xFFFF	TSK_NONE	0xFFFF	TA_TFIFO TA_CLR

Display the status of event flag

Column name	description
ID	Event flag ID number
Pattern	Current bit pattern
Waiting Task	ID number of the task at the head of the event flag's queue
Initial Pattern	Initial bit pattern
Attribute	Attributes of event flag ((TA_TFIFO TA_TPRI) (TA_WMUL) [TA_CLR])

4.5 MailBox / Status of mailbox

ID	Waiting Task	Attribute
1	TSK_NONE	TA_TFIFO TA_MFIFO
2	TASK ID: 4	TA_TFIFO TA_MFIFO
3	TASK ID: 5	TA_TPRI TA_MFIFO
4	TSK_NONE	TA_TPRI TA_MPRI

Display the status of mailbox

Column name	Description
ID	Mailbox ID number
Waiting Task	ID number of the task at the head of the mailbox's queue
Attribute	Attributes of Mailbox ((TA_TFIFO TA_TPRI) (TA_MFIFO TA_MPRI))

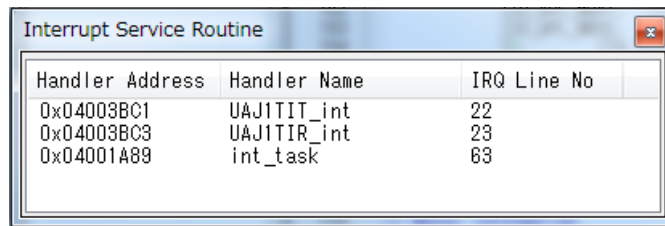
4.6 Mutex / Status of mutex

ID	Locked Task	Waiting Task	Attribute
43	TASK ID: 4	TASK ID: 5	TA_TFIFO
4	TSK_NONE	TSK_NONE	TA_TPRI

Display the status of mutex

Column name	Description
ID	Mutex ID number
Locked Task	ID number of the task locking the mutex
Waiting Task	ID number of the task at the head of the mutex's queue
Attribute	Attributes of mutex (TA_TFIFO TA_TPRI)

4.7 Interrupt Service Routine / Status of interrupt service routine

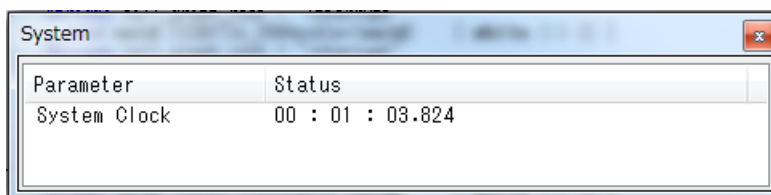


Handler Address	Handler Name	IRQ Line No
0x04003BC1	UAJITIT_int	22
0x04003BC3	UAJITIR_int	23
0x04001A89	int_task	63

Display status of interrupt service routine

Column name	description
Handler Address	Start address of the interrupt service routine
Handler Name	Function name of the interrupt service routine
IRQ Line No.	The exception number corresponding to the interrupt service routine

4.8 System / system information



Parameter	Status
System Clock	00 : 01 : 03.824

Display kernel system information

Column name	Description
Parameter	System information parameter
Status	System information status
System Parameter	Status
System Clock	Current system time

5. Website and Support

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Inquiries

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Revision History

Rev.	Date	Description	
		Page	Summary
1.00	Jul 26, 2018	-	First Edition Issued

General Precautions in the Handling of Microprocessing Unit and Microcontroller Unit Products

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1. Handling of Unused Pins

Handle unused pins in accordance with the directions given under Handling of Unused Pins in the manual.

- The input pins of CMOS products are generally in the high-impedance state. In operation with an unused pin in the open-circuit state, extra electromagnetic noise is induced in the vicinity of LSI, an associated shoot-through current flows internally, and malfunctions occur due to the false recognition of the pin state as an input signal become possible. Unused pins should be handled as described under Handling of Unused Pins in the manual.

2. Processing at Power-on

The state of the product is undefined at the moment when power is supplied.

- The states of internal circuits in the LSI are indeterminate and the states of register settings and pins are undefined at the moment when power is supplied.

In a finished product where the reset signal is applied to the external reset pin, the states of pins are not guaranteed from the moment when power is supplied until the reset process is completed.

In a similar way, the states of pins in a product that is reset by an on-chip power-on reset function are not guaranteed from the moment when power is supplied until the power reaches the level at which resetting has been specified.

3. Prohibition of Access to Reserved Addresses

Access to reserved addresses is prohibited.

- The reserved addresses are provided for the possible future expansion of functions. Do not access these addresses; the correct operation of LSI is not guaranteed if they are accessed.

4. Clock Signals

After applying a reset, only release the reset line after the operating clock signal has become stable. When switching the clock signal during program execution, wait until the target clock signal has stabilized.

- When the clock signal is generated with an external resonator (or from an external oscillator) during a reset, ensure that the reset line is only released after full stabilization of the clock signal. Moreover, when switching to a clock signal produced with an external resonator (or by an external oscillator) while program execution is in progress, wait until the target clock signal is stable.

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